

Automation systems
Drive solutions



Controls
Inverters

Motors

Gearboxes
Engineering Tools

Contents of the L-force catalogue

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 Selected portfolio
 Additional portfolio

Lenze makes many things easy for you.

With our motivated and committed approach, we work together with you to create the best possible solution and set your ideas in motion - whether you are looking to optimise an existing machine or develop a new one. We always strive to make things easy and seek perfection therein. This is anchored in our thinking, in our services and in every detail of our products. It's as easy as that!

1

Developing ideas

Are you looking to build the best machine possible and already have some initial ideas? Then get these down on paper together with us, starting with small innovative details and stretching all the way to completely new machines. Working together, we will develop an intelligent and sustainable concept that is perfectly aligned with your specific requirements.

4

Manufacturing machines

Functional diversity in perfect harmony: as one of the few full-range providers in the market, we can provide you with precisely those products that you actually need for any machine task – no more and no less. Our L-force product portfolio, a consistent platform for implementing drive and automation tasks, is invaluable in this regard.

2

Drafting concepts

We see welcome challenges in your machine tasks, supporting you with our comprehensive expertise and providing valuable impetus for your innovations. We take a holistic view of the individual motion and control functions here and draw up consistent, end-to-end drive and automation solutions for you - keeping everything as easy as possible and as extensive as necessary.

5

Ensuring productivity

Productivity, reliability and new performance peaks on a daily basis – these are our key success factors for your machine. After delivery, we offer you cleverly devised service concepts to ensure continued safe operation. The primary focus here is on technical support, based on the excellent application expertise of our highly-skilled and knowledgeable after-sales team.

3

Implementing solutions

Our easy formula for satisfied customers is to establish an active partnership with fast decision-making processes and an individually tailored offer. We have been using this simple principle to meet the ever more specialised customer requirements in the field of mechanical engineering for many years.

A matter of principle: the right products for every application.

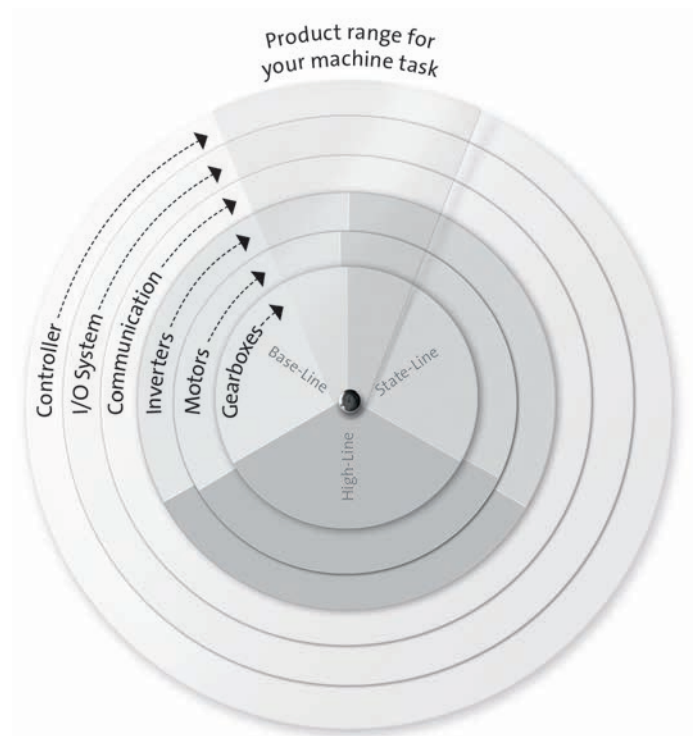
Lenze's extensive L-force product portfolio follows a very simple principle. The functions of our finely scaled products are assigned to the three lines Base-Line, State-Line or High-Line.

But what does this mean for you? It allows you to quickly recognise which products represent the best solution for your own specific requirements.

Powerful products with a major impact:

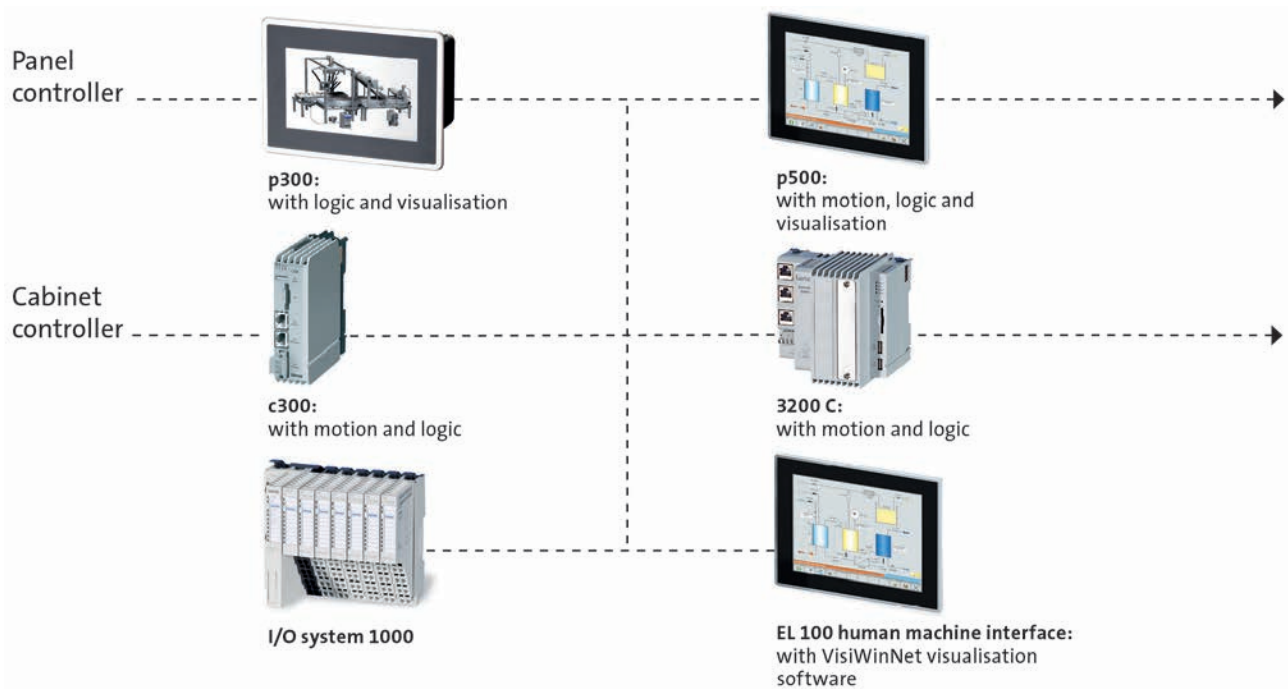
- Easy handling
- High quality and durability
- Reliable technologies in tune with the latest developments

Lenze products undergo the most stringent testing in our own laboratory. This allows us to ensure that you will receive consistently high quality and a long service life. In addition to this, five logistics centres ensure that the Lenze products you select are available for quick delivery anywhere across the globe. It's as easy as that!

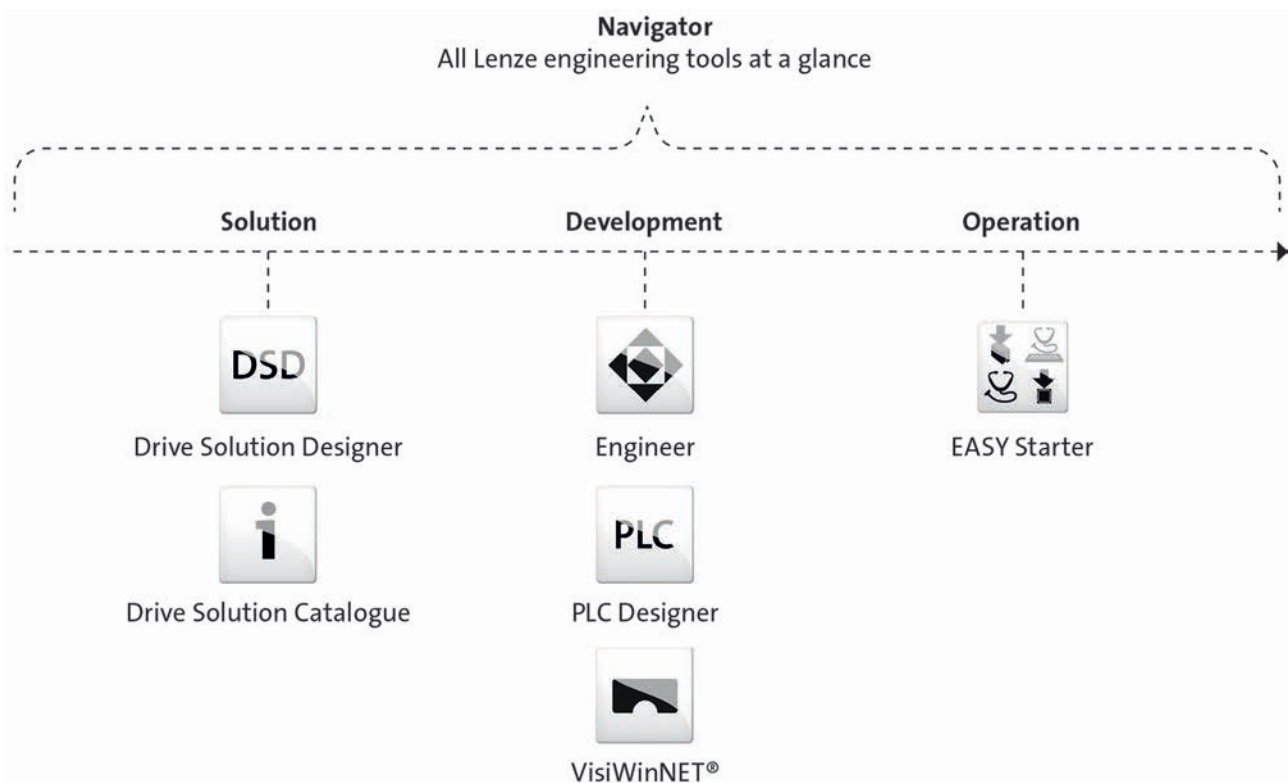


L-force product portfolio

Controls

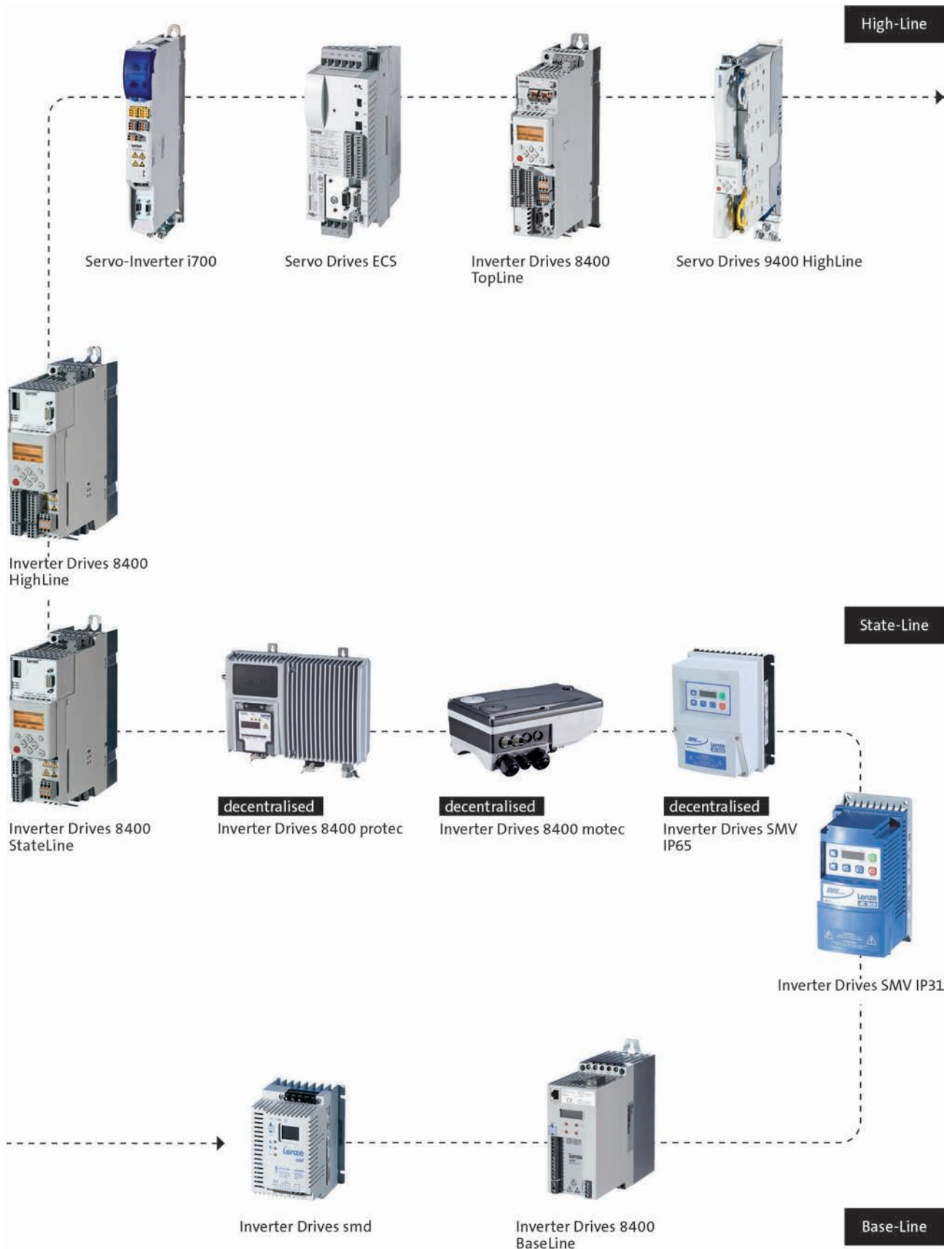


Engineering Tools



L-force product portfolio

Inverters



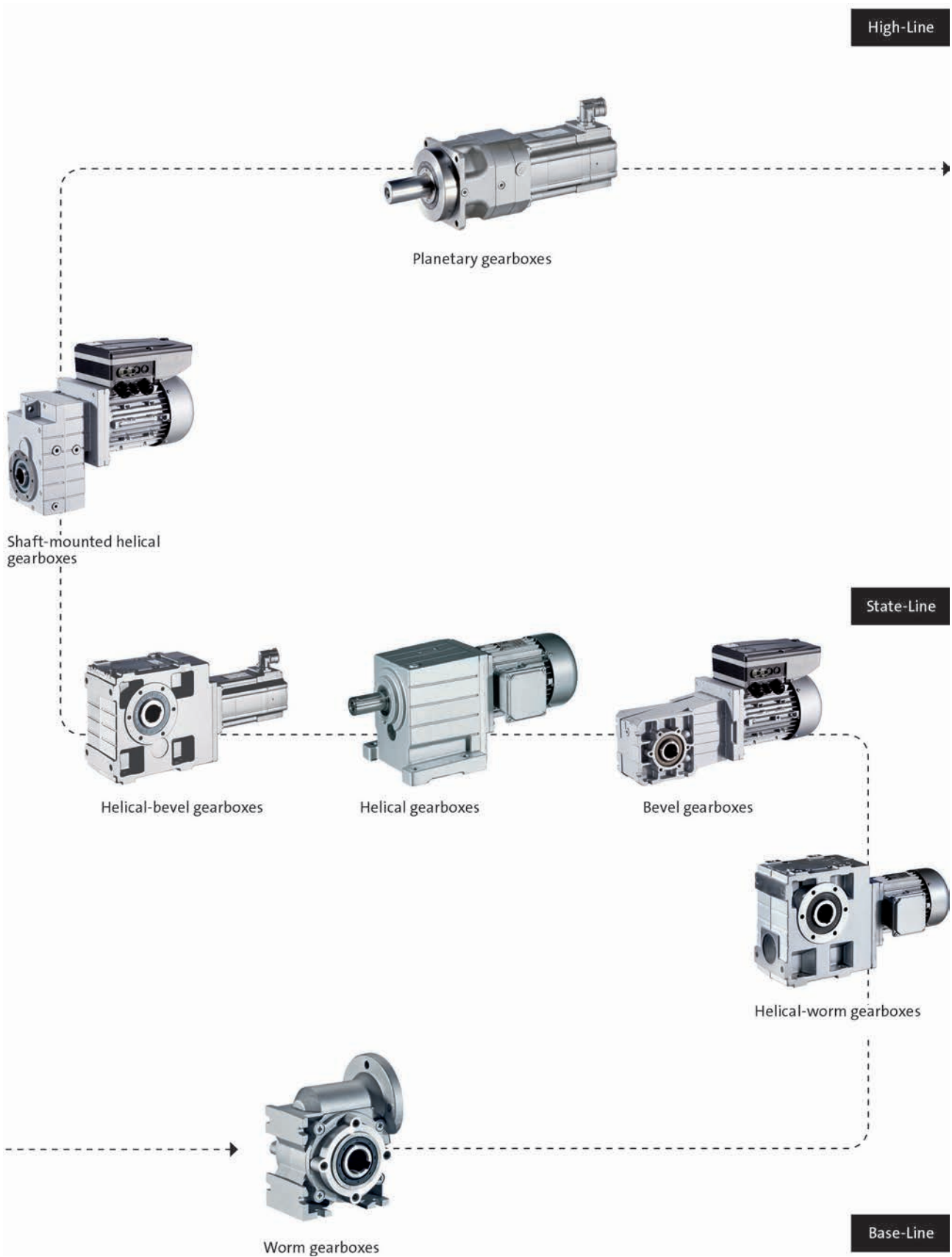
L-force product portfolio

Motors



L-force product portfolio

Gearboxes



Motors

MCS synchronous servo motors

0.25 to 190 Nm



MCS synchronous servo motors

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MCS synchronous servo motors

General information



List of abbreviations

$\eta_{100\%}$	[%]	Efficiency
$\cos \phi$		Power factor
du/dt	[kV/ μ s]	Insulation resistance
$F_{ax,-}$	[N]	Min. axial force
$F_{ax,+}$	[N]	Max. axial force
$f_{in,max}$	[Hz]	Max. input frequency
f_{max}	[kHz]	Limit frequency
f_{max}	[kHz]	Max. switching frequency
f_N	[Hz]	Rated frequency
F_{rad}	[N]	Max. radial force
H_{max}	[m]	Site altitude
I_0	[A]	Standstill current
I_{max}	[A]	Max. short-time DC-bus current
I_{max}	[A]	Max. current
I_{max}	[A]	Max. current consumption
I_{max}	[A]	Max. current
I_{max}	[A]	Max. DC-bus current
I_N	[A]	Rated current
J	[kgcm ²]	Moment of inertia
J_{MB}	[kgcm ²]	Moment of inertia
$KE_{LL\ 150\ ^\circ C}$	[V /1000 rp]	Voltage constant
$Kt_{0\ 150\ ^\circ C}$	[Nm/A]	Torque constant
L	[mH]	Mutual inductance
$L_{1\sigma}$	[mH]	Stator leakage inductance
$L_{2\sigma}$	[mH]	Rotor leakage inductance
L_N	[mH]	Rated inductance
m	[kg]	Mass
M_0	[Nm]	Stall torque
$M_{0,max}$	[Nm]	Max. standstill torque
M_{av}	[Nm]	Average dynamic torque
M_{max}	[Nm]	Max. torque
M_N	[Nm]	Rated torque
n_{eto}	[r/min]	Transition speed
n_k	[r/min]	Speed
n_{max}	[r/min]	Max. speed

n_N	[r/min]	Rated speed
P_N	[kW]	Rated power
Q_E	[J]	Maximum switching energy
R	[Ω]	Insulation resistance
R	[Ω]	Min. insulation resistance
R_1	[Ω]	Stator impedance
R_2	[Ω]	Charging resistor
R_2	[Ω]	Rotor impedance
$R_{UV\ 150\ ^\circ C}$	[Ω]	Stator impedance
$R_{UV\ 20\ ^\circ C}$	[Ω]	Stator impedance
$S_{h\u00fc}$	[1/h]	Transition operating frequency
T	[$^\circ C$]	Operating temperature
T	[$^\circ C$]	Rated temperature
T	[$^\circ C$]	Max. ambient temperature of bearing
T	[$^\circ C$]	Max. surface temperature
T	[$^\circ C$]	Max. ambient temperature for transport
T	[$^\circ C$]	Min. ambient storage temperature
T	[$^\circ C$]	Min. ambient temperature for transport
T	[$^\circ C$]	Ambient temperature
t_1	[ms]	Engagement time
t_2	[ms]	Disengagement time
$T_{opr,max}$	[$^\circ C$]	Max. ambient operating temperature
$T_{opr,min}$	[$^\circ C$]	Min. ambient operating temperature
$U_{in,max}$	[V]	Max. input voltage
$U_{in,min}$	[V]	Min. input voltage
U_{max}	[V]	Max. mains voltage
U_{max}	[V]	Min. input voltage
U_{min}	[V]	Min. mains voltage
$U_{N, AC}$	[V]	Rated voltage
$U_{N, DC}$	[V]	Rated voltage
Z_{ro}	[Ω]	Rotor impedance
Z_{rs}	[Ω]	Impedance
Z_{so}	[Ω]	Stator impedance

MCS synchronous servo motors

General information



List of abbreviations

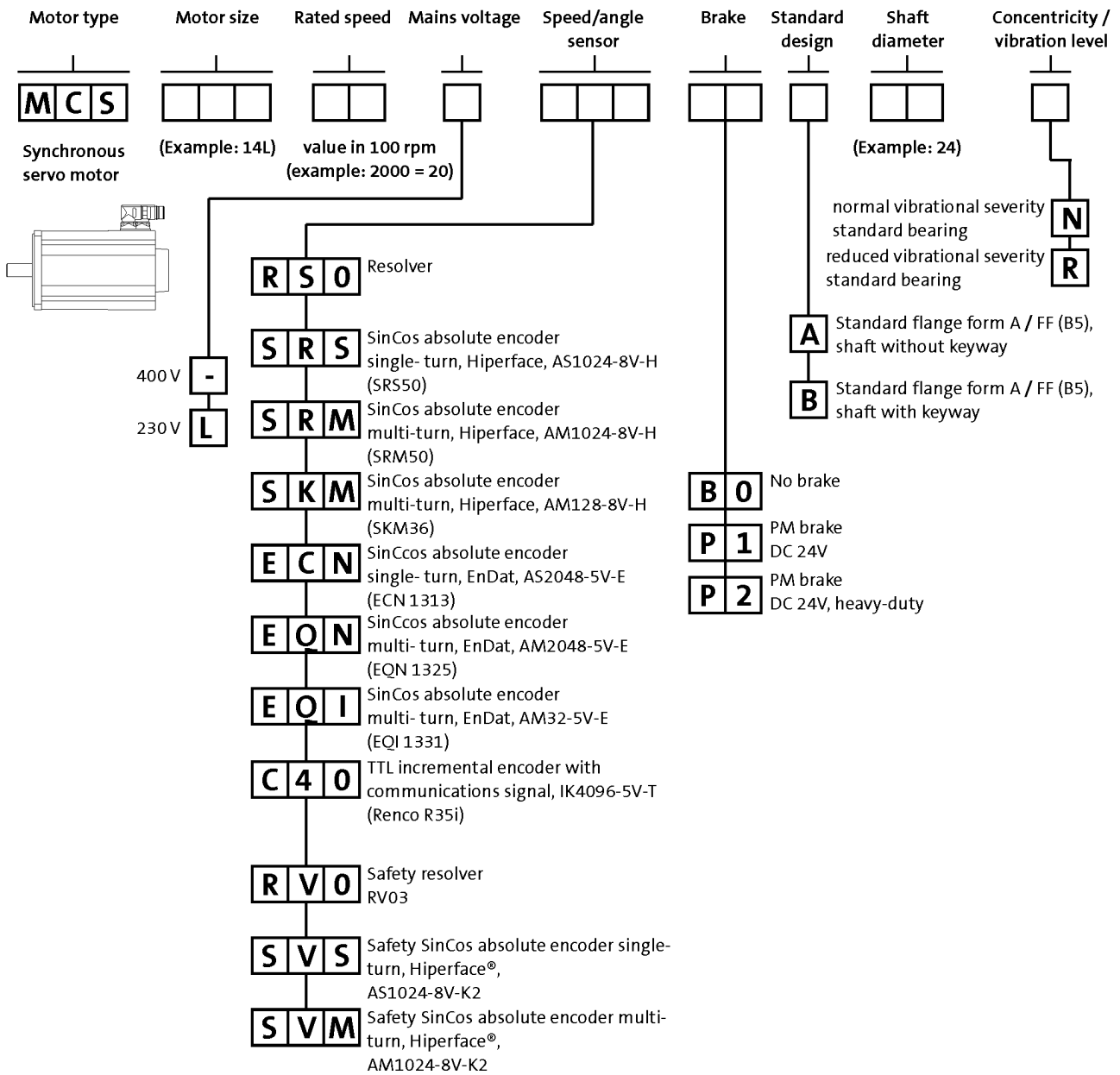
CE	Communauté Européenne
CSA	Canadian Standards Association
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
GOST	Certificate for Russian Federation
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UkrSEPRO	Certificate for Ukraine
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

MCS synchronous servo motors

General information



Product key

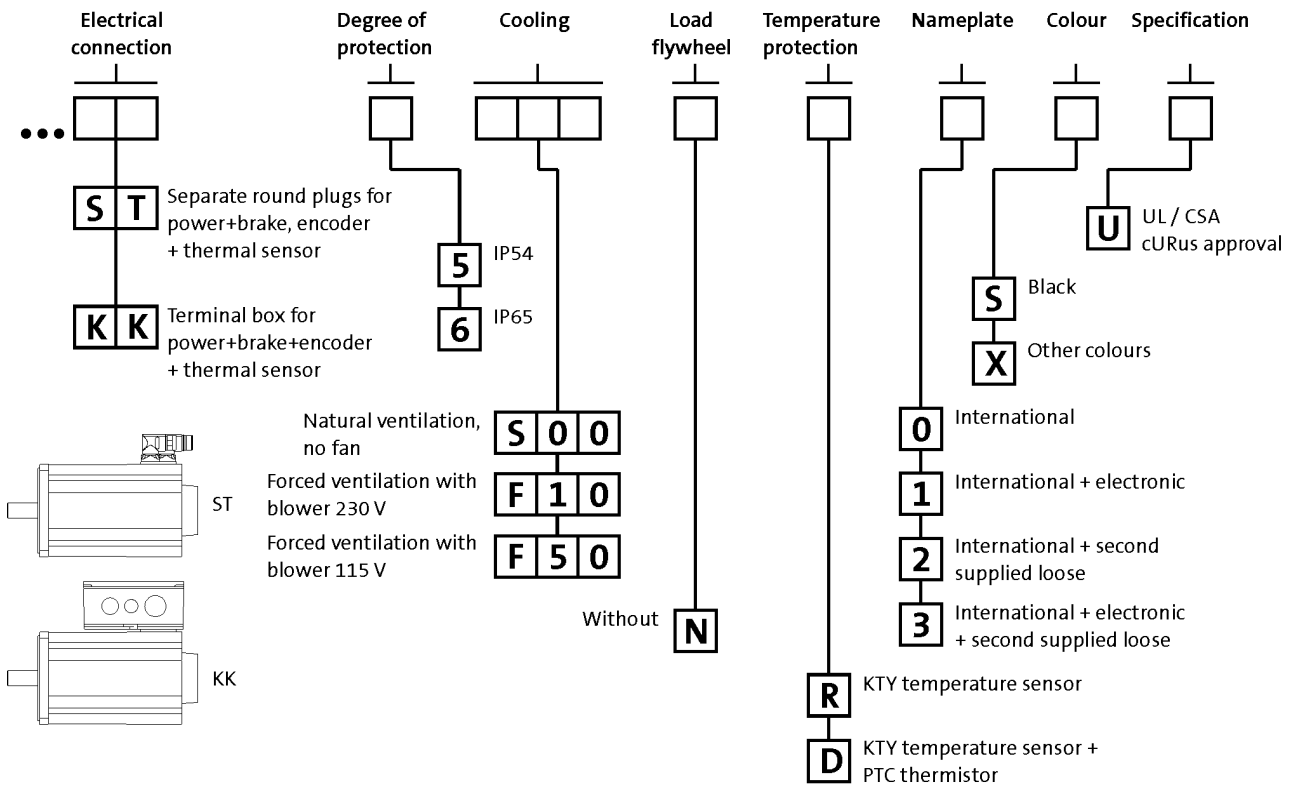


MCS synchronous servo motors

General information



Product key



MCS synchronous servo motors

General information



Product information

When space is limited, but strict requirements in terms of dynamics and precision still have to be met, the MCS synchronous servo motors are the right choice.

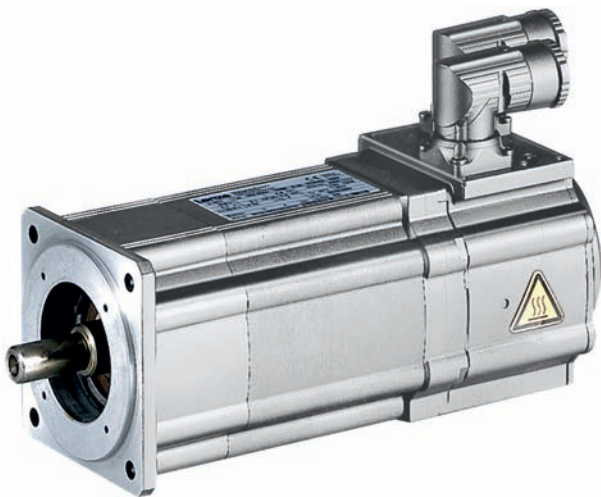
With a power range from 0.25 kW to 15.8 kW and a rated torque range from 0.5 Nm to 72 Nm and peak torques of up to 190 Nm, these motors leave nothing to be desired in installations requiring compact and dynamic drive technology.

The stator winding of the MCS motors employs innovative Single Element Pole Technology – SEPT – and is made up of individual coils. High-quality magnetic materials and specially developed pole shapes set the conditions for their excellent drive characteristics. This results in a significant increase in power density, while at the same time reducing moments of inertia. The minimum detent torques offer exceptional smooth running characteristics and thereby secure excellent control behaviour.

The robust mechanical structure with reinforced bearings, the high degree of protection and the full stator encapsulation increase operational reliability, even in harsh ambient conditions.

Advantages

- High dynamic performance thanks to low moments of inertia
- Compact size with high power density
- Cooling with or without axial external fan
- Robust regenerative resolver system as standard
- Alternatively sin/cos encoder for the highest precision
- Easy to install and service friendly thanks to use of SpeedTec connectors
- Optional terminal box
- Protection: IP54, IP65 optional
- cURus-approved, GOST-certified, CE, RoHS compliant
- Smooth surface
- Single Element Pole Technology
- Optimum rotation characteristics
- Virtually free of detent torque
- Electronic nameplate



MCS09 synchronous servo motor

MCS synchronous servo motors

General information



Functions and features

	MCS06	MCS09	MCS12	MCS14	MCS19
Design					
	B5-FF75	B5-FF100	B5-FF130	B5-FF165	B5-FF215
Shaft end (with and without keyway)					
	11 x 23	14 x 30	19 x 40	24 x 50	28 x 60
A end shield	Not oil-tight				
Brake					
Permanent magnetic brake	DC 24 V	DC 24 V 24 V DC, reinforced			
Speed and angle encoder	Resolver SinCos single-turn/multi-turn				
Cooling					
Without blower	Naturally ventilated				
Axial blower, 1 phase					230 V; 50 Hz 115 V; 60 Hz
Thermal sensor					
Thermal detector	KTY				
PTC thermistor	2x PTC additional (3-phase monitoring)				
Motor connection: plug connector					
	Power + brake Encoder + thermal sensor		Power + brake Encoder + thermal sensor Blower		
Motor connection: terminal box	Power + brake + encoder + thermal sensor				
Shaft bearings					
Bearing type	Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate				
Position of the locating bearing	Non-drive end				
Colour	RAL9005M				

- Terminal boxes not possible if blower is fitted.

MCS synchronous servo motors



General information

Dimensioning

Speed-dependent safety functions

Single encoder concepts with resolvers

Servo motors can perform speed-dependent safety functions for safe speed and / or safe relative position monitoring in a drive system with the Servo Drives 9400. The SM301 safety module, which can be integrated in the Servo Drives 9400, is used to implement these functions. When planning systems/installations of this kind, the following must always be observed:

When using just one single feedback system in the environment of these safety applications, the applicable safety engineering standard IEC 61800-5-2 [Adjustable speed electrical power drive systems - Part: 5-2: Safety requirements - Functional] stipulates special requirements for the connection between feedback system and motor shaft. This is due to the fact that two-channel safety systems at this point in the mechanical system are actually designed as single-channel systems. If this mechanical connection is designed with considerable overdimensioning, the standard permits exclusion of the fault "encoder-shaft breakage" or "encoder-shaft slip". As such, acceleration limit values must not be exceeded for the individual drive solutions. You can find the limit values in the corresponding feedback data of the individual motor ranges.

Speed-dependent safety functions in connection with the SM301 safety module

For the following speed-dependent safety functions, the motor-feedback system combinations listed in the following table are available:

- Safe stop 1 (SS1)
- Safe operational stop (SOS)
- Safely Limited Speed (SLS)
- Safe Maximum Speed (SMS)

- Safe direction (SDI)
- Operation mode selector (OMS) with confirmation (ES)
- Safe speed monitor (SSM)
- Safely limited increment (SLI).

5.1

Encoder type	Encoder type	Product key	Feedback Design	Safe speed monitoring
SinCos absolute value	Single-turn	AS1024-8V-K2		PL d/SIL 2
	Multi-turn	AM1024-8V-K2		PL e/SIL 3
Resolver		RV03		2-encoder concept

MCS synchronous servo motors



General information

Dimensioning

Cooling effect of mounting flange

Mounting on a thermally conducting / insulating plate or machine chassis has an influence on heating up the motor, particularly when using naturally ventilated motors.

The motor rating data specified in the catalogue applies when mounting on a steel plate with free convection with the following dimensions:

- MCS06: 270 x 270 mm
- MCS09: 330 x 330 mm
- MCS12 / 14 / 19: 450 x 450 mm

Vibrational severity

		MCS06	MCS09	MCS12	MCS14	MCS19
Vibrational severity						
IEC/EN 60034-14				A		
Maximum r.m.s. value of the vibration velocity ¹⁾	[mm/s]			1.60		

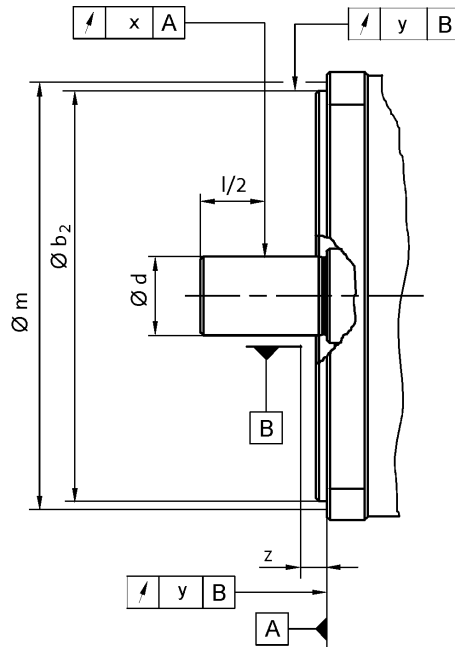
¹⁾ Free suspension

- ▶ at n = 600 to 3,600 rpm



Dimensioning

Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends



5.1

				MCS06	MCS09	MCS12	MCS14	MCS19
Flange size				FF75	FF100	FF130	FF165	FF215
Dimensions								
	b_2	j6	[mm]	60	80	110	130	180
	d	k6	[mm]	11	14	19	24	28
Distance								
Measuring diameter	m		[mm]	65.0	85.0	115	135	185
Dial gauge holder for flange check	z	+/- 1	[mm]	10.0				
Concentricity				Normal class				
IEC 60072				0.080		0.10		
Value	y		[mm]	0.080		0.10		
Linear movement				Normal class				
IEC 60072				0.080		0.10		
Value	y		[mm]	0.080		0.10		
Smooth running				Normal class				
IEC 60072				0.035		0.040		
Value	x		[mm]	0.035		0.040		

- Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072

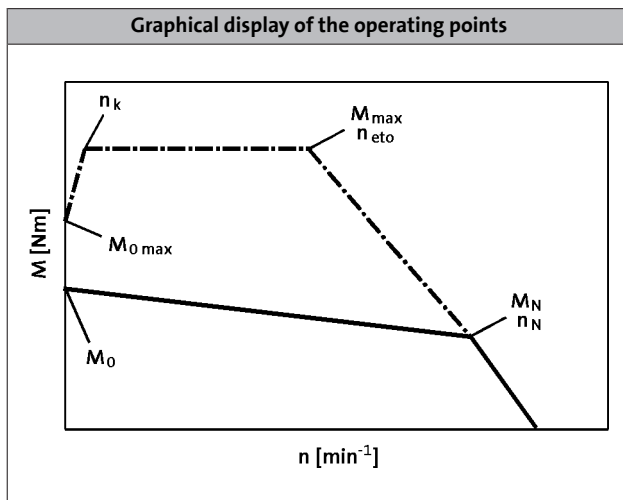
MCS synchronous servo motors

General information



Dimensioning

Notes on the selection tables



Please note:

- In case of an active load (e.g. vertical drive axes, hoists, test benches, unwinders), $M_{0\max}$ has to be considered
- In case of a passive load (e.g. horizontal drive axes), M_{\max} can be usually used
- In case of a speed $< n_k$ and inverter-specifically, the achievable torque $M_{0\max}$ is smaller than M_{\max}
- In case of a speed $n = 0$, the standstill torque M_0 and the standstill current I_0 have to be reduced by 30% after 2 seconds. In case of applications which require a longer holding of M_0 , we recommend the drive to be held via the holding brake and reduce the current, e.g. by controller inhibit.
- In case of servo inverters, the switching frequency dependent overload capacity is considered in the default setting. For more information, see the servo inverter catalogue.

	n_k [r/min]
MCS	75.0
MDSKS	100
MDFKS	

Further selection tables with different switching frequencies are available with the following codes:

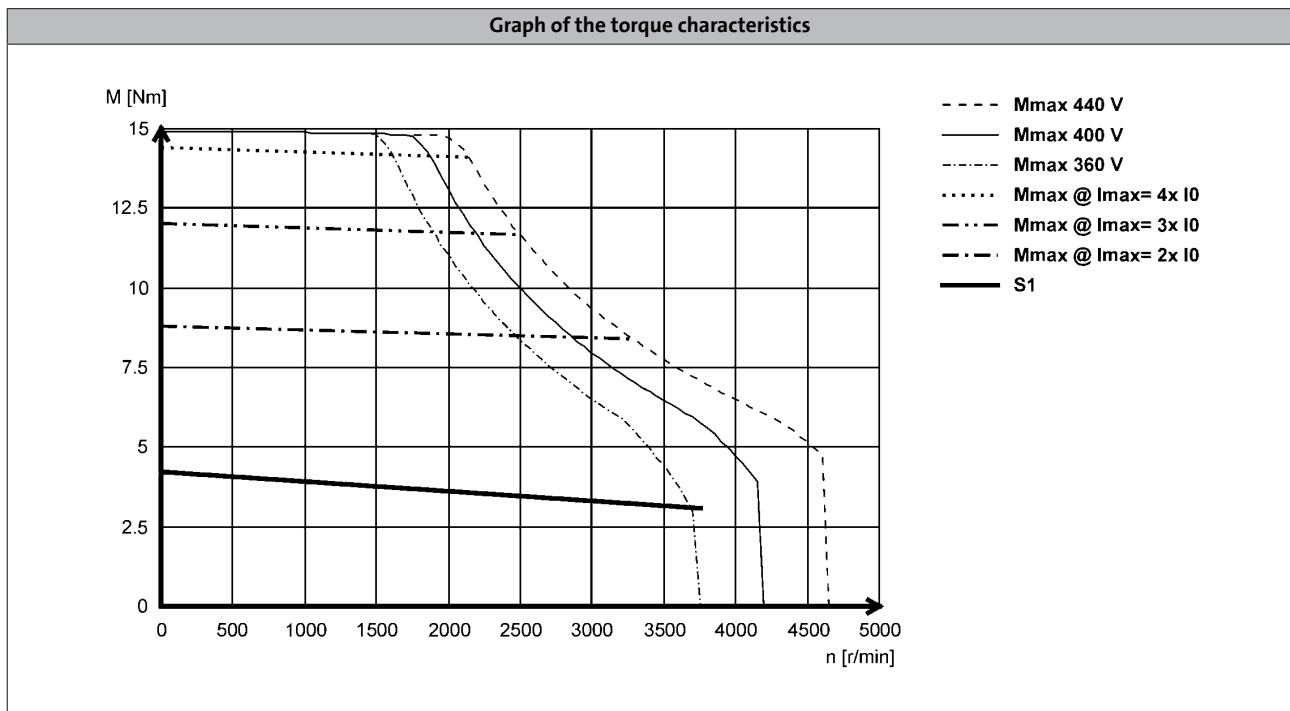
- DS_ZT_MCS_0001
- DS_ZT_MCA_0001
- DS_ZT_MDSKS_0001
- DS_ZT_MDFKS_0001

Simply enter this code (e.g. DS_ZT_MCS_0001) as a search string at www.lenze.de/dsc and you will be given the information immediately in the form of a PDF format.



Dimensioning

Notes on the torque characteristics



5.1

With synchronous servo motors, the limit torque characteristics that result from the selection of servo inverters with maximum currents are also shown alongside the characteristics for continuous operation (S1). These correspond to a multiple of the motor standstill current ($2x I_0$ to $4x I_0$).

Characteristics in the Internet

You can find the torque characteristic for inverter-motor combinations on the Internet at www.lenze.de/dsc. This lists all useful combinations with the servo inverters 9400, 9300, ECS and Inverter Drives 8400 TopLine. These characteristics are each determined using the factory default settings of the inverters:

- 9400 with variable switching frequency.
This means that up to 6-fold overcurrent can be applied in borderline cases.
- 9300 and ECS with fixed switching frequency.
- 8400 TopLine with variable switching frequency.

The continuous operation characteristics (S1) show the inverter-independent motor rating values

Further information on the terms switching frequency and factory default settings can be found in the operating manual of the respective servo inverter.

MCS synchronous servo motors

General information

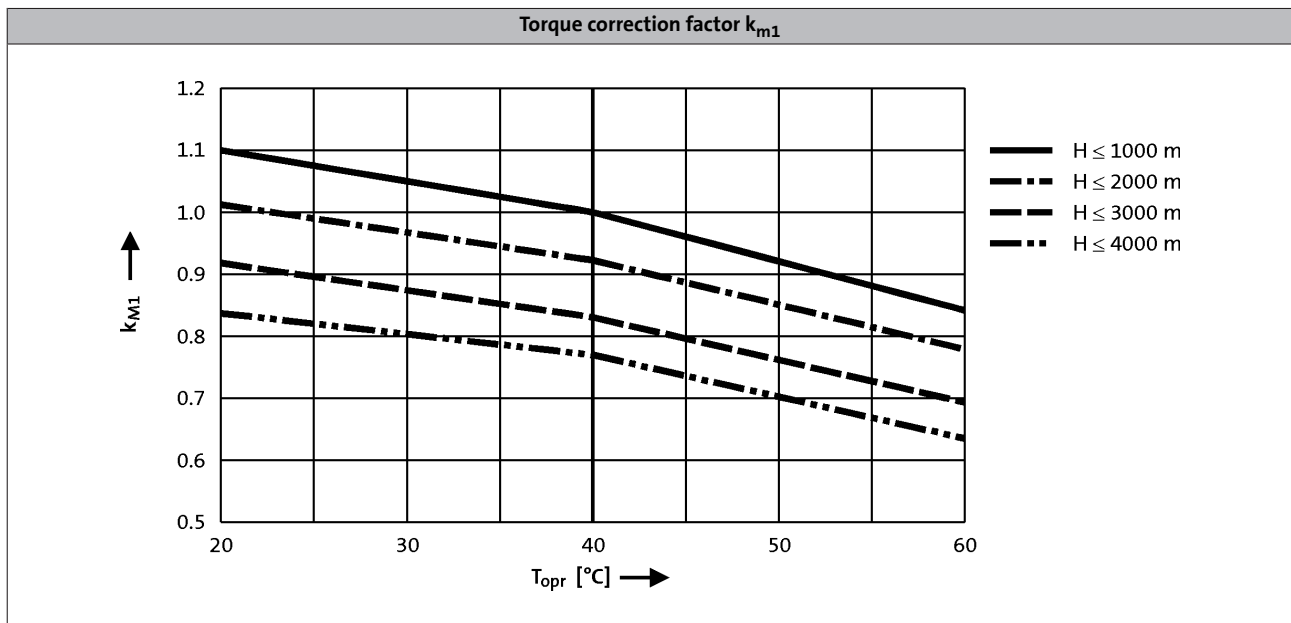


Dimensioning

Influence of ambient temperature and site altitude

The information relating to the servo motors in the tables and graphs is valid for a maximum ambient temperature (T_{opr}) of 40 °C and a site altitude (H) up to 1000 m above sea level. The torque correction factor (k_{M1}) shall be applied to the S1 torque characteristic ($M_0...M_N$) in the event of differing installation conditions.

- ▶ The maximum permissible ambient temperature (T_{opr}) for servo motors with blowers is 40 °C



MCS synchronous servo motors

General information



MCS synchronous servo motors

Technical data



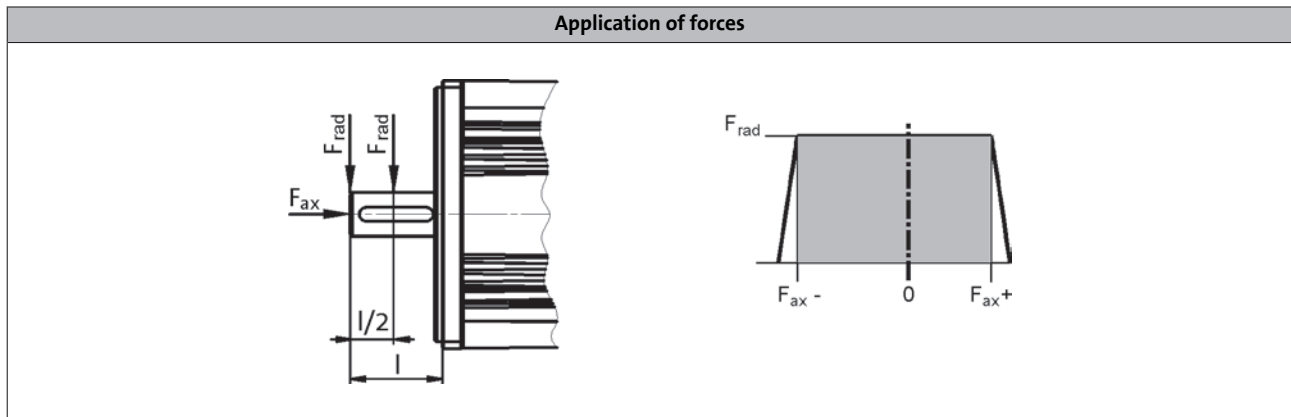
Standards and operating conditions

			MCS	
Cooling type			Naturally ventilated	Blower
Enclosure				
EN 60529			IP54 IP65	IP54
Temperature class				
IEC/EN 60034-1; utilisation			F	
IEC/EN 60034-1; insulation system (enamel-insulated wire)			H	
Conformity				
CE			Low-Voltage Directive 2006/95/EC	
EAC			TP TC 004/2011 (TR C	
Approval				
			UkrSEPRO	
CSA			CSA 22.2 No. 100	
cURus			UL 1004-1 UL 1004-6 Power Conversion Equipment (File-No. E210321)	
Max. voltage load				
IEC/TS 60034-25			Pulse voltage limiting curve A	
Smooth running				
IEC 60072			Normal class	
Linear movement				
IEC 60072			Normal class	
Concentricity				
IEC 60072			Normal class	
Mechanical ambient conditions (vibration)				
IEC/EN 60721-3-3			3M6	
Min. ambient operating temperature				
Without brake	$T_{opr,min}$	[°C]	-20	-15
With brake	$T_{opr,min}$	[°C]	-10	
Max. ambient temperature for operation				
	$T_{opr,max}$	[°C]	40	
Max. surface temperature				
	T	[°C]	140	110
Mechanical tolerance				
Flange centring diameter			$b_2 \leq 230 \text{ mm} = j6$ $b_2 > 230 \text{ mm} = h6$	
Shaft diameter			$d \leq 50 \text{ mm} = k6$ $d > 50 \text{ mm} = m6$	
Site altitude				
Amsl	H_{max}	[m]	4000	

5.1



Permissible radial and axial forces



Application of force at $l/2$

	Bearing service life L_{10}														
	5000 h			10000 h			20000 h			30000 h			50000 h		
	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCS06	740	-260	140	590	-210	80	470	-170	40	410	-150	30	340	-140	10
MCS09	1040	-700	470	830	-550	310	660	-440	200	580	-380	150	490	-330	90
MCS12	1030	-880	560	820	-690	370	650	-550	230	570	-490	160	480	-420	100
MCS14	1830	-1150	720	1450	-900	470	1150	-720	290	1010	-640	200	850	-550	120
MCS19	3840	-1550	950	3050	-1210	620	2430	-960	360	2120	-840	250	1790	-730	130

5.1

Application of force at l

	Bearing service life L_{10}														
	5000 h			10000 h			20000 h			30000 h			50000 h		
	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCS06	630	-210	90	500	-170	50	400	-140	20	350	-130	0	290	-120	-10
MCS09	900	-630	400	710	-500	260	570	-400	160	500	-350	120	420	-300	70
MCS12	890	-820	490		-640	320	560	-520	190	490	-460	130		-400	
MCS14	1590	-1040	610	1260	-820	390	1000	-660	230	880	-580	150	740	-510	
MCS19	3330	-1320	730	2650	-1040	450	2100	-830	240	1840	-740	140	1550	-640	40

- The values for the bearing service life L_{10} refer to an average speed of 4000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease life-time.

MCS synchronous servo motors

Technical data



Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS06C41-	4050	0.80	0.60	2.40	0.25	1.30	1.30	5.40	225	270
MCS06C60-	6000	0.80	0.50	2.40	0.31	2.50	2.40	10.8	135	400
MCS06F41-	4050	1.50	1.20	4.40	0.51	1.50	1.50	5.30	320	270
MCS06F60-	6000	1.50	0.90	4.40	0.57	2.90	2.50	10.5	180	400
MCS06I41-	4050	2.00	1.50	6.20	0.64	1.70	1.60	5.90	325	270
MCS06I60-	6000	2.00	1.20	6.20	0.75	3.40	2.90	11.8	190	400
MCS09D41-	4050	3.30	2.30	9.50	1.00	2.60	2.30	10.0	320	270
MCS09D60-	6000	3.30	1.80	9.50	1.10	5.30	3.80	20.0	210	400
MCS09F38-	3750	4.20	3.10	15.0	1.20	3.00	2.50	15.0	330	250
MCS09F60-	6000	4.20	2.40	15.0	1.50	6.00	4.50	30.0	230	400
MCS09H41-	4050	5.50	3.80	20.0	1.60	4.30	3.40	20.0	300	270
MCS09H60-	6000	5.50	3.00	20.0	1.90	8.50	6.00	40.0	190	400
MCS09L41-	4050	7.50	4.50	32.0	1.90	6.20	4.20	32.0	295	270
MCS09L51-	5100	7.50	3.60	32.0	1.90	12.4	6.90	64.0	180	340

	$\eta_{100\%}$ [%]	$J^{1)}$ [kgcm ²]	$KE_{LL 150\text{ }^\circ\text{C}}$ [V / 1000 rp]	$R_{UV 20\text{ }^\circ\text{C}}$ [Ω]	$R_{UV 150\text{ }^\circ\text{C}}$ [Ω]	L_N [mH]	$Kt_{0 150\text{ }^\circ\text{C}}$ [Nm/A]	$n_{max}^{2)}$ [r/min]	$m^{1)}$ [kg]
MCS06C41-	65.0	0.14	36.6	27.1	36.5	51.0	0.66	8000	1.80
MCS06C60-	70.0	0.14	18.3	6.80	9.10	12.8	0.33	8000	1.80
MCS06F41-	77.0	0.22	60.1	21.9	29.5	63.5	1.05	8000	2.20
MCS06F60-	81.0	0.22	30.0	5.50	7.40	15.9	0.53	8000	2.20
MCS06I41-	81.0	0.30	73.4	18.8	25.4	60.2	1.21	8000	2.90
MCS06I60-	84.0	0.30	36.7	4.70	6.30	15.1	0.60	8000	2.90
MCS09D41-	87.0	1.10	71.2	7.00	9.40	25.1	1.25	7000	4.30
MCS09D60-	87.0	1.10	35.6	1.80	2.40	6.30	0.62	7000	4.30
MCS09F38-	91.0	1.50	79.8	5.20	7.00	24.6	1.40	7000	5.20
MCS09F60-	91.0	1.50	39.9	1.30	1.80	6.20	0.70	7000	5.20
MCS09H41-	91.0	1.90	75.7	3.20	4.30	16.1	1.29	7000	6.10
MCS09H60-	91.0	1.90	37.8	0.80	1.10	4.00	0.65	7000	6.10
MCS09L41-	91.0	2.80	71.7	1.80	2.40	9.90	1.21	7000	7.90
MCS09L51-	91.0	2.80	35.9	0.44	0.59	2.50	0.60	7000	7.90

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS12D20-	1950	6.40	5.50	18.0	1.10	2.70	2.60	10.0	345	130
MCS12D41-	4050	6.40	4.30	18.0	1.80	5.50	4.50	20.0	310	270
MCS12H15-	1500	11.4	10.0	29.0	1.60	4.10	3.80	12.0	300	100
MCS12H35-	3525	11.4	7.50	29.0	2.80	8.20	5.70	24.0	325	235
MCS12L20-	1950	15.0	13.5	56.0	2.80	6.20	5.90	28.0	330	130
MCS12L41-	4050	15.0	11.0	56.0	4.70	12.4	10.2	57.0	300	270
MCS14D15-	1500	11.0	9.20	29.0	1.45	5.00	4.50	17.0	305	100
MCS14D36-	3600	11.0	7.50	29.0	2.80	10.0	7.50	33.0	295	240
MCS14H15-	1500	21.0	16.0	55.0	2.50	8.50	6.60	26.0	325	100
MCS14H32-	3225	21.0	14.0	55.0	4.70	16.9	11.9	52.0	295	215
MCS14L15-	1500	28.0	23.0	77.0	3.60	12.0	9.70	37.0	315	100
MCS14L32-	3225	28.0	17.2	77.0	5.80	24.0	15.0	75.0	275	215
MCS14P14-	1350	37.0	30.0	105	4.20	12.2	10.8	46.0	340	90
MCS14P32-	3225	37.0	21.0	105	7.10	24.3	15.6	92.0	315	215

	$\eta_{100\%}$ [%]	$J^{1)}$ [kgcm ²]	$KE_{LL, 150\text{ }^\circ\text{C}}$ [V / 1000 rp]	$R_{UV, 20\text{ }^\circ\text{C}}$ [Ω]	$R_{UV, 150\text{ }^\circ\text{C}}$ [Ω]	L_N [mH]	$Kt_{0, 150\text{ }^\circ\text{C}}$ [Nm/A]	$n_{max}^{2)}$ [r/min]	$m^{1)}$ [kg]
MCS12D20-	79.0	4.00	137	8.70	11.8	52.2	2.34	6000	6.40
MCS12D41-	84.0	4.00	68.6	2.20	2.90	13.0	1.17	6000	6.40
MCS12H15-	88.0	7.30	173	5.70	7.70	42.1	2.79	6000	9.50
MCS12H35-	91.0	7.30	86.5	1.40	1.90	10.5	1.40	6000	9.50
MCS12L20-	90.0	10.6	149	2.20	3.00	21.8	2.42	6000	12.6
MCS12L41-	91.0	10.6	74.6	0.55	0.75	5.50	1.21	6000	12.6
MCS14D15-	88.0	8.10	129	4.00	5.40	49.8	2.19	6000	10.7
MCS14D36-	92.0	8.10	64.2	1.00	1.35	12.5	1.09	6000	10.7
MCS14H15-	92.0	14.2	153	2.08	2.81	34.1	2.48	6000	15.5
MCS14H32-	93.0	14.2	76.3	0.52	0.70	8.50	1.24	6000	15.5
MCS14L15-	90.0	23.4	152	1.21	1.64	22.0	2.33	6000	20.1
MCS14L32-	93.0	23.4	76.2	0.30	0.41	5.50	1.16	6000	20.1
MCS14P14-	90.0	34.7	179	1.10	1.49	23.9	3.04	6000	24.9
MCS14P32-	93.0	34.7	89.4	0.28	0.37	6.00	1.52	6000	24.9

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS19F14-	1425	32.0	27.0	86.0	4.00	9.90	8.60	31.0	335	95
MCS19F30-	3000	32.0	21.0	86.0	6.60	19.8	14.0	63.0	300	200
MCS19J14-	1425	51.0	40.0	129	6.00	15.2	12.3	45.0	330	95
MCS19J30-	3000	51.0	29.0	129	9.10	30.5	18.5	90.0	300	200
MCS19P14-	1350	64.0	51.0	190	7.20	17.5	14.3	60.0	330	90
MCS19P30-	3000	64.0	32.0	190	10.0	34.9	19.0	120	320	200

	$\eta_{100\%}$ [%]	$J^1)$ [kgcm ²]	$KE_{LL 150\text{ °C}}$ [V / 1000 rp]	$R_{UV 20\text{ °C}}$ [Ω]	$R_{UV 150\text{ °C}}$ [Ω]	L_N [mH]	$Kt_{0 150\text{ °C}}$ [Nm/A]	$n_{max}^2)$ [r/min]	$m^1)$ [kg]
MCS19F14-	92.0	65.0	195	1.30	1.75	20.8	3.23	4000	23.0
MCS19F30-	93.0	65.0	97.2	0.32	0.44	5.20	1.62	4000	23.0
MCS19J14-	92.0	105	199	0.65	0.88	12.8	3.31	4000	30.0
MCS19J30-	93.0	105	99.5	0.16	0.22	3.20	1.65	4000	30.0
MCS19P14-	92.0	160	216	0.54	0.73	9.60	3.66	4000	40.0
MCS19P30-	93.0	160	108	0.14	0.18	2.40	1.83	4000	40.0

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 230 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS06C41L	4050	0.80	0.60	2.40	0.25	2.50	2.50	10.8	125	270
MCS06C60L	6000	0.80	0.50	2.40	0.31	4.30	4.00	18.5	85	400
MCS06F41L	4050	1.50	1.20	4.40	0.51	2.90	2.90	10.5	165	270
MCS06F60L	6000	1.50	0.90	4.40	0.57	3.80	3.40	16.5	125	400
MCS06I41L	4050	2.00	1.50	6.20	0.64	3.10	2.90	11.8	175	270
MCS06I60L	6000	2.00	1.20	6.20	0.75	4.20	3.60	16.0	150	400
MCS09D41L	4050	3.30	2.30	9.50	1.00	5.30	4.60	20.0	165	270
MCS09D60L	6000	3.30	1.80	9.50	1.10	10.3	7.00	39.0	110	400
MCS09F38L	3750	4.20	3.10	15.0	1.20	6.00	5.00	30.0	160	250
MCS09F60L	6000	4.20	2.40	15.0	1.50	10.5	7.90	53.0	125	400
MCS09H41L	4050	5.50	3.80	20.0	1.60	8.50	6.80	40.0	160	270
MCS09H60L	6000	5.50	3.00	20.0	1.90	12.0	8.00	57.0	145	400
MCS09L41L	4050	7.50	4.50	32.0	1.90	12.4	8.40	64.0	145	270

	$\eta_{100\%}$ [%]	$J^{1)}$ [kgcm ²]	$KE_{LL 150\text{ °C}}$ [V / 1000 rp]	$R_{UV 20\text{ °C}}$ [Ω]	$R_{UV 150\text{ °C}}$ [Ω]	L_N [mH]	$Kt_{0 150\text{ °C}}$ [Nm/A]	$n_{max}^{2)}$ [r/min]	$m^{1)}$ [kg]
MCS06C41L	65.0	0.14	21.5	6.00	8.00	12.8	0.33	8000	1.80
MCS06C60L	70.0	0.14	12.5	2.20	2.90	4.30	0.19	8000	1.80
MCS06F41L	81.0	0.22	34.5	5.50	7.40	15.9	0.62	8000	2.20
MCS06F60L	82.0	0.22	22.2	2.30	3.00	6.90	0.40	8000	2.20
MCS06I41L	81.0	0.30	38.0	4.70	6.20	15.1	0.64	8000	2.90
MCS06I60L	84.0	0.30	28.5	2.50	3.40	9.30	0.48	8000	2.90
MCS09D41L	87.0	1.10	35.6	1.80	2.40	6.30	0.62	7000	4.30
MCS09D60L	87.0	1.10	18.3	0.45	0.61	1.70	0.32	7000	4.30
MCS09F38L	90.0	1.50	39.9	1.30	1.80	6.20	0.70	7000	5.20
MCS09F60L	91.0	1.50	22.8	0.42	0.56	2.00	0.40	7000	5.20
MCS09H41L	91.0	1.90	37.8	0.80	1.10	4.00	0.65	7000	6.10
MCS09H60L	91.0	1.90	26.6	0.36	0.48	2.00	0.46	7000	6.10
MCS09L41L	91.0	2.80	35.9	0.44	0.59	2.50	0.60	7000	7.90

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 230 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS12D20L	1950	6.40	5.50	18.0	1.10	5.50	5.20	20.0	175	130
MCS12D41L	4050	6.40	4.30	18.0	1.80	10.7	8.80	40.0	155	270
MCS12H15L	1500	11.4	10.0	29.0	1.60	8.20	7.80	24.0	158	100
MCS12H30L	3000	11.4	8.00	29.0	2.50	13.5	10.5	39.0	165	200
MCS12L20L	1950	15.0	13.5	56.0	2.80	12.4	11.8	57.0	165	130

	$\eta_{100\%}$ [%]	$J^{1)}$ [kgcm ²]	$KE_{LL, 150\text{ °C}}$ [V / 1000 rp]	$R_{UV, 20\text{ °C}}$ [Ω]	$R_{UV, 150\text{ °C}}$ [Ω]	L_N [mH]	$Kt_{0, 150\text{ °C}}$ [Nm/A]	$n_{max}^{2)}$ [r/min]	$m^{1)}$ [kg]
MCS12D20L	79.0	4.00	68.6	2.20	2.90	13.0	1.17	6000	6.40
MCS12D41L	84.0	4.00	35.0	0.55	0.75	3.40	0.60	6000	6.40
MCS12H15L	82.0	7.30	86.5	1.41	1.90	10.5	1.40	6000	9.50
MCS12H30L	87.0	7.30	53.0	0.50	0.67	4.00	0.86	6000	9.50
MCS12L20L	90.0	10.6	76.9	0.55	0.75	5.50	1.21	6000	12.6

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Rated data, forced ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS12D17-	1650	7.50	7.00	17.7	1.20	3.20	3.00	10.0	330	110
MCS12D35-	3525	7.50	6.00	17.7	2.20	6.40	5.60	20.0	300	235
MCS12H14-	1350	12.8	12.0	29.0	1.70	4.30	4.10	12.0	310	90
MCS12H34-	3375	12.8	10.5	29.0	3.70	8.50	7.50	24.0	320	225
MCS12L17-	1650	19.0	17.0	56.4	2.90	7.20	6.70	28.0	300	110
MCS12L39-	3900	19.0	14.0	56.4	5.70	14.4	11.7	57.0	295	260
MCS14D14-	1350	12.5	12.0	29.0	1.70	5.70	5.40	17.0	345	90
MCS14D30-	3000	12.5	10.5	29.0	3.30	11.4	9.70	33.0	325	200
MCS14H12-	1200	25.5	23.5	54.8	3.00	9.30	8.30	26.0	335	80
MCS14H28-	2775	25.5	20.5	54.8	6.00	18.4	15.0	52.0	325	185
MCS14L14-	1350	34.5	30.5	77.1	4.30	13.4	11.8	37.0	335	90
MCS14L30-	3000	34.5	25.5	77.1	8.00	26.7	20.8	75.0	310	200
MCS14P11-	1050	43.5	42.0	105	4.60	14.1	13.4	46.0	330	70
MCS14P26-	2625	43.5	33.0	105	9.10	28.3	21.9	92.0	325	175

	$\eta_{100\%}$ [%]	$J^{1)}$ [kgcm ²]	$KE_{LL, 150\text{ }^\circ\text{C}}$ [V / 1000 rp]	$R_{UV, 20\text{ }^\circ\text{C}}$ [Ω]	$R_{UV, 150\text{ }^\circ\text{C}}$ [Ω]	L_N [mH]	$Kt_{0, 150\text{ }^\circ\text{C}}$ [Nm/A]	$n_{max}^{2)}$ [r/min]	$m^{1)}$ [kg]
MCS12D17-	75.0	4.00	137	8.72	11.8	52.2	2.34	6000	8.50
MCS12D35-	82.0	4.00	68.6	2.18	2.94	13.0	1.17	6000	8.50
MCS12H14-	80.0	7.30	173	5.72	7.72	42.1	2.98	6000	11.6
MCS12H34-	86.0	7.30	86.5	1.39	1.88	10.5	1.51	6000	11.6
MCS12L17-	90.0	10.6	149	2.22	2.99	21.8	2.64	6000	14.7
MCS12L39-	94.0	10.6	74.6	0.55	0.75	5.50	1.32	6000	14.7
MCS14D14-	84.0	8.10	129	4.00	5.40	49.8	2.19	6000	14.5
MCS14D30-	92.0	8.10	64.2	1.00	1.35	12.5	1.09	6000	14.5
MCS14H12-	87.0	14.2	153	2.08	2.81	34.1	2.75	6000	19.5
MCS14H28-	93.0	14.2	76.3	0.52	0.70	8.50	1.39	6000	19.5
MCS14L14-	88.0	23.4	152	1.21	1.64	22.0	2.57	6000	24.0
MCS14L30-	92.0	23.4	76.2	0.30	0.41	5.50	1.29	6000	24.0
MCS14P11-	86.0	34.7	179	1.10	1.49	23.9	3.08	6000	29.0
MCS14P26-	92.0	34.7	89.4	0.28	0.37	6.00	1.54	6000	29.0

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Rated data, forced ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	I_{max} [A]	$U_{N, AC}$ [V]	f_N [Hz]
MCS19F12-	1200	41.5	38.0	86.0	4.80	12.2	11.3	31.0	320	80
MCS19F29-	2850	41.5	32.5	86.0	9.70	24.5	20.1	63.0	320	190
MCS19J12-	1200	70.5	62.5	129	7.90	20.3	18.3	45.0	320	80
MCS19J29-	2850	70.5	50.5	129	15.1	40.6	31.0	90.0	315	190
MCS19P12-	1200	86.0	72.0	190	9.00	22.4	21.3	60.0	310	80
MCS19P29-	2850	86.0	53.0	190	15.8	44.7	29.5	120	315	190

	$\eta_{100\%}$ [%]	J^1 [kgcm ²]	$KE_{LL 150\text{ °C}}$ [V /1000 rp]	$R_{UV 20\text{ °C}}$ [Ω]	$R_{UV 150\text{ °C}}$ [Ω]	L_N [mH]	$Kt_{0 150\text{ °C}}$ [Nm/A]	n_{max}^2 [r/min]	m^1 [kg]
MCS19F12-	90.4	65.0	195	1.30	1.75	20.8	3.40	4000	29.0
MCS19F29-	94.7	65.0	97.2	0.32	0.44	5.20	1.69	4000	29.0
MCS19J12-	89.3	105	199	0.65	0.88	12.8	3.47	4000	36.0
MCS19J29-	92.8	105	99.5	0.16	0.22	3.20	1.74	4000	36.0
MCS19P12-	90.3	160	216	0.54	0.73	9.60	3.84	4000	46.0
MCS19P29-	93.4	160	108	0.14	0.18	2.40	1.92	4000	46.0

¹⁾ Without brake.

²⁾ Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

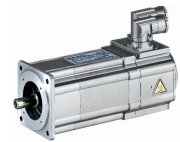
- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
06C41-	0.6	4050	1.3	0.25	M_0	0.8										
					M_N	0.6										
					$M_{0,max}$	2.4										
					M_{max}	2.4										
					η_{eto}	-										
06C60-	0.5	6000	2.4	0.31	M_0	0.6	0.8									
					M_N	0.4	0.5									
					$M_{0,max}$	1.5	2.3									
					M_{max}	1.5	2.3									
					η_{eto}	-	-									
06F41-	1.2	4050	1.5	0.51	M_0	1.5										
					M_N	1.2										
					$M_{0,max}$	4.4										
					M_{max}	4.4										
					η_{eto}	-										
06F60-	0.9	6000	2.5	0.57	M_0	1.0	1.5									
					M_N	0.7	0.9									
					$M_{0,max}$	3.0	4.3									
					M_{max}	3.0	4.3									
					η_{eto}	-	-									
06I41-	1.5	4050	1.6	0.64	M_0	2.0										
					M_N	1.5										
					$M_{0,max}$	6.2										
					M_{max}	6.2										
					η_{eto}	-										
06I60-	1.2	6000	2.9	0.75	M_0	1.1	1.8	2.0								
					M_N	0.8	1.2	1.2								
					$M_{0,max}$	3.3	5.5	6.2								
					M_{max}	3.3	5.5	6.2								
					η_{eto}	-	-	-								
09D41-	2.3	4050	2.3	1.00	M_0	2.4	3.3									
					M_N	1.9	2.3									
					$M_{0,max}$	6.3	9.5									
					M_{max}	6.3	9.5									
					η_{eto}	-	-									
09D60-	1.8	6000	3.8	1.10	M_0			3.1	3.3							
					M_N			1.8	1.8							
					$M_{0,max}$			8.0	9.5							
					M_{max}			8.0	9.5							
					η_{eto}			-	-							
09F38-	3.1	3750	2.5	1.20	M_0		4.2	4.2								
					M_N		3.1	3.1								
					$M_{0,max}$		11.6	14.9								
					M_{max}		11.6	14.9								
					η_{eto}		-	-								

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
09F60-	2.4	6000	4.5	1.50	M_0			3.5	4.2	4.2	4.2					
					M_N			2.4	2.4	2.4	2.4					
					$M_{0,max}$			9.8	12.0	14.4	14.9					
					M_{max}			9.8	12.0	14.4	14.9					
					η_{eto}			-	-	-	-					
09H41-	3.8	4050	3.4	1.60	M_0		4.0	5.5	5.5							
					M_N		3.5	3.8	3.8							
					$M_{0,max}$		12.0	17.5	20.4							
					M_{max}		12.0	17.5	20.4							
					η_{eto}		-	-	-							
09H60-	3.0	6000	6.0	1.90	M_0				5.5	5.5	5.5	5.5				
					M_N				3.0	3.0	3.0	3.0				
					$M_{0,max}$				12.5	15.8	20.1	20.4				
					M_{max}				12.5	15.8	20.1	20.4				
					η_{eto}				-	-	-	-				
09L41-	4.5	4050	4.2	1.90	M_0			6.0	7.5	7.5						
					M_N			4.5	4.5	4.5						
					$M_{0,max}$			17.4	22.2	28.5						
					M_{max}			17.4	22.2	28.5						
					η_{eto}			-	-	-						
09L51-	3.6	5100	6.9	1.90	M_0				5.3	7.0	7.5	7.5	7.5			
					M_N				3.6	3.6	3.6	3.6	3.6			
					$M_{0,max}$				11.9	15.5	20.9	25.8	29.7			
					M_{max}				11.9	15.5	20.9	25.8	29.7			
					η_{eto}				-	-	-	-	-			
12D20-	5.5	1950	2.6	1.10	M_0	4.4	6.4									
					M_N	4.0	5.5									
					$M_{0,max}$	11.8	17.7									
					M_{max}	11.8	17.7									
					η_{eto}	-	-									
12D41-	4.3	4050	4.5	1.80	M_0			5.9	6.4							
					M_N			4.3	4.3							
					$M_{0,max}$			14.7	17.7							
					M_{max}			14.7	17.7							
					η_{eto}			-	-							
12H15-	10.0	1500	3.8	1.60	M_0		8.7	11.4								
					M_N		8.2	10.0								
					$M_{0,max}$		24.6	29.0								
					M_{max}		24.6	29.0								
					η_{eto}		-	-								
12H35-	7.5	3525	5.7	2.80	M_0			7.0	11.4	11.4	11.4					
					M_N			6.6	7.5	7.5	7.5					
					$M_{0,max}$			20.1	25.8	29.0	29.0					
					M_{max}			20.1	25.8	29.0	29.0					
					η_{eto}			-	-	-	-					

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594				
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0				
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0				
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0				
12L20-	13.5	1950	5.9	2.80	M_0			12.1	15.0	15.0	15.0									
					M_N			11.4	13.5	13.5	13.5									
					$M_{0,max}$			35.5	44.6	55.7	56.4									
					M_{max}			35.5	44.6	55.7	56.4									
					η_{eto}			-	-	-	-									
12L41-	11.0	4050	10.2	4.70	M_0				10.6	14.0	15.0	15.0	15.0							
					M_N				9.5	11.0	11.0	11.0	11.0							
					$M_{0,max}$				24.4	31.6	41.9	50.8	56.4							
					M_{max}				24.4	31.6	41.9	50.8	56.4							
					η_{eto}				-	-	-	-	-							
14D15-	9.2	1500	4.5	1.45	M_0			11.0	11.0											
					M_N			9.2	9.2											
					$M_{0,max}$			28.3	29.0											
					M_{max}			28.3	29.0											
					η_{eto}			-	-											
14D36-	7.5	3600	7.5	2.80	M_0				9.6	11.0	11.0									
					M_N				7.5	7.5	7.5									
					$M_{0,max}$				20.2	25.6	29.0									
					M_{max}				20.2	25.6	29.0									
					η_{eto}				-	-	-									
14H15-	16.0	1500	6.6	2.50	M_0			12.4	21.0	21.0	21.0									
					M_N			12.1	16.0	16.0	16.0									
					$M_{0,max}$			37.1	46.6	54.8	54.8									
					M_{max}			37.1	46.6	54.8	54.8									
					η_{eto}			-	-	-	-									
14H32-	14.0	3225	11.9	4.70	M_0					14.4	20.3	21.0	21.0							
					M_N					13.6	14.0	14.0	14.0							
					$M_{0,max}$					33.0	43.9	53.2	54.8							
					M_{max}					33.0	43.9	53.2	54.8							
					η_{eto}					-	-	-	-							
14L15-	23.0	1500	9.7	3.60	M_0				20.5	27.1	28.0									
					M_N				20.9	23.0	23.0									
					$M_{0,max}$				48.0	61.4	77.1									
					M_{max}				48.0	61.4	77.1									
					η_{eto}				-	-	-									
14L32-	17.2	3225	15.0	5.80	M_0						19.0	24.0	28.0	28.0	28.0					
					M_N					17.2	17.2	17.2	17.2	17.2						
					$M_{0,max}$					45.0	55.3	63.9	77.1	77.1						
					M_{max}					45.0	55.3	63.9	77.1	77.1						
					η_{eto}					-	-	-	-	-						
14P14-	30.0	1350	10.8	4.20	M_0				26.7	35.2	37.0	37.0								
					M_N				24.4	30.0	30.0	30.0								
					$M_{0,max}$				56.1	71.7	93.3	105.1								
					M_{max}				56.1	71.7	93.3	105.1								
					η_{eto}				-	-	-	-								

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I _N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					I _{0,max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M _N	n _N	I _N	P _N	I _{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
14P32-	21.0	3225	15.6	7.10	M ₀						24.8	31.4	37.0	37.0	37.0	
					M _N						21.0	21.0	21.0	21.0	21.0	
					M _{0,max}						52.5	64.6	74.7	92.2	105.1	
					M _{max}						52.5	64.6	74.7	92.2	105.1	
					η _{eto}						-	-	-	-	-	
19F14-	27.0	1425	8.6	4.00	M ₀			28.4	32.0	32.0						
					M _N			27.0	27.0	27.0						
					M _{0,max}			62.1	78.9	86.0						
					M _{max}			62.1	78.9	86.0						
					η _{eto}			-	-	-						
19F30-	21.0	3000	14.0	6.60	M ₀					26.3	32.0	32.0	32.0			
					M _N					21.0	21.0	21.0	21.0			
					M _{0,max}					56.6	70.2	81.6	86.0			
					M _{max}					56.6	70.2	81.6	86.0			
					η _{eto}					-	-	-	-			
19J14-	40.0	1425	12.3	6.00	M ₀				38.9	51.0	51.0					
					M _N				37.7	40.0	40.0					
					M _{0,max}				85.0	114.4	129.0					
					M _{max}				85.0	114.4	129.0					
					η _{eto}				-	-	-					
19J30-	29.0	3000	18.5	9.10	M ₀					27.3	34.4	49.2	51.0	51.0		
					M _N					25.6	29.0	29.0	29.0	29.0		
					M _{0,max}					60.8	75.9	88.9	112.9	129.0		
					M _{max}					60.8	75.9	88.9	112.9	129.0		
					η _{eto}					-	-	-	-	-		
19P14-	51.0	1350	14.3	7.20	M ₀					59.6	64.0	64.0	64.0			
					M _N					51.0	51.0	51.0	51.0			
					M _{0,max}					128.4	159.9	186.6	190.0			
					M _{max}					128.4	159.9	186.6	190.0			
					η _{eto}					-	-	-	-			
19P30-	32.0	3000	19.0	10.00	M ₀					29.9	37.8	53.9	64.0	64.0	64.0	
					M _N					27.5	32.0	32.0	32.0	32.0	32.0	
					M _{0,max}					65.7	83.6	98.5	126.6	152.5	187.2	
					M _{max}					65.7	83.6	98.5	126.6	152.5	187.2	
					η _{eto}					-	-	-	-	-	-	

- I... [A], M... [Nm], n... [r/min], P... [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3x230V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
06C41L	0.6	4050	2.6	0.25	M_0	0.6	0.8							
					M_N	0.5	0.6							
					$M_{0,max}$	1.5	2.3							
					M_{max}	1.5	2.3							
					η_{eto}	-	-							
06C60L	0.5	6000	4.0	0.31	M_0		0.6	0.8	0.8					
					M_N		0.4	0.5	0.5					
					$M_{0,max}$		1.5	2.2	2.4					
					M_{max}		1.5	2.2	2.4					
					η_{eto}		-	-	-					
06F41L	1.2	4050	2.9	0.51	M_0	1.0	1.5	1.5						
					M_N	0.8	1.2	1.2						
					$M_{0,max}$	2.7	4.2	4.4						
					M_{max}	2.7	4.2	4.4						
					η_{eto}	-	-	-						
06F60L	0.9	6000	3.8	0.57	M_0		1.2	1.5	1.5					
					M_N		0.8	0.9	0.9					
					$M_{0,max}$		3.1	4.3	4.4					
					M_{max}		3.1	4.3	4.4					
					η_{eto}		-	-	-					
06I41L	1.5	4050	3.2	0.64	M_0		2.0	2.0						
					M_N		1.5	1.5						
					$M_{0,max}$		5.4	6.2						
					M_{max}		5.4	6.2						
					η_{eto}		-	-						
06I60L	1.2	6000	3.8	0.75	M_0		1.5	2.0						
					M_N		1.0	1.2						
					$M_{0,max}$		4.4	6.2						
					M_{max}		4.4	6.2						
					η_{eto}		-	-						
09D41L	2.3	4050	4.6	1.00	M_0			3.1	3.3					
					M_N			2.3	2.3					
					$M_{0,max}$			8.0	9.5					
					M_{max}			8.0	9.5					
					η_{eto}			-	-					
09D60L	1.8	6000	7.0	1.10	M_0				2.8	3.3	3.3			
					M_N				1.8	1.8	1.8			
					$M_{0,max}$				5.7	7.3	9.5			
					M_{max}				5.7	7.3	9.5			
					η_{eto}				-	-	-			
09F38L	3.1	3750	5.0	1.20	M_0			3.5	4.2	4.2	4.2			
					M_N			3.1	3.1	3.1	3.1			
					$M_{0,max}$			9.8	12.0	13.8	15.0			
					M_{max}			9.8	12.0	13.8	15.0			
					η_{eto}			-	-	-	-			

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3x230V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
09F60L	2.4	6000	7.9	1.50	M_0				3.5	4.2	4.2	4.2	4.2	
					M_N				2.4	2.4	2.4	2.4	2.4	
					$M_{0,max}$				7.8	9.8	12.6	14.5	15.0	
					M_{max}				7.8	9.8	12.6	14.5	15.0	
					η_{eto}				-	-	-	-	-	
09H41L	3.8	4050	6.8	1.60	M_0				5.5	5.3	5.5	5.5		
					M_N				3.8	3.0	3.8	3.8		
					$M_{0,max}$				12.4	11.8	19.7	20.0		
					M_{max}				12.4	11.8	19.7	20.0		
					η_{eto}				-	-	-	-		
09H60L	3.0	6000	8.0	1.90	M_0				4.0	5.5	5.5	5.5	5.5	
					M_N				3.0	3.8	3.0	3.0	3.0	
					$M_{0,max}$				9.2	15.6	15.4	18.3	20.0	
					M_{max}				9.2	15.6	15.4	18.3	20.0	
					η_{eto}				-	-	-	-	-	
09L41L	4.5	4050	8.4	1.90	M_0				5.3	7.0	7.5	7.5	7.5	7.5
					M_N				4.5	4.5	4.5	4.5	4.5	4.5
					$M_{0,max}$				11.9	15.5	20.9	25.8	29.7	31.9
					M_{max}				11.9	15.5	20.9	25.8	29.7	31.9
					η_{eto}				-	-	-	-	-	-
12D20L	5.5	1950	5.2	1.10	M_0			5.9	6.4					
					M_N			5.3	5.5					
					$M_{0,max}$			14.9	17.7					
					M_{max}			14.9	17.7					
					η_{eto}			-	-					
12D41L	4.3	4050	8.8	1.80	M_0				5.3	6.4	6.4	6.4		
					M_N				4.3	4.3	4.3	4.3		
					$M_{0,max}$				10.6	13.6	17.7	17.9		
					M_{max}				10.6	13.6	17.7	17.9		
					η_{eto}				-	-	-	-		
12H15L	10.0	1500	7.6	1.60	M_0				11.4	11.4	10.0			
					M_N				10.0	10.0	11.4			
					$M_{0,max}$				25.8	29.0	29.0			
					M_{max}				25.8	29.0	29.0			
					η_{eto}				-	-	-			
12H30L	8.0	3000	10.5	2.50	M_0				7.4	9.8	11.4			
					M_N				6.7	8.0	8.0			
					$M_{0,max}$				16.4	21.5	29.0			
					M_{max}				16.4	21.5	29.0			
					η_{eto}				-	-	-			
12L20L	13.5	1950	11.8	2.80	M_0				10.6	14.0	15.0	15.0	15.0	
					M_N				10.1	13.3	13.5	13.5	13.5	
					$M_{0,max}$				24.4	31.5	41.8	50.5	56.0	
					M_{max}				24.4	31.5	41.8	50.5	56.0	
					η_{eto}				-	-	-	-	-	

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
12D17-	7.0	1650	3.0	1.20	M_0	4.4	7.3									
					M_N	4.0	7.0									
					$M_{0,max}$	11.8	17.7									
					M_{max}	11.8	17.7									
					η_{eto}	-	-									
12D35-	6.0	3525	5.6	2.20	M_0			5.9	7.5							
					M_N			5.4	6.0							
					$M_{0,max}$			14.7	17.7							
					M_{max}			14.7	17.7							
					η_{eto}			-	-							
12H14-	12.0	1350	4.1	1.70	M_0		8.7	12.8								
					M_N		8.2	12.0								
					$M_{0,max}$		24.6	29.0								
					M_{max}		24.6	29.0								
					η_{eto}		-	-								
12H34-	10.5	3375	7.5	3.70	M_0			7.0	12.8	12.8	12.8					
					M_N			6.6	10.5	10.5	10.5					
					$M_{0,max}$			20.1	25.8	29.0	29.0					
					M_{max}			20.1	25.8	29.0	29.0					
					η_{eto}			-	-	-	-					
12L17-	17.0	1650	6.7	2.90	M_0			12.1	19.0	19.0	19.0					
					M_N			11.4	17.0	17.0	17.0					
					$M_{0,max}$			35.5	44.6	55.7	56.4					
					M_{max}			35.5	44.6	55.7	56.4					
					η_{eto}			-	-	-	-					
12L39-	14.0	3900	11.7	5.70	M_0				10.6	15.3	19.0	19.0	19.0			
					M_N				9.5	13.9	14.0	14.0	14.0			
					$M_{0,max}$				24.4	31.6	41.9	50.8	56.4			
					M_{max}				24.4	31.6	41.9	50.8	56.4			
					η_{eto}				-	-	-	-	-			
14D14-	12.0	1350	5.4	1.70	M_0			11.0	12.5							
					M_N			11.0	12.0							
					$M_{0,max}$			28.3	29.0							
					M_{max}			28.3	29.0							
					η_{eto}			-	-							
14D30-	10.5	3000	9.7	3.30	M_0				9.6	12.5	12.5					
					M_N				9.5	10.5	10.5					
					$M_{0,max}$				20.2	25.6	29.0					
					M_{max}				20.2	25.6	29.0					
					η_{eto}				-	-	-					
14H12-	23.5	1200	8.3	3.00	M_0			12.4	24.1	25.5	25.5					
					M_N			12.1	23.5	23.5	23.5					
					$M_{0,max}$			37.1	46.6	54.8	54.8					
					M_{max}			37.1	46.6	54.8	54.8					
					η_{eto}			-	-	-	-					

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
14H28-	20.5	2775	15.0	6.00	M_0					16.1	20.5	25.5	25.5			
					M_N					15.9	20.5	20.5	20.5			
					$M_{0,max}$						33.0	43.9	53.2	54.8		
					M_{max}							33.0	43.9	53.2	54.8	
					η_{eto}							-	-	-	-	
14L14-	30.5	1350	11.8	4.30	M_0			20.5	30.0	34.5						
					M_N			20.5	30.0	30.5						
					$M_{0,max}$			48.0	61.4	77.1						
					M_{max}			48.0	61.4	77.1						
					η_{eto}			-	-	-						
14L30-	25.5	3000	20.8	8.00	M_0					21.0	26.6	34.5	34.5	34.5		
					M_N					20.0	25.3	25.5	25.5	25.5		
					$M_{0,max}$						45.0	55.3	63.9	77.1	77.1	
					M_{max}						45.0	55.3	63.9	77.1	77.1	
					η_{eto}						-	-	-	-	-	
14P11-	42.0	1050	13.4	4.60	M_0			26.7	36.4	43.5	43.5					
					M_N			24.4	36.4	42.0	42.0					
					$M_{0,max}$			56.1	71.7	93.3	105.1					
					M_{max}			56.1	71.7	93.3	105.1					
					η_{eto}			-	-	-	-					
14P26-	33.0	2625	21.9	9.10	M_0					24.8	31.4	43.5	43.5	43.5		
					M_N					24.6	31.0	33.0	33.0	33.0		
					$M_{0,max}$						52.5	64.6	74.7	92.2	105.1	
					M_{max}						52.5	64.6	74.7	92.2	105.1	
					η_{eto}						-	-	-	-	-	
19F12-	38.0	1200	11.3	4.80	M_0			29.9	39.5	41.5						
					M_N			29.3	38.0	38.0						
					$M_{0,max}$			62.1	78.9	86.0						
					M_{max}			62.1	78.9	86.0						
					η_{eto}			-	-	-						
19F29-	32.5	2850	20.1	9.70	M_0					26.3	34.9	41.5	41.5			
					M_N					26.0	32.5	32.5	32.5			
					$M_{0,max}$						56.6	70.2	81.6	86.0		
					M_{max}						56.6	70.2	81.6	86.0		
					η_{eto}						-	-	-	-		
19J12-	62.5	1200	18.3	7.90	M_0					56.6	70.5					
					M_N					55.7	62.5					
					$M_{0,max}$						114.4	129.0				
					M_{max}						114.4	129.0				
					η_{eto}						-	-				
19J29-	50.5	2850	31.0	15.10	M_0							49.2	66.7	70.5		
					M_N							47.9	50.5	50.5		
					$M_{0,max}$							88.9	112.9	129.0		
					M_{max}							88.9	112.9	129.0		
					η_{eto}							-	-	-		

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
19P12-	72.0	1200	21.3	9.00	M_0							79.1	86.0	86.0		
					M_N							69.6	72.0	72.0		
					$M_{0,max}$							159.9	186.6	190.0		
					M_{max}							159.9	186.6	190.0		
					η_{eto}							-	-	-		
19P29-	53.0	2850	29.5	15.80	M_0							56.5	73.9	86.0	86.0	
					M_N							52.8	53.0	53.0	53.0	
					$M_{0,max}$							98.5	126.6	152.5	187.2	
					M_{max}							98.5	126.6	152.5	187.2	
					η_{eto}							-	-	-	-	

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.8	14.6
06C41-	0.6	4050	1.3	0.25	M_0	0.8	0.8	0.8	0.8	0.8		
					M_N	0.6	0.6	0.6	0.6	0.6		
					$M_{0,max}$	1.4	1.7	2.3	2.4	2.4		
					M_{max}	1.4	1.7	2.3	2.4	2.4		
					η_{eto}	-	-	-	-	-		
06C60-	0.5	6000	2.4	0.31	M_0			0.8	0.8	0.8	0.8	0.8
					M_N			0.5	0.5	0.5	0.5	0.5
					$M_{0,max}$			1.3	1.6	2.0	2.4	2.4
					M_{max}			1.3	1.6	2.0	2.4	2.4
					η_{eto}			-	-	-	-	-
06F41-	1.2	4050	1.5	0.51	M_0	1.3	1.5	1.5	1.5	1.5		
					M_N	1.0	1.2	1.2	1.2	1.2		
					$M_{0,max}$	2.3	3.2	4.3	4.4	4.4		
					M_{max}	2.3	3.2	4.3	4.4	4.4		
					η_{eto}	-	-	-	-	-		
06F60-	0.9	6000	2.5	0.57	M_0			1.2	1.5	1.5	1.5	1.5
					M_N			0.9	0.9	0.9	0.9	0.9
					$M_{0,max}$			2.1	3.3	4.0	4.4	4.4
					M_{max}			2.1	3.3	4.0	4.4	4.4
					η_{eto}			-	-	-	-	-
06I41-	1.5	4050	1.6	0.64	M_0	1.6	2.0	2.0	2.0	2.0		
					M_N	1.2	1.5	1.5	1.5	1.5		
					$M_{0,max}$	2.9	4.0	5.3	6.2	6.2		
					M_{max}	2.9	4.0	5.3	6.2	6.2		
					η_{eto}	-	-	-	-	-		
06I60-	1.2	6000	2.9	0.75	M_0				2.0	2.0	2.0	2.0
					M_N				1.2	1.2	1.2	1.2
					$M_{0,max}$				3.6	4.4	5.7	5.7
					M_{max}				3.6	4.4	5.7	5.7
					η_{eto}				-	-	-	-
09D41-	2.3	4050	2.3	1.00	M_0		2.2	3.1	3.3	3.3	3.3	3.3
					M_N		1.7	2.3	2.3	2.3	2.3	2.3
					$M_{0,max}$		4.0	5.3	6.7	8.2	9.4	9.4
					M_{max}		4.0	5.3	6.7	8.2	9.4	9.4
					η_{eto}		-	-	-	-	-	-
09D60-	1.8	6000	3.8	1.10	M_0				2.0	2.4	3.3	3.3
					M_N				1.5	1.8	1.8	1.8
					$M_{0,max}$				3.5	4.2	6.3	7.8
					M_{max}				3.5	4.2	6.3	7.8
					η_{eto}				-	-	-	-
09F38-	3.1	3750	2.5	1.20	M_0			3.4	4.2	4.2	4.2	4.2
					M_N			3.0	3.1	3.1	3.1	3.1
					$M_{0,max}$			6.6	8.4	10.2	12.0	12.0
					M_{max}			6.6	8.4	10.2	12.0	12.0
					η_{eto}			-	-	-	-	-

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC					
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N	P_N	I_N	n_N	M_N	MCS
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$					
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}					
								M_0	0.25	1.3	4050	0.6	06C41-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
								M_0	0.31	2.4	6000	0.5	06C60-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
								M_0	0.51	1.5	4050	1.2	06F41-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
								M_0	0.57	2.5	6000	0.9	06F60-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
								M_0	0.64	1.6	4050	1.5	06I41-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
								M_0	0.75	2.9	6000	1.2	06I60-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
								M_0	1.00	2.3	4050	2.3	09D41-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					
3.3	3.3							M_0	1.10	3.8	6000	1.8	09D60-
1.8	1.8							M_N					
9.1	9.3							$M_{0,max}$					
9.1	9.3							M_{max}					
-	-							n_{eto}					
								M_0	1.20	2.5	3750	3.1	09F38-
								M_N					
								$M_{0,max}$					
								M_{max}					
								n_{eto}					

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.8	14.6
09F60-	2.4	6000	4.5	1.50	M_0						4.2	4.2
					M_N						2.4	2.4
					$M_{0,max}$						7.8	9.6
					M_{max}						7.8	9.6
					η_{eto}						-	-
09H41-	3.8	4050	3.4	1.60	M_0				4.7	5.0	5.5	5.5
					M_N				3.6	3.8	3.8	3.8
					$M_{0,max}$				8.1	9.9	14.0	17.4
					M_{max}				8.1	9.9	14.0	17.4
					η_{eto}				-	-	-	-
09H60-	3.0	6000	6.0	1.90	M_0						4.4	4.5
					M_N						3.0	3.0
					$M_{0,max}$						7.5	9.3
					M_{max}						7.5	9.3
					η_{eto}						-	-
09L41-	4.5	4050	4.2	1.90	M_0				3.9	4.7	7.5	7.5
					M_N				3.4	4.2	4.5	4.5
					$M_{0,max}$				7.3	8.9	13.1	16.3
					M_{max}				7.3	8.9	13.1	16.3
					η_{eto}				-	-	-	-
09L51-	3.6	5100	6.9	1.90	M_0							4.2
					M_N							3.6
					$M_{0,max}$							8.3
					M_{max}							8.3
					η_{eto}							-
12D20-	5.5	1950	2.6	1.10	M_0			5.7	6.4	6.4	6.4	6.4
					M_N			5.1	5.5	5.5	5.5	5.5
					$M_{0,max}$			9.6	12.6	15.3	17.7	17.7
					M_{max}			9.6	12.6	15.3	17.7	17.7
					η_{eto}			-	-	-	-	-
12D41-	4.3	4050	4.5	1.80	M_0				3.8	4.6	6.4	6.4
					M_N				3.0	3.7	4.3	4.3
					$M_{0,max}$				6.4	7.8	11.4	14.0
					M_{max}				6.4	7.8	11.4	14.0
					η_{eto}				-	-	-	-
12H15-	10.0	1500	3.8	1.60	M_0				9.2	10.9	11.4	11.4
					M_N				8.4	10.0	10.0	10.0
					$M_{0,max}$				16.4	20.0	29.0	29.0
					M_{max}				16.4	20.0	29.0	29.0
					η_{eto}				-	-	-	-
12H35-	7.5	3525	5.7	2.80	M_0						9.8	9.8
					M_N						7.5	7.5
					$M_{0,max}$						15.2	18.8
					M_{max}						15.2	18.8
					η_{eto}						-	-

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC						
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N		P_N	I_N	n_N	M_N	MCS
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$						
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}						
4.2	4.2							M_0	1.50	4.5	6000	2.4	09F60-	
2.4	2.4							M_N						
11.1	11.4							$M_{0,max}$						
11.1	11.4							M_{max}						
-	-							n_{eto}	1.60	3.4	4050	3.8	09H41-	
5.5	5.5							M_0						
3.8	3.8							M_N						
19.6	20.1							$M_{0,max}$						
19.6	20.1							M_{max}	1.90	6.0	6000	3.0	09H60-	
-	-							n_{eto}						
5.5	5.5							M_0						
3.0	3.0							M_N						
11.4	11.7							$M_{0,max}$	1.90	4.2	4050	4.5	09L41-	
11.4	11.7							M_{max}						
-	-							n_{eto}						
7.5	7.5							M_0						
4.5	4.5							M_N	1.90	6.9	5100	3.6	09L51-	
20.3	20.8							$M_{0,max}$						
20.3	20.8							M_{max}						
-	-							n_{eto}						
7.5	7.5	7.5	7.5					M_0	1.90	2.6	1950	5.5	12D20-	
3.6	3.6	3.6	3.6					M_N						
10.8	19.1	19.1	19.1					$M_{0,max}$						
10.8	19.1	19.1	19.1					M_{max}						
-	-	-	-					n_{eto}	1.80	4.5	4050	4.3	12D41-	
								M_0						
								M_N						
								$M_{0,max}$						
								M_{max}	1.60	3.8	1500	10.0	12H15-	
								n_{eto}						
6.4	6.4							M_0						
4.3	4.3							M_N						
16.9	17.3							$M_{0,max}$	2.80	5.7	3525	7.5	12H35-	
16.9	17.3							M_{max}						
-	-							n_{eto}						
11.4	11.4							M_0						
10.0	10.0							M_N	2.80	7.5	3525	7.5	12H35-	
28.3	29.0							$M_{0,max}$						
28.3	29.0							M_{max}						
-	-							n_{eto}						
11.4	11.4							M_0	2.80	5.7	3525	7.5	12H35-	
7.5	7.5							M_N						
23.5	24.1							$M_{0,max}$						
23.5	24.1							M_{max}						
-	-							n_{eto}						

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.8	14.6
12L20-	13.5	1950	5.9	2.80	M_0						15.0	15.0
					M_N						13.5	13.5
					$M_{0,max}$						27.4	33.9
					M_{max}						27.4	33.9
					η_{eto}						-	-
12L41-	11.0	4050	10.2	4.70	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					η_{eto}							
14D15-	9.2	1500	4.5	1.45	M_0				7.0	8.5	11.0	11.0
					M_N				6.6	8.0	9.2	9.2
					$M_{0,max}$				13.1	16.0	22.7	28.1
					M_{max}				13.1	16.0	22.7	28.1
					η_{eto}				-	-	-	-
14D36-	7.5	3600	7.5	2.80	M_0							8.0
					M_N							7.3
					$M_{0,max}$							15.2
					M_{max}							15.2
					η_{eto}							-
14H15-	16.0	1500	6.6	2.50	M_0							17.3
					M_N							16.0
					$M_{0,max}$							35.3
					M_{max}							35.3
					η_{eto}							-
14H32-	14.0	3225	11.9	4.70	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					η_{eto}							
14L15-	23.0	1500	9.7	3.60	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					η_{eto}							
14L32-	17.2	3225	15.0	5.80	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					η_{eto}							
14P14-	30.0	1350	10.8	4.20	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					η_{eto}							

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC					
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N	2.80	5.9	1950	13.5	12L20-
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$					
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}					
15.0	15.0							M_0					
13.5	13.5							M_N					
40.8	41.9							$M_{0,max}$	4.70	10.2	4050	11.0	12L41-
40.8	41.9							M_{max}					
-	-							n_{eto}					
14.0	15.0	15.0	15.0	15.0				M_0					
10.2	11.0	11.0	11.0	11.0				M_N					
22.2	30.4	35.5	35.5	35.5				$M_{0,max}$	1.45	4.5	1500	9.2	14D15-
22.2	30.4	49.6	49.6	49.6				M_{max}					
-	-	-	-	-				n_{eto}					
11.0	11.0							M_0					
9.2	9.2							M_N					
28.3	29.0							$M_{0,max}$	2.80	7.5	3600	7.5	14D36-
28.3	29.0							M_{max}					
-	-							n_{eto}					
11.0	11.0	11.0	11.0					M_0					
7.5	7.5	7.5	7.5					M_N					
21.0	21.0							$M_{0,max}$	2.50	6.6	1500	16.0	14H15-
16.0	16.0							M_N					
42.8	43.9							$M_{0,max}$					
42.8	43.9							M_{max}					
-	-							n_{eto}					
12.9	16.2	21.0	21.0	21.0				M_0	4.70	11.9	3225	14.0	14H32-
11.2	14.0	14.0	14.0	14.0				M_N					
23.2	31.7	37.1	37.1	37.1				$M_{0,max}$					
23.2	31.7	51.9	51.9	51.9				M_{max}					
-	-	-	-	-				n_{eto}					
27.4	28.0	28.0	28.0					M_0	3.60	9.7	1500	23.0	14L15-
22.5	23.0	23.0	23.0					M_N					
43.8	52.9	52.9	52.9					$M_{0,max}$					
43.8	60.0	73.8	73.8					M_{max}					
-	-	-	-					n_{eto}					
	15.2	27.4	27.4	28.0	28.0	28.0		M_0	5.80	15.0	3225	17.2	14L32-
	14.9	17.2	17.2	17.2	17.2	17.2		M_N					
	31.3	39.7	52.9	52.9	52.9	52.9		$M_{0,max}$					
	31.3	57.6	73.9	73.9	73.9	73.9		M_{max}					
	-	-	-	-	-	-		n_{eto}					
32.5	37.0	37.0	37.0	37.0				M_0	4.20	10.8	1350	30.0	14P14-
26.4	30.0	30.0	30.0	30.0				M_N					
51.2	70.0	80.0	80.0	80.0				$M_{0,max}$					
51.2	70.0	105.1	105.1	105.1				M_{max}					
-	-	-	-	-				n_{eto}					

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.8	14.6
14P32-	21.0	3225	15.6	7.10	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
19F14-	27.0	1425	8.6	4.00	M_0							23.6
					M_N							22.9
					$M_{0,max}$							45.9
					M_{max}							45.9
					n_{eto}							-
19F30-	21.0	3000	14.0	6.60	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
19J14-	40.0	1425	12.3	6.00	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
19J30-	29.0	3000	18.5	9.10	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
19P14-	51.0	1350	14.3	7.20	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
19P30-	32.0	3000	19.0	10.00	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC						
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N		P_N	I_N	n_N	M_N	MCS
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$						
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}						
	19.8	35.8	35.8	37.0	37.0	37.0		M_0	7.10	15.6	3225	21.0	14P32-	
	17.5	21.0	21.0	21.0	21.0	21.0		M_N						
	36.5	46.3	61.8	61.8	61.8	61.8		$M_{0,max}$						
	36.5	67.3	86.4	86.4	86.4	86.4		M_{max}						
	-	-	-	-	-	-		n_{eto}						
32.0	32.0	32.0	32.0					M_0	4.00	8.6	1425	27.0	19F14-	
27.0	27.0	27.0	27.0					M_N						
56.7	68.3	68.3	68.3					$M_{0,max}$						
56.7	77.6	86.0	86.0					M_{max}						
-	-	-	-					n_{eto}						
	21.0	32.0	32.0	32.0				M_0	6.60	14.0	3000	21.0	19F30-	
	19.5	21.0	21.0	21.0				M_N						
	47.2	47.2	47.2	47.2				$M_{0,max}$						
	38.9	68.3	68.3	68.3				M_{max}						
	-	-	-	-				n_{eto}						
	43.6	51.0	51.0	51.0				M_0	6.00	12.3	1425	40.0	19J14-	
	40.0	40.0	40.0	40.0				M_N						
	81.1	96.0	96.0	96.0				$M_{0,max}$						
	81.1	129.0	129.0	129.0				M_{max}						
	-	-	-	-				n_{eto}						
			39.3	51.0	51.0	51.0	51.0	M_0	9.10	18.5	3000	29.0	19J30-	
			29.0	29.0	29.0	29.0	29.0	M_N						
			73.6	79.5	79.5	79.5	79.5	$M_{0,max}$						
			110.4	127.6	127.6	127.6	127.6	M_{max}						
			-	-	-	-	-	n_{eto}						
	47.5	64.0	64.0	64.0				M_0	7.20	14.3	1350	51.0	19P14-	
	46.4	51.0	51.0	51.0				M_N						
	92.7	106.7	106.7	106.7				$M_{0,max}$						
	92.7	155.5	155.5	155.5				M_{max}						
	-	-	-	-				n_{eto}						
			43.1	58.7	64.0	64.0	64.0	M_0	10.00	19.0	3000	32.0	19P30-	
			32.0	32.0	32.0	32.0	32.0	M_N						
			79.2	87.6	87.6	87.6	87.6	$M_{0,max}$						
			118.6	144.3	144.3	144.3	144.3	M_{max}						
			-	-	-	-	-	n_{eto}						

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034				
					I_N	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0				
					$I_{0,max}$	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5				
MCS	M_N	n_N	I_N	P_N	I_{max}	6.4	7.8	11.8	14.6	19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0				
12D17-	7.0	1650	3.0	1.20	M_0	7.5	7.5	7.5	7.5												
					M_N	7.0	7.0	7.0	7.0												
					$M_{0,max}$	12.6	15.3	17.7	17.7												
					M_{max}	12.6	15.3	17.7	17.7												
					η_{eto}	-	-	-	-												
12D35-	6.0	3525	5.6	2.20	M_0		4.6	7.5	7.5	7.5	7.5										
					M_N		3.7	6.0	6.0	6.0	6.0										
					$M_{0,max}$		7.8	11.4	14.0	16.9	17.3										
					M_{max}		7.8	11.4	14.0	16.9	17.3										
					η_{eto}		-	-	-	-	-										
12H14-	12.0	1350	4.1	1.70	M_0	8.9	10.9	12.8	12.8	12.8	12.8										
					M_N	8.5	10.3	12.0	12.0	12.0	12.0										
					$M_{0,max}$	16.4	20.0	29.0	29.0	28.3	29.0										
					M_{max}	16.4	20.0	29.0	29.0	28.3	29.0										
					η_{eto}	-	-	-	-	-	-										
12H34-	10.5	3375	7.5	3.70	M_0				10.2	12.8	12.8										
					M_N				10.0	10.5	10.5										
					$M_{0,max}$				18.8	23.5	24.1										
					M_{max}				18.8	23.5	24.1										
					η_{eto}				-	-	-										
12L17-	17.0	1650	6.7	2.90	M_0				18.5	19.0	19.0										
					M_N				17.0	17.0	17.0										
					$M_{0,max}$				33.9	40.8	41.9										
					M_{max}				33.9	40.8	41.9										
					η_{eto}				-	-	-										
12L39-	14.0	3900	11.7	5.70	M_0					17.2	17.2	19.0	19.0	19.0							
					M_N					14.0	14.0	14.0	14.0	14.0							
					$M_{0,max}$					22.2	30.4	35.5	35.5	35.5							
					M_{max}					22.2	30.4	49.6	49.6	49.6							
					η_{eto}					-	-	-	-	-							
14D14-	12.0	1350	5.4	1.70	M_0		8.5	12.5	12.5	12.5	12.5										
					M_N		8.0	12.0	12.0	12.0	12.0										
					$M_{0,max}$		16.0	22.7	28.1	28.3	29.0										
					M_{max}		16.0	22.7	28.1	28.3	29.0										
					η_{eto}		-	-	-	-	-										
14D30-	10.5	3000	9.7	3.30	M_0					7.7	12.2	12.5	12.5	12.5							
					M_N					7.0	9.8	10.0	10.0	10.0							
					$M_{0,max}$					15.2	18.5	25.3	29.0	29.0							
					M_{max}					15.2	18.5	22.2	22.2	22.2							
					η_{eto}					-	-	-	-	-							
14H12-	23.5	1200	8.3	3.00	M_0					18.0	25.5	25.5									
					M_N					17.9	23.5	23.5									
					$M_{0,max}$					35.3	42.8	43.9									
					M_{max}					35.3	42.8	43.9									
					η_{eto}					-	-	-									

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034				
					I_N	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0				
					$I_{0,max}$	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5				
MCS	M_N	n_N	I_N	P_N	I_{max}	6.4	7.8	11.8	14.6	19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0				
14H28-	20.5	2775	15.0	6.00	M_0						16.2	25.5	25.5	25.5							
					M_N					16.1	20.5	20.5	20.5								
					$M_{0,max}$							31.7	37.1	37.1	37.1						
					M_{max}								31.7	51.9	51.9	51.9					
					η_{eto}									-	-	-	-				
14L14-	30.5	1350	11.8	4.30	M_0					26.9	33.4	34.5	34.5								
					M_N					24.6	30.5	30.5	30.5								
					$M_{0,max}$							43.8	52.9	52.9	52.9						
					M_{max}								43.8	60.0	73.8	73.8					
					η_{eto}								-	-	-	-					
14L30-	25.5	3000	20.8	8.00	M_0								27.4	34.5	34.5	34.5					
					M_N								25.5	25.5	25.5	25.5					
					$M_{0,max}$									52.9	52.9	52.9	52.9				
					M_{max}										73.9	73.9	73.9	73.9			
					η_{eto}										-	-	-	-			
14P11-	42.0	1050	13.4	4.60	M_0						38.9	43.5	43.5	43.5							
					M_N						38.8	42.0	42.0	42.0							
					$M_{0,max}$								70.0	80.0	80.0	80.0					
					M_{max}									70.0	105.1	105.1	105.1				
					η_{eto}									-	-	-	-				
14P26-	33.0	2625	21.9	9.10	M_0									35.8	43.5	43.5	43.5				
					M_N									33.0	33.0	33.0	33.0				
					$M_{0,max}$										66.0	86.4	86.4	86.4			
					M_{max}											86.4	86.4	86.4	86.4		
					η_{eto}											-	-	-	-		
19F12-	38.0	1200	11.3	4.80	M_0			23.6	34.9	41.5	41.5	41.5									
					M_N				22.9	31.9	38.0	38.0	38.0								
					$M_{0,max}$					45.9	56.7	68.3	68.3	68.3							
					M_{max}						45.9	56.7	77.6	86.0	86.0						
					η_{eto}						-	-	-	-	-						
19F29-	32.5	2850	20.1	9.70	M_0									39.9	41.5						
					M_N										32.5	32.5					
					$M_{0,max}$											47.2	47.2				
					M_{max}												68.3	68.3			
					η_{eto}												-	-			
19J12-	62.5	1200	18.3	7.90	M_0						43.6		70.5	70.5							
					M_N							43.4		62.5	62.5						
					$M_{0,max}$								81.1	96.0	96.0						
					M_{max}									81.1	129.0	129.0					
					η_{eto}									-	-	-					
19J29-	50.5	2850	31.0	15.10	M_0									55.5	70.5	70.5	70.5				
					M_N									50.5	50.5	50.5	50.5				
					$M_{0,max}$										87.6	87.6	87.6	87.6			
					M_{max}											127.6	127.6	127.6	127.6		
					η_{eto}											-	-	-	-		

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	
					I_N	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	
					$I_{0,max}$	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	
MCS	M_N	n_N	I_N	P_N	I_{max}	6.4	7.8	11.8	14.6	19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	
19P12-	72.0	1200	21.3	9.00	M_0						47.5		86.0	86.0				
					M_N						46.4		72.0	72.0				
					$M_{0,max}$						92.7		106.7	106.7				
					M_{max}						92.7		155.5	155.5				
					η_{eto}									-		-	-	
19P29-	53.0	2850	29.5	15.80	M_0									58.7	86.0	86.0	86.0	
					M_N									53.0	53.0	53.0	53.0	
					$M_{0,max}$									87.6	87.6	87.6	87.6	
					M_{max}									144.3	144.3	144.3	144.3	
					η_{eto}											-	-	-

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
06C41-	0.6	4050	1.3	0.25	M_0	0.8					
					M_N	0.6					
					$M_{0,max}$	1.2					
					M_{max}	1.9					
					n_{eto}	2747					
06C60-	0.5	6000	2.4	0.31	M_0	0.6	0.8				
					M_N	0.4	0.5				
					$M_{0,max}$	0.6	1.2				
					M_{max}	1.0	1.9				
					n_{eto}	7000	6814				
06F41-	1.2	4050	1.5	0.51	M_0	1.5					
					M_N	1.2					
					$M_{0,max}$	2.0					
					M_{max}	3.6					
					n_{eto}	1902					
06F60-	0.9	6000	2.5	0.57	M_0	1.0	1.5				
					M_N	0.7	0.9				
					$M_{0,max}$	1.0	2.0				
					M_{max}	1.8	3.7				
					n_{eto}	7000	4602				
06I41-	1.5	4050	1.6	0.64	M_0	2.0	2.0				
					M_N	1.5	1.5				
					$M_{0,max}$	2.6	5.0				
					M_{max}	4.4	6.2				
					n_{eto}	1898	1384				
06I60-	1.2	6000	2.9	0.75	M_0	1.2	2.0	2.0			
					M_N	0.8	1.2	1.2			
					$M_{0,max}$	1.3	2.6	5.2			
					M_{max}	2.2	4.7	6.2			
					n_{eto}	6407	4200	3157			
09D41-	2.3	4050	2.3	1.00	M_0		3.3	3.3			
					M_N		2.3	2.3			
					$M_{0,max}$		5.0	8.8			
					M_{max}		8.0	9.4			
					n_{eto}		2361	2008			
09D60-	1.8	6000	3.8	1.10	M_0		2.5	3.3			
					M_N		1.8	1.8			
					$M_{0,max}$		2.5	4.9			
					M_{max}		4.4	8.0			
					n_{eto}		7000	5217			
09F38-	3.1	3750	2.5	1.20	M_0		4.2	4.2			
					M_N		3.1	3.1			
					$M_{0,max}$		6.2	10.8			
					M_{max}		9.8	14.9			
					n_{eto}		2589	1737			

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
09F60-	2.4	6000	4.5	1.50	M_0		2.8	4.2	4.2		
					M_N		2.1	2.4	2.4		
					$M_{0,max}$		3.2	6.1	10.8		
					M_{max}		5.4	9.8	14.9		
					n_{eto}		7000	5906	3715		
09H41-	3.8	4050	3.4	1.60	M_0		5.2	5.5			
					M_N		3.8	3.8			
					$M_{0,max}$		5.9	11.1			
					M_{max}		9.9	17.5			
					n_{eto}		3675	2231			
09H60-	3.0	6000	6.0	1.90	M_0			5.2	5.5	5.5	
					M_N			3.0	3.0	3.0	
					$M_{0,max}$			5.9	11.0	15.5	
					M_{max}			9.9	17.5	20.4	
					n_{eto}			7000	5061	4375	
09L41-	4.5	4050	4.2	1.90	M_0		4.8	7.5	7.5		
					M_N		4.3	4.5	4.5		
					$M_{0,max}$		5.2	10.3	19.5		
					M_{max}		9.1	17.4	31.9		
					n_{eto}		4450	3188	1878		
09L51-	3.6	5100	6.9	1.90	M_0			4.8	7.5	7.5	7.5
					M_N			3.6	3.6	3.6	3.6
					$M_{0,max}$			5.2	10.3	15.1	19.6
					M_{max}			9.1	17.5	25.1	31.9
					n_{eto}			7000	7000	5647	4076
12D20-	5.5	1950	2.6	1.10	M_0	4.7	6.4	6.4			
					M_N	4.2	5.5	5.5			
					$M_{0,max}$	4.6	9.1	17.0			
					M_{max}	8.0	15.3	17.7			
					n_{eto}	1730	1089	919			
12D41-	4.3	4050	4.5	1.80	M_0		4.7	6.4			
					M_N		3.8	4.3			
					$M_{0,max}$		4.6	8.8			
					M_{max}		7.8	14.7			
					n_{eto}		3902	2433			
12H15-	10.0	1500	3.8	1.60	M_0		11.2	11.4			
					M_N		10.0	10.0			
					$M_{0,max}$		11.9	22.6			
					M_{max}		20.1	29.0			
					n_{eto}		1220	918			
12H35-	7.5	3525	5.7	2.80	M_0		5.6	11.2	11.4		
					M_N		5.3	7.5	7.5		
					$M_{0,max}$		6.0	11.8	22.5		
					M_{max}		10.4	20.1	29.0		
					n_{eto}		3850	2838	2092		

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
12L20-	13.5	1950	5.9	2.80	M_0			15.0	15.0		
					M_N			13.5	13.5		
					$M_{0,max}$			21.4	39.4		
					M_{max}			35.5	56.4		
					n_{eto}			1324	863		
12L41-	11.0	4050	10.2	4.70	M_0			9.7	15.0	15.0	15.0
					M_N			8.6	11.0	11.0	11.0
					$M_{0,max}$			10.8	21.3	30.8	39.5
					M_{max}			19.0	35.5	49.6	56.4
					n_{eto}			4450	3013	2236	1907
14D15-	9.2	1500	4.5	1.45	M_0		8.8	11.0			
					M_N		8.2	9.2			
					$M_{0,max}$		9.6	17.9			
					M_{max}		15.9	28.3			
					n_{eto}		1141	689			
14D36-	7.5	3600	7.5	2.80	M_0			8.8	11.0		
					M_N			7.5	7.5		
					$M_{0,max}$			9.5	17.8		
					M_{max}			15.9	28.3		
					n_{eto}			2496	1614		
14H15-	16.0	1500	6.6	2.50	M_0			19.8	21.0		
					M_N			16.0	16.0		
					$M_{0,max}$			22.3	41.2		
					M_{max}			37.1	54.8		
					n_{eto}			920	667		
14H32-	14.0	3225	11.9	4.70	M_0				15.8	21.0	21.0
					M_N				14.0	14.0	14.0
					$M_{0,max}$				22.2	32.1	41.3
					M_{max}				37.1	51.9	54.8
					n_{eto}				1953	1471	1409
14L15-	23.0	1500	9.7	3.60	M_0			18.7	28.0	28.0	
					M_N			19.0	23.0	23.0	
					$M_{0,max}$			21.9	42.1	59.9	
					M_{max}			37.6	68.5	77.1	
					n_{eto}			1284	828	767	
14L32-	17.2	3225	15.0	5.80	M_0				14.8	19.8	23.3
					M_N				14.6	17.2	17.2
					$M_{0,max}$				21.8	32.4	42.2
					M_{max}				37.6	53.9	68.5
					n_{eto}				2801	2096	1757
14P14-	30.0	1350	10.8	4.20	M_0				37.0	37.0	37.0
					M_N				30.0	30.0	30.0
					$M_{0,max}$				49.1	70.0	88.4
					M_{max}				80.0	105.1	105.1
					n_{eto}				710	573	573

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
14P32-	21.0	3225	15.6	7.10	M_0				19.3	25.9	30.5
					M_N				17.1	21.0	21.0
					$M_{0,max}$				25.4	37.9	49.3
					M_{max}				43.9	63.0	80.0
					n_{eto}				2469	1829	1495
19F14-	27.0	1425	8.6	4.00	M_0			25.9	32.0		
					M_N			25.1	27.0		
					$M_{0,max}$			28.6	54.6		
					M_{max}			48.9	86.0		
					n_{eto}			1204	746		
19F30-	21.0	3000	14.0	6.60	M_0				20.5	27.5	32.0
					M_N				19.0	21.0	21.0
					$M_{0,max}$				27.2	40.5	53.0
					M_{max}				47.2	68.3	86.0
					n_{eto}				2774	2033	1653
19J14-	40.0	1425	12.3	6.00	M_0				42.6	51.0	
					M_N				40.0	40.0	
					$M_{0,max}$				58.9	82.8	
					M_{max}				96.0	129.0	
					n_{eto}				1063	839	
19J30-	29.0	3000	18.5	9.10	M_0					28.4	33.4
					M_N					26.6	29.0
					$M_{0,max}$					42.6	56.9
					M_{max}					73.8	96.0
					n_{eto}					2850	2323
19P14-	51.0	1350	14.3	7.20	M_0				46.4	62.2	64.0
					M_N				45.3	51.0	51.0
					$M_{0,max}$				64.6	91.5	120.1
					M_{max}				106.7	155.5	190.0
					n_{eto}				1227	996	870
19P30-	32.0	3000	19.0	10.00	M_0					31.2	36.7
					M_N					28.6	32.0
					$M_{0,max}$					45.8	61.1
					M_{max}					81.2	106.7
					n_{eto}					2938	2715

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Non-ventilated motors

- The data applies to a mains connection voltage of 3x230V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
06C41L	0.6	4050	2.6	0.25	M_0	0.6	0.8				
					M_N	0.5	0.6				
					$M_{0,max}$	0.6	1.1				
					M_{max}	1.0	1.9				
					n_{eto}	6298	2835				
06C60L	0.5	6000	4.0	0.31	M_0		0.7	0.8			
					M_N		0.5	0.5			
					$M_{0,max}$		0.7	1.3			
					M_{max}		1.2	2.2			
					n_{eto}		7000	1149			
06F41L	1.2	4050	2.9	0.51	M_0	1.0	1.5	1.5			
					M_N	0.8	1.2	1.2			
					$M_{0,max}$	1.2	2.1	3.9			
					M_{max}	1.9	3.5	4.4			
					n_{eto}	3838	2118	2831			
06F60L	0.9	6000	3.8	0.57	M_0		1.5	1.5			
					M_N		0.9	0.9			
					$M_{0,max}$		1.5	2.9			
					M_{max}		2.6	4.3			
					n_{eto}		6138	3182			
06I41L	1.5	4050	3.2	0.64	M_0	1.3	2.0	2.0			
					M_N	1.0	1.5	1.5			
					$M_{0,max}$	1.4	2.8	5.0			
					M_{max}	2.4	4.4	6.2			
					n_{eto}	3549	1947	2831			
06I60L	1.2	6000	3.8	0.75	M_0		1.9	2.0			
					M_N		1.2	1.2			
					$M_{0,max}$		2.1	4.1			
					M_{max}		3.6	6.2			
					n_{eto}		3417	1149			
09D41L	2.3	4050	4.6	1.00	M_0		2.5	3.3	3.3		
					M_N		2.0	2.3	2.3		
					$M_{0,max}$		2.5	4.9	8.8		
					M_{max}		4.4	8.0	9.5		
					n_{eto}		4091	2547	2170		
09D60L	1.8	6000	7.0	1.10	M_0			2.6	3.3	3.3	
					M_N			1.8	1.8	1.8	
					$M_{0,max}$			2.6	5.0	7.1	
					M_{max}			4.5	8.1	9.5	
					n_{eto}			7000	5373	4626	
09F38L	3.1	3750	5.0	1.20	M_0			4.2	4.2		
					M_N			3.1	3.1		
					$M_{0,max}$			6.1	10.8		
					M_{max}			9.8	15.0		
					n_{eto}			1149	1951		

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Non-ventilated motors

- The data applies to a mains connection voltage of 3x230V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
09F60L	2.4	6000	7.9	1.50	M_0			3.2	4.2	4.2	4.2
					M_N			2.4	2.4	2.4	2.4
					$M_{0,max}$			3.6	6.8	9.6	11.9
					M_{max}			6.1	10.9	14.3	15.0
					η_{eto}			6985	3448	2612	2397
09H41L	3.8	4050	6.8	1.60	M_0			5.2	5.5	5.5	
					M_N			3.8	3.8	3.8	
					$M_{0,max}$			5.9	11.0	15.3	
					M_{max}			9.9	17.2	20.0	
					η_{eto}			1149	2138	1852	
09H60L	3.0	6000	8.0	1.90	M_0			3.7	5.5	5.5	5.5
					M_N			3.0	3.0	3.0	3.0
					$M_{0,max}$			4.1	8.0	11.5	14.5
					M_{max}			7.2	13.2	17.9	20.0
					η_{eto}			1149	4081	2984	2695
09L41L	4.5	4050	8.4	1.90	M_0			4.8	7.5	7.5	7.5
					M_N			4.3	4.5	4.5	4.5
					$M_{0,max}$			5.2	10.3	15.1	19.6
					M_{max}			9.1	17.5	25.1	31.9
					η_{eto}			4562	3243	2497	1909
12D20L	5.5	1950	5.2	1.10	M_0		4.7	6.4			
					M_N		4.2	5.5			
					$M_{0,max}$		4.6	9.0			
					M_{max}		8.0	14.9			
					η_{eto}		1878	1181			
12D41L	4.3	4050	8.8	1.80	M_0			4.8	6.4	6.4	
					M_N			3.9	4.3	4.3	
					$M_{0,max}$			4.6	9.2	13.3	
					M_{max}			8.1	15.2	17.9	
					η_{eto}			4102	2535	2187	
12H15L	10.0	1500	7.6	1.60	M_0			11.2	11.4		
					M_N			10.0	10.0		
					$M_{0,max}$			11.8	22.5		
					M_{max}			20.1	29.0		
					η_{eto}			1098	827		
12H30L	8.0	3000	10.5	2.50	M_0			6.8	10.7	11.4	
					M_N			6.1	8.0	8.0	
					$M_{0,max}$			7.2	14.3	20.9	
					M_{max}			12.7	24.3	29.0	
					η_{eto}			2831	1849	1591	
12L20L	13.5	1950	11.8	2.80	M_0				15.0	15.0	15.0
					M_N				13.5	13.5	13.5
					$M_{0,max}$				21.3	30.7	39.4
					M_{max}				35.4	49.3	56.0
					η_{eto}				1307	1004	866

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
12D17-	7.0	1650	3.0	1.20	M_0	4.7	7.5	7.5			
					M_N	4.2	7.0	7.0			
					$M_{0,max}$	4.6	9.1	17.0			
					M_{max}	8.0	15.3	17.7			
					n_{eto}	1730	1089	919			
12D35-	6.0	3525	5.6	2.20	M_0		4.7	7.5			
					M_N		3.8	6.0			
					$M_{0,max}$		4.6	8.8			
					M_{max}		7.8	14.7			
					n_{eto}		3902	2433			
12H14-	12.0	1350	4.1	1.70	M_0		11.2	12.8			
					M_N		10.6	12.0			
					$M_{0,max}$		11.9	22.6			
					M_{max}		20.1	29.0			
					n_{eto}		1220	918			
12H34-	10.5	3375	7.5	3.70	M_0		5.6	11.2	12.8		
					M_N		5.3	10.0	7.5		
					$M_{0,max}$		6.0	11.8	22.5		
					M_{max}		10.4	20.1	29.0		
					n_{eto}		3850	2838	2092		
12L17-	17.0	1650	6.7	2.90	M_0			19.0	19.0		
					M_N			17.0	17.0		
					$M_{0,max}$			21.4	39.4		
					M_{max}			35.5	56.4		
					n_{eto}			1324	863		
12L39-	14.0	3900	11.7	5.70	M_0			9.7	16.7	19.0	19.0
					M_N			8.6	14.0	14.0	14.0
					$M_{0,max}$			10.8	21.3	30.8	39.5
					M_{max}			19.0	35.5	49.6	56.4
					n_{eto}			4450	3013	2236	1907
14D14-	12.0	1350	5.4	1.70	M_0		8.8	12.5			
					M_N		8.2	12.0			
					$M_{0,max}$		9.6	17.9			
					M_{max}		15.9	28.3			
					n_{eto}		1141	689			
14D30-	10.5	3000	9.7	3.30	M_0			8.8	11.4		
					M_N			8.6	9.7		
					$M_{0,max}$			9.5	17.8		
					M_{max}			15.9	28.3		
					n_{eto}			2496	1614		
14H12-	23.5	1200	8.3	3.00	M_0			19.8	25.5		
					M_N			19.6	23.5		
					$M_{0,max}$			22.3	41.2		
					M_{max}			37.1	54.8		
					n_{eto}			920	667		

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
14H28-	20.5	2775	15.0	6.00	M_0				15.8	23.5	25.5
					M_N				15.6	20.5	20.5
					$M_{0,max}$				22.2	32.1	41.3
					M_{max}				37.1	51.9	54.8
					η_{eto}				1953	1471	1409
14L14-	30.5	1350	11.8	4.30	M_0			18.7	32.7	34.5	
					M_N			19.0	30.5	30.5	
					$M_{0,max}$			21.9	42.1	59.9	
					M_{max}			37.6	68.5	77.1	
					η_{eto}			1284	828	767	
14L30-	25.5	3000	20.8	8.00	M_0					19.8	23.3
					M_N					19.7	23.3
					$M_{0,max}$					32.4	42.2
					M_{max}					53.9	68.5
					η_{eto}					2096	1757
14P11-	42.0	1050	13.4	4.60	M_0				39.1	43.5	43.5
					M_N				38.9	42.0	42.0
					$M_{0,max}$				49.1	70.0	88.4
					M_{max}				80.0	105.1	105.1
					η_{eto}				710	573	573
14P26-	33.0	2625	21.9	9.10	M_0					25.9	30.5
					M_N					25.6	30.1
					$M_{0,max}$					37.9	49.3
					M_{max}					63.0	80.0
					η_{eto}					1829	1495
19F12-	38.0	1200	11.3	4.80	M_0			25.9	41.5		
					M_N			25.1	38.0		
					$M_{0,max}$			28.6	54.6		
					M_{max}			48.9	86.0		
					η_{eto}			1204	746		
19F29-	32.5	2850	20.1	9.70	M_0					27.5	33.9
					M_N					27.4	32.5
					$M_{0,max}$					40.5	53.0
					M_{max}					68.3	86.0
					η_{eto}					2033	1653
19J12-	62.5	1200	18.3	7.90	M_0					59.0	69.4
					M_N					58.1	62.5
					$M_{0,max}$					82.8	82.8
					M_{max}					129.0	129.0
					η_{eto}					839	839
19J29-	50.5	2850	31.0	15.10	M_0						34.3
					M_N						32.6
					$M_{0,max}$						56.9
					M_{max}						96.0
					η_{eto}						2323

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
19P12-	72.0	1200	21.3	9.00	M_0					62.2	76.8
					M_N					57.5	67.6
					$M_{0,max}$					91.5	120.1
					M_{max}					155.5	190.0
					n_{eto}					996	870
19P29-	53.0	2850	29.5	15.80	M_0						36.7
					M_N						35.9
					$M_{0,max}$						61.1
					M_{max}						106.7
					n_{eto}						2715

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321- E□	9322- E□	9323- E□	9324- E□	9325- E□	9326- E□	9327- E□	9328- E□	9329- E□
					I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
06C41-	0.6	4050	1.3	0.25	M_0	0.8	0.8	0.8						
					M_N	0.6	0.6	0.6						
					$M_{0,max}$	1.2	1.8	2.4						
					M_{max}	1.2	1.8	2.4						
					n_{eto}	4635	2871	2019						
06C60-	0.5	6000	2.4	0.31	M_0		0.8	0.8	0.8					
					M_N		0.5	0.5	0.5					
					$M_{0,max}$		1.0	1.5	2.4					
					M_{max}		1.0	1.5	2.4					
					n_{eto}		7000	7000	5368					
06F41-	1.2	4050	1.5	0.51	M_0	1.5	1.5	1.5						
					M_N	1.2	1.2	1.2						
					$M_{0,max}$	2.0	3.4	4.4						
					M_{max}	2.0	3.4	4.4						
					n_{eto}	2819	1973	1562						
06F60-	0.9	6000	2.5	0.57	M_0		1.3	1.5	1.5					
					M_N		0.9	0.9	0.9					
					$M_{0,max}$		1.7	3.0	4.4					
					M_{max}		1.7	3.0	4.4					
					n_{eto}		7000	5714	3773					
06I41-	1.5	4050	1.6	0.64	M_0	1.8	2.0	2.0						
					M_N	1.4	1.5	1.5						
					$M_{0,max}$	2.6	4.2	6.2						
					M_{max}	2.6	4.2	6.2						
					n_{eto}	2994	1980	1384						
06I60-	1.2	6000	2.9	0.75	M_0		1.5	2.0	2.0					
					M_N		1.0	1.2	1.2					
					$M_{0,max}$		2.1	3.3	5.7					
					M_{max}		2.1	3.3	5.7					
					n_{eto}		7000	5486	3414					
09D41-	2.3	4050	2.3	1.00	M_0		3.1	3.3	3.3					
					M_N		2.3	2.3	2.3					
					$M_{0,max}$		4.2	6.2	9.4					
					M_{max}		4.2	6.2	9.4					
					n_{eto}		4895	2937	2008					
09D60-	1.8	6000	3.8	1.10	M_0			2.4	3.3	3.3				
					M_N			1.8	1.8	1.8				
					$M_{0,max}$			3.2	5.6	9.3				
					M_{max}			3.2	5.6	9.3				
					n_{eto}			7000	7000	4492				
09F38-	3.1	3750	2.5	1.20	M_0		3.5	4.2	4.2					
					M_N		3.1	3.1	3.1					
					$M_{0,max}$		5.2	7.7	12.0					
					M_{max}		5.2	7.7	12.0					
					n_{eto}		4000	3250	2173					

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321- E□	9322- E□	9323- E□	9324- E□	9325- E□	9326- E□	9327- E□	9328- E□	9329- E□
					I _N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					I _{0,max}	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M _N	n _N	I _N	P _N	I _{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
09F60-	2.4	6000	4.5	1.50	M ₀				4.2	4.2				
					M _N				2.4	2.4				
					M _{0,max}				6.9	11.4				
					M _{max}				6.9	11.4				
					n _{eto}				7000	5035				
09H41-	3.8	4050	3.4	1.60	M ₀			5.0	5.5	5.5				
					M _N			3.8	3.8	3.8				
					M _{0,max}			7.5	12.5	20.1				
					M _{max}			7.5	12.5	20.1				
					n _{eto}			4250	2977	1988				
09H60-	3.0	6000	6.0	1.90	M ₀				4.5	5.5				
					M _N				3.0	3.0				
					M _{0,max}				6.7	11.7				
					M _{max}				6.7	11.7				
					n _{eto}				7000	7000				
09L41-	4.5	4050	4.2	1.90	M ₀			4.7	7.5	7.5				
					M _N			4.2	4.5	4.5				
					M _{0,max}			6.7	11.7	20.8				
					M _{max}			6.7	11.7	20.8				
					n _{eto}			4450	4154	2796				
09L51-	3.6	5100	6.9	1.90	M ₀				4.2	7.5	7.5			
					M _N				3.6	3.6	3.6			
					M _{0,max}				6.0	11.1	13.2			
					M _{max}				6.0	11.1	19.1			
					n _{eto}				7000	7000	7000			
12D20-	5.5	1950	2.6	1.10	M ₀		5.9	6.4	6.4					
					M _N		5.3	5.5	5.5					
					M _{0,max}		7.6	11.6	17.7					
					M _{max}		7.6	11.6	17.7					
					n _{eto}		1790	1358	919					
12D41-	4.3	4050	4.5	1.80	M ₀			4.6	6.4	6.4				
					M _N			3.7	4.3	4.3				
					M _{0,max}			5.9	10.1	17.3				
					M _{max}			5.9	10.1	17.3				
					n _{eto}			4344	3275	2116				
12H15-	10.0	1500	3.8	1.60	M ₀			10.9	11.4	11.4				
					M _N			10.0	10.0	10.0				
					M _{0,max}			15.1	25.8	29.0				
					M _{max}			15.1	25.8	29.0				
					n _{eto}			1676	1013	918				
12H35-	7.5	3525	5.7	2.80	M ₀				9.8	11.4				
					M _N				7.5	7.5				
					M _{0,max}				13.5	24.1				
					M _{max}				13.5	24.1				
					n _{eto}				3618	2447				

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321- E□	9322- E□	9323- E□	9324- E□	9325- E□	9326- E□	9327- E□	9328- E□	9329- E□
					I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
12L20-	13.5	1950	5.9	2.80	M_0				15.0	15.0				
					M_N				13.5	13.5				
					$M_{0,max}$				24.4	41.9				
					M_{max}				24.4	41.9				
					n_{eto}				1718	1158				
12L41-	11.0	4050	10.2	4.70	M_0					15.0	15.0	15.0		
					M_N					11.0	11.0	11.0		
					$M_{0,max}$					22.8	27.0	35.5		
					M_{max}					22.8	38.5	49.6		
					n_{eto}					4287	2799	2236		
14D15-	9.2	1500	4.5	1.45	M_0		8.5	11.0	11.0					
					M_N		8.0	9.2	9.2					
					$M_{0,max}$		12.1	20.2	29.0					
					M_{max}		12.1	20.2	29.0					
					n_{eto}		1437	928	676					
14D36-	7.5	3600	7.5	2.80	M_0			7.7	11.0	11.0				
					M_N			7.0	7.5	7.5				
					$M_{0,max}$			10.9	19.0	22.2				
					M_{max}			10.9	19.0	29.0				
					n_{eto}			3479	2159	1593				
14H15-	16.0	1500	6.6	2.50	M_0			17.3	21.0					
					M_N			16.0	16.0					
					$M_{0,max}$			25.4	43.9					
					M_{max}			25.4	43.9					
					n_{eto}			1247	800					
14H32-	14.0	3225	11.9	4.70	M_0				16.2	21.0	21.0			
					M_N				14.0	14.0	14.0			
					$M_{0,max}$				23.8	28.2	37.1			
					M_{max}				23.8	40.2	51.9			
					n_{eto}				2875	1817	1471			
14L15-	23.0	1500	9.7	3.60	M_0				28.0	28.0				
					M_N				23.0	23.0				
					$M_{0,max}$				45.0	52.9				
					M_{max}				45.0	73.8				
					n_{eto}				1126	788				
14L32-	17.2	3225	15.0	5.80	M_0				15.2	27.4	28.0	28.0		
					M_N				14.9	17.2	17.2	17.2		
					$M_{0,max}$				23.5	28.3	37.6	52.9		
					M_{max}				23.5	41.0	53.9	73.9		
					n_{eto}				3953	2608	2096	1672		
14P14-	30.0	1350	10.8	4.20	M_0				37.0	37.0	37.0			
					M_N				30.0	30.0	30.0			
					$M_{0,max}$				52.5	61.8	80.0			
					M_{max}				52.5	86.3	105.1			
					n_{eto}				998	668	573			

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Non-ventilated motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321- E□	9322- E□	9323- E□	9324- E□	9325- E□	9326- E□	9327- E□	9328- E□	9329- E□	
					I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0	
					$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0	
MCS	M_N	n_N	I_N	P_N	I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5	
14P32-	21.0	3225	15.6	7.10	M_0					19.8	35.8	37.0	37.0		
					M_N					17.5	21.0	21.0	21.0		
					$M_{0,max}$					27.4	33.0	43.9	61.8		
					M_{max}					27.4	47.9	63.0	86.4		
					n_{eto}					3300	2299	1829	1404		
19F14-	27.0	1425	8.6	4.00	M_0				22.6	32.0	32.0				
					M_N					22.0	27.0	27.0			
					$M_{0,max}$					33.0	58.2	68.3			
					M_{max}					33.0	58.2	86.0			
					n_{eto}					1459	1056	746			
19F30-	21.0	3000	14.0	6.60	M_0					21.0	32.0	32.0			
					M_N					19.5	21.0	21.0			
					$M_{0,max}$					29.2	35.2	47.2			
					M_{max}					29.2	51.5	68.3			
					n_{eto}					3352	2573	2033			
19J14-	40.0	1425	12.3	6.00	M_0					43.6	51.0	51.0			
					M_N					40.0	40.0	40.0			
					$M_{0,max}$					60.8	72.4	96.0			
					M_{max}					60.8	104.5	129.0			
					n_{eto}					1376	996	839			
19J30-	29.0	3000	18.5	9.10	M_0						39.3	51.0	51.0	51.0	
					M_N							29.0	29.0	29.0	29.0
					$M_{0,max}$							36.8	50.2	72.4	79.5
					M_{max}							55.2	73.8	104.7	127.6
					n_{eto}							3150	2850	2162	1817
19P14-	51.0	1350	14.3	7.20	M_0					47.5	64.0	64.0			
					M_N					46.4	51.0	51.0			
					$M_{0,max}$					69.5	79.6	106.7			
					M_{max}					69.5	116.7	155.5			
					n_{eto}					1400	1187	996			
19P30-	32.0	3000	19.0	10.00	M_0						43.1	58.7	64.0	64.0	
					M_N							32.0	32.0	32.0	32.0
					$M_{0,max}$							39.6	53.9	79.6	87.6
					M_{max}							59.3	81.2	116.9	144.3
					n_{eto}							3000	2938	2638	2298

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
12D17-	7.0	1650	3.0	1.20	M_0	5.9	7.5	7.5					
					M_N	5.3	7.0	7.0					
					$M_{0,max}$	7.6	11.6	17.7					
					M_{max}	7.6	11.6	17.7					
					n_{eto}	1790	1358	919					
12D35-	6.0	3525	5.6	2.20	M_0		4.6	7.5	7.5				
					M_N		3.7	6.0	6.0				
					$M_{0,max}$		5.9	10.1	17.3				
					M_{max}		5.9	10.1	17.3				
					n_{eto}		4344	3275	2116				
12H14-	12.0	1350	4.1	1.70	M_0		10.9	12.8	12.8				
					M_N		10.3	12.0	12.0				
					$M_{0,max}$		15.1	25.8	29.0				
					M_{max}		15.1	25.8	29.0				
					n_{eto}		1676	1013	918				
12H34-	10.5	3375	7.5	3.70	M_0			9.8	12.8				
					M_N			9.6	10.5				
					$M_{0,max}$			13.5	24.1				
					M_{max}			13.5	24.1				
					n_{eto}			3618	2447				
12L17-	17.0	1650	6.7	2.90	M_0			18.5	19.0				
					M_N			17.0	17.0				
					$M_{0,max}$			24.4	41.9				
					M_{max}			24.4	41.9				
					n_{eto}			1718	1158				
12L39-	14.0	3900	11.7	5.70	M_0				17.2	19.0	19.0		
					M_N				14.0	14.0	14.0		
					$M_{0,max}$				22.8	27.0	35.5		
					M_{max}				22.8	38.5	49.6		
					n_{eto}				4287	2799	2236		
14D14-	12.0	1350	5.4	1.70	M_0		8.5	12.5	12.5				
					M_N		8.0	12.0	12.0				
					$M_{0,max}$		12.1	20.2	29.0				
					M_{max}		12.1	20.2	29.0				
					n_{eto}		1437	928	676				
14D30-	10.5	3000	9.7	3.30	M_0			7.7	12.5	12.5			
					M_N			7.0	10.0	10.0			
					$M_{0,max}$			10.9	19.0	22.2			
					M_{max}			10.9	19.0	29.0			
					n_{eto}			3479	2159	1593			
14H12-	23.5	1200	8.3	3.00	M_0			17.3	25.5				
					M_N			17.2	23.5				
					$M_{0,max}$			25.4	43.9				
					M_{max}			25.4	43.9				
					n_{eto}			1247	800				

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
14H28-	20.5	2775	15.0	6.00	M_0				16.2	25.5	25.5		
					M_N				16.1	20.5	20.5		
					$M_{0,max}$				23.8	28.2	37.1		
					M_{max}				23.8	40.2	51.9		
					n_{eto}					2875	1817	1471	
14L14-	30.5	1350	11.8	4.30	M_0				33.4	34.5			
					M_N				30.5	30.5			
					$M_{0,max}$				45.0	52.9			
					M_{max}				45.0	73.8			
					n_{eto}					1126	788		
14L30-	25.5	3000	20.8	8.00	M_0					27.4	34.5	34.5	
					M_N					25.5	25.5	25.5	
					$M_{0,max}$					28.3	37.6	52.9	
					M_{max}					41.0	53.9	73.9	
					n_{eto}						2608	2096	1672
14P11-	42.0	1050	13.4	4.60	M_0				40.1	43.5	43.5		
					M_N				40.0	42.0	42.0		
					$M_{0,max}$				52.5	61.8	80.0		
					M_{max}				52.5	86.3	105.1		
					n_{eto}					998	668	573	
14P26-	33.0	2625	21.9	9.10	M_0					35.8	43.5	43.5	
					M_N					33.0	33.0	33.0	
					$M_{0,max}$					33.0	43.9	61.8	
					M_{max}					47.9	63.0	86.4	
					n_{eto}						2299	1829	1404
19F12-	38.0	1200	11.3	4.80	M_0			22.6	41.5	41.5			
					M_N			22.0	38.0	38.0			
					$M_{0,max}$			33.0	58.2	68.3			
					M_{max}			33.0	58.2	86.0			
					n_{eto}			1459	1056	746			
19F29-	32.5	2850	20.1	9.70	M_0					39.9	41.5		
					M_N					32.5	32.5		
					$M_{0,max}$					35.2	47.2		
					M_{max}					51.5	68.3		
					n_{eto}						2573	2033	
19J12-	62.5	1200	18.3	7.90	M_0				43.6	70.5	70.5		
					M_N				43.4	62.5	62.5		
					$M_{0,max}$				60.8	72.4	96.0		
					M_{max}				60.8	104.5	129.0		
					n_{eto}				1376	996	839		
19J29-	50.5	2850	31.0	15.10	M_0						55.5	70.5	70.5
					M_N						50.5	50.5	50.5
					$M_{0,max}$						50.2	72.4	79.5
					M_{max}						73.8	104.7	127.6
					n_{eto}						2850	2162	1817

- $I...$ [A], $M...$ [Nm], $n...$ [r/min], $P...$ [kW]

5.1

MCS synchronous servo motors

Technical data



Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

- The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
19P12-	72.0	1200	21.3	9.00	M_0				47.5	86.0	86.0		
					M_N				46.4	72.0	72.0		
					$M_{0,max}$				69.5	79.6	106.7		
					M_{max}				69.5	116.7	155.5		
					n_{eto}				1400	1187	996		
19P29-	53.0	2850	29.5	15.80	M_0						58.7	86.0	86.0
					M_N						53.0	53.0	53.0
					$M_{0,max}$						53.9	79.6	87.6
					M_{max}						81.2	116.9	144.3
					n_{eto}						2938	2638	2298

- I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

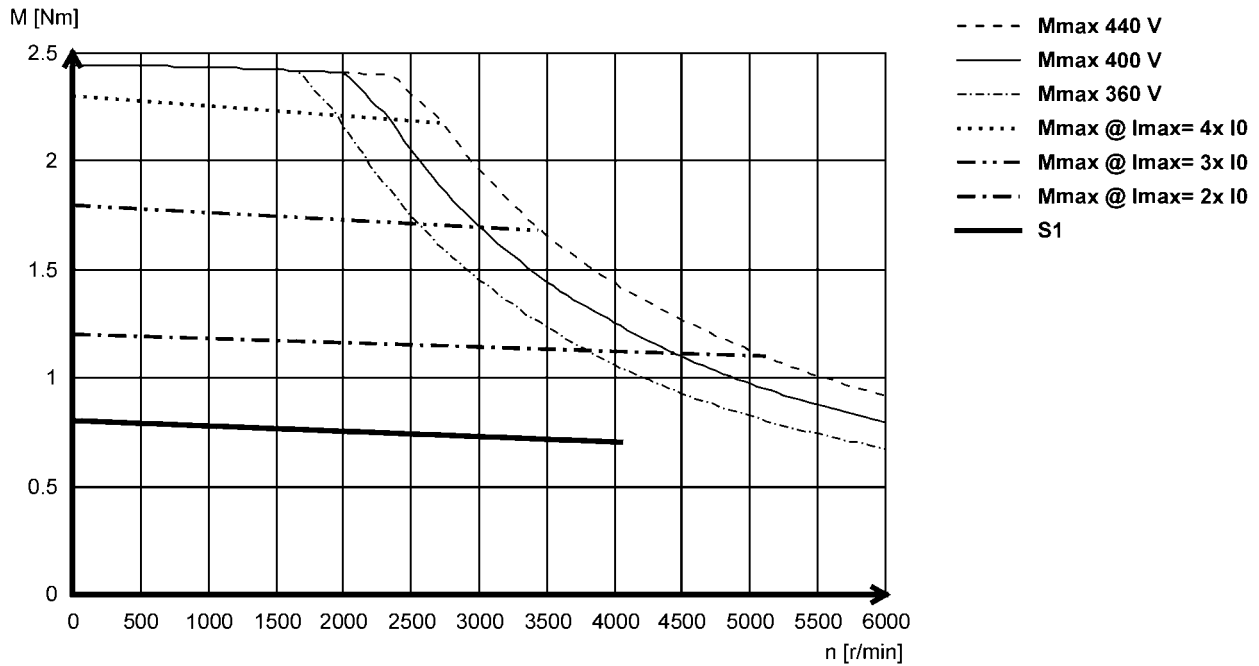
Technical data



Torque characteristics

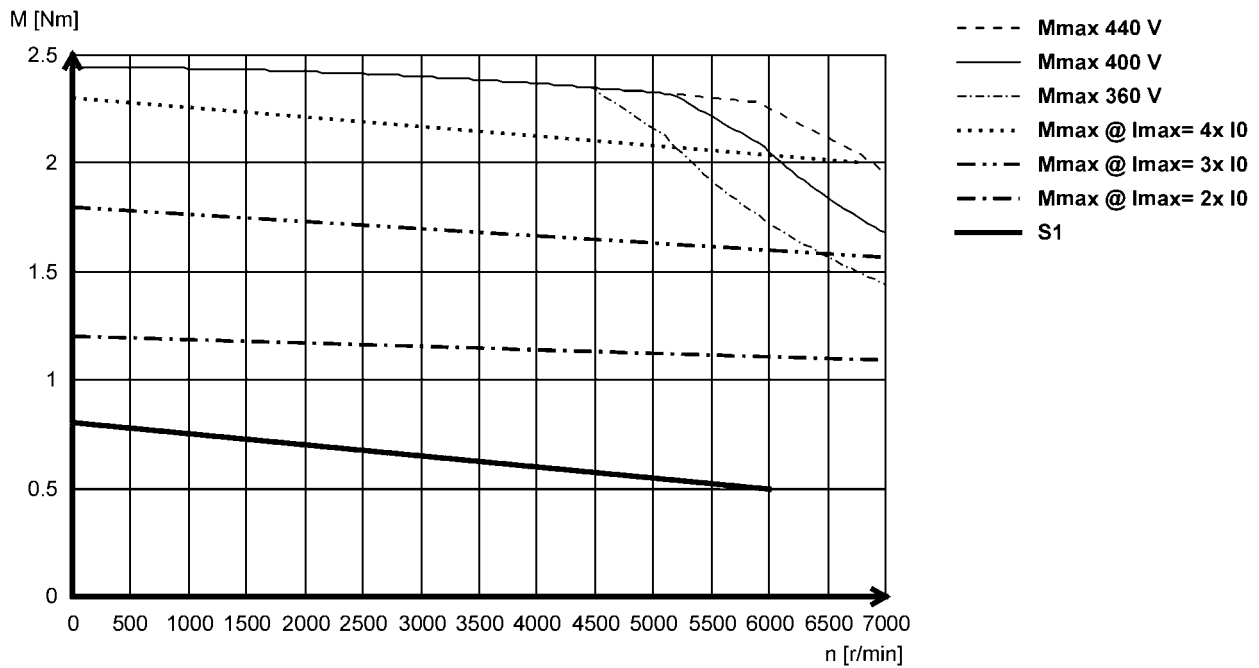
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS06C41- (non-ventilated)



5.1

MCS06C60- (non-ventilated)



MCS synchronous servo motors

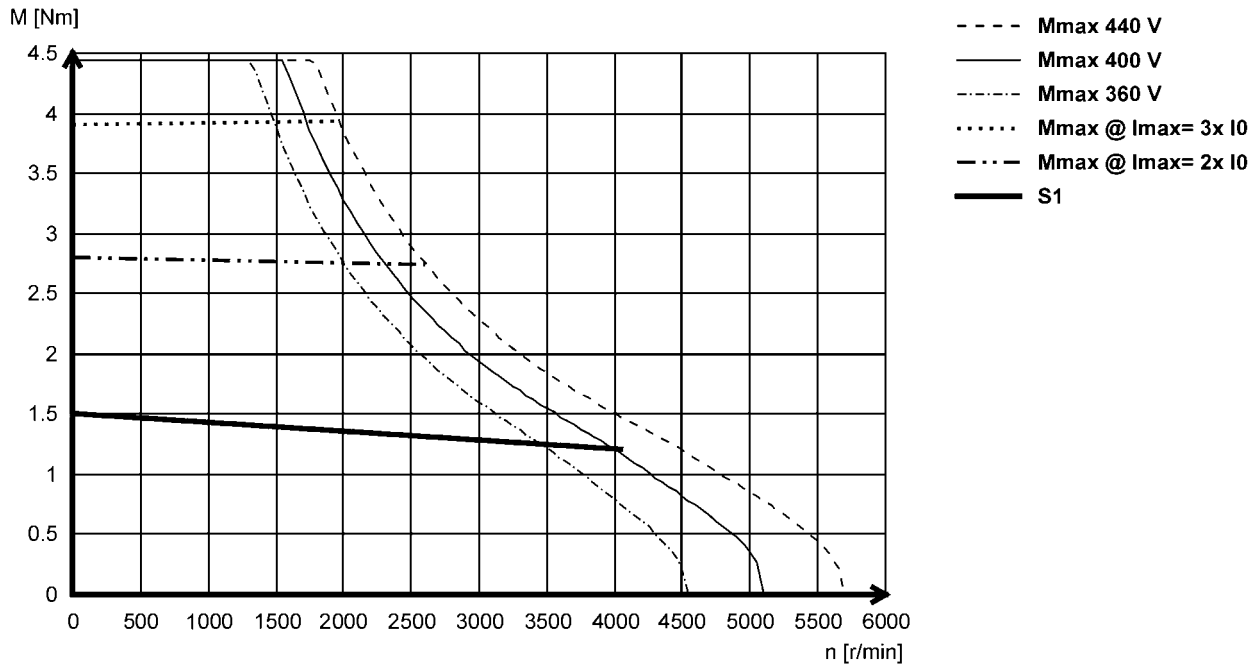
Technical data



Torque characteristics

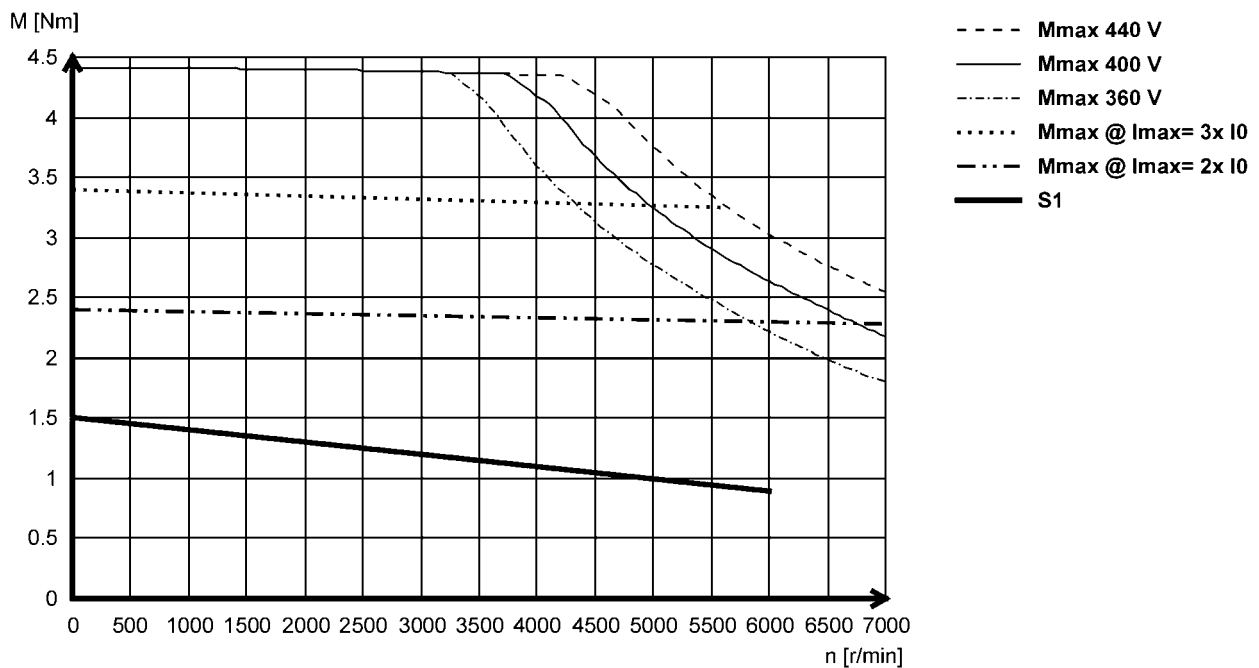
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS06F41- (non-ventilated)



5.1

MCS06F60- (non-ventilated)



MCS synchronous servo motors

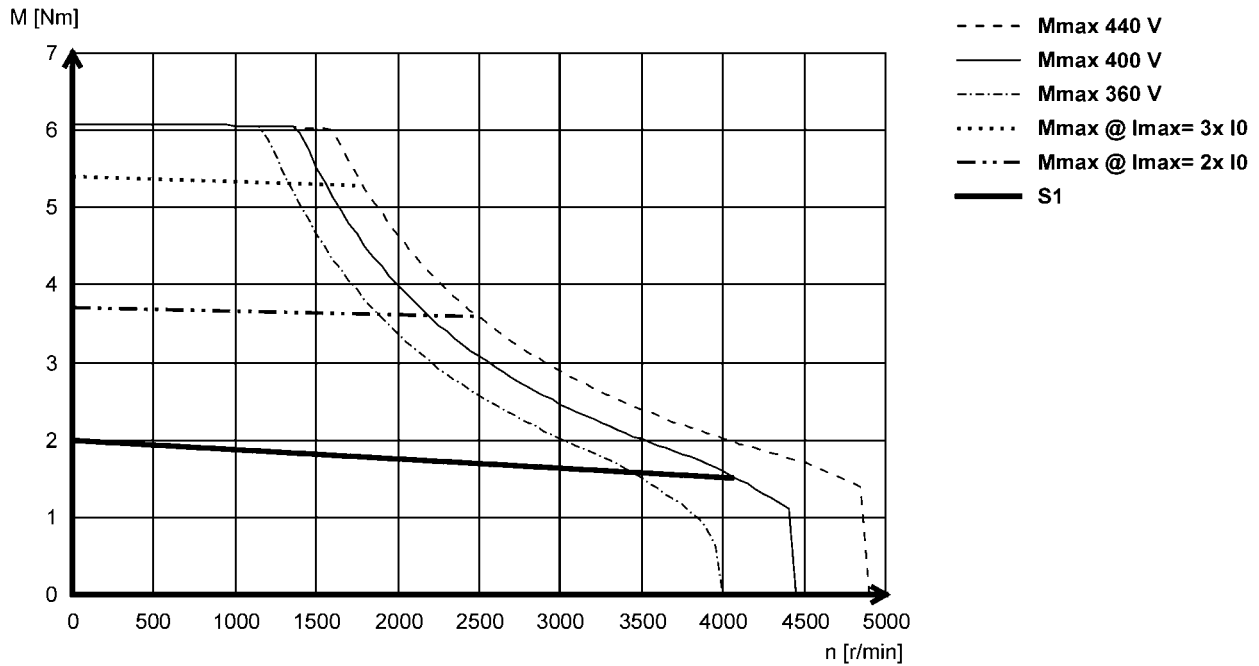
Technical data



Torque characteristics

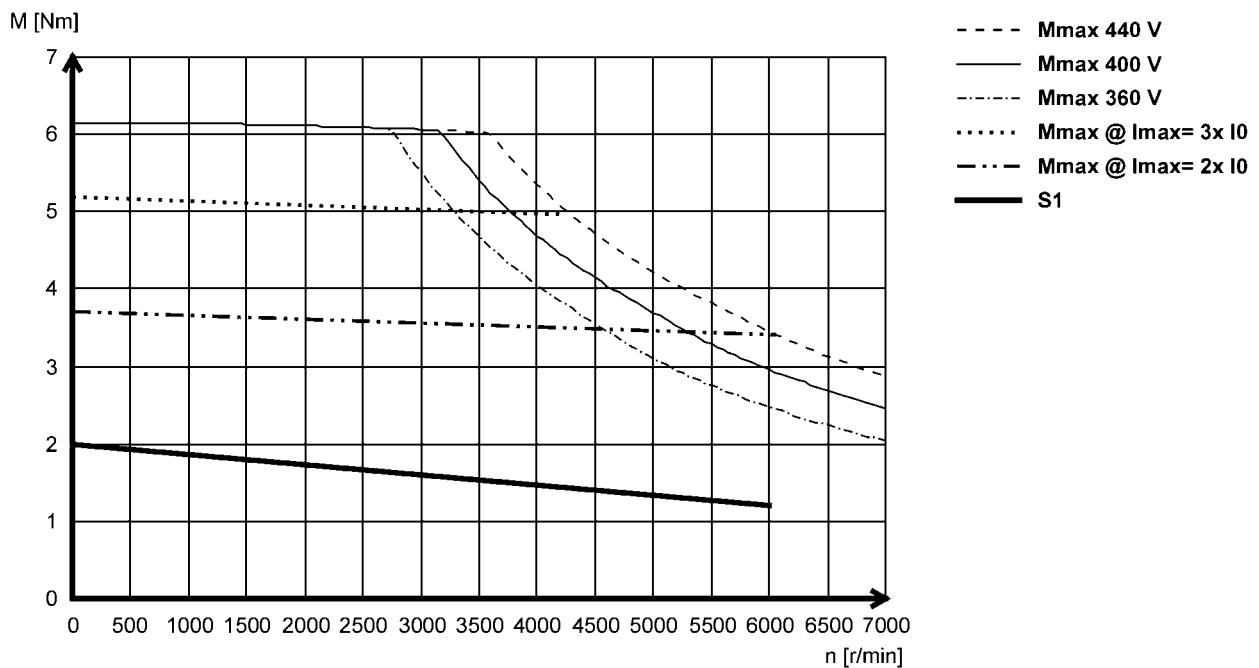
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS06I41- (non-ventilated)



5.1

MCS06I60- (non-ventilated)



MCS synchronous servo motors

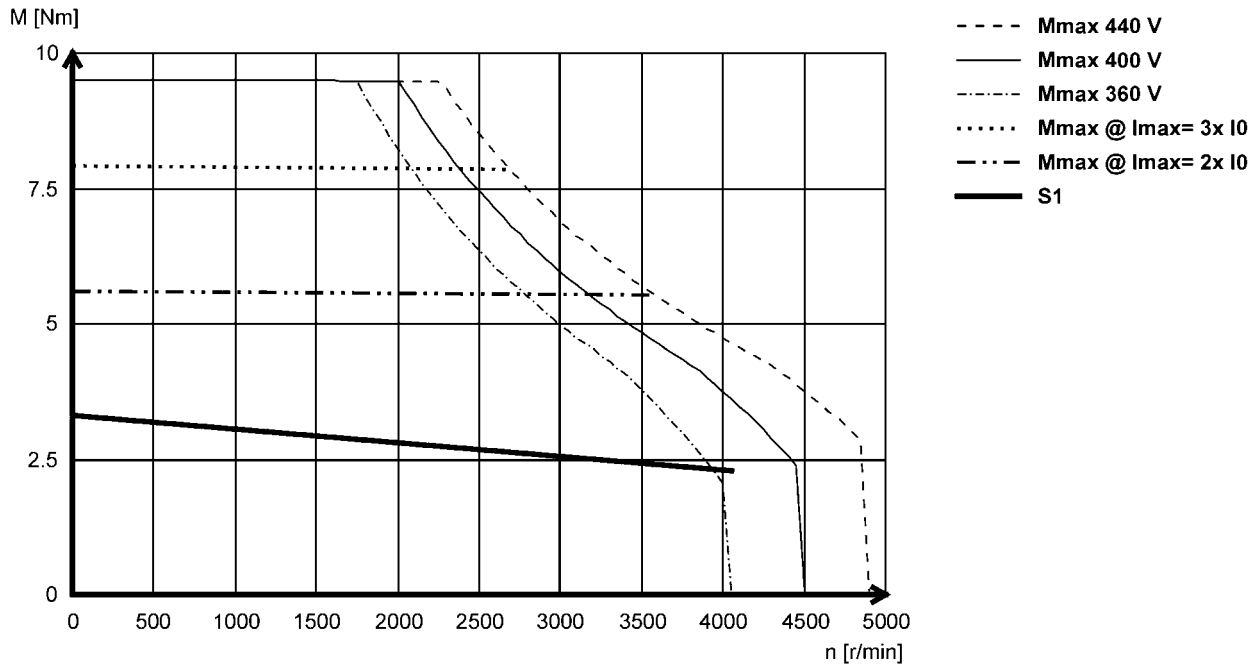
Technical data



Torque characteristics

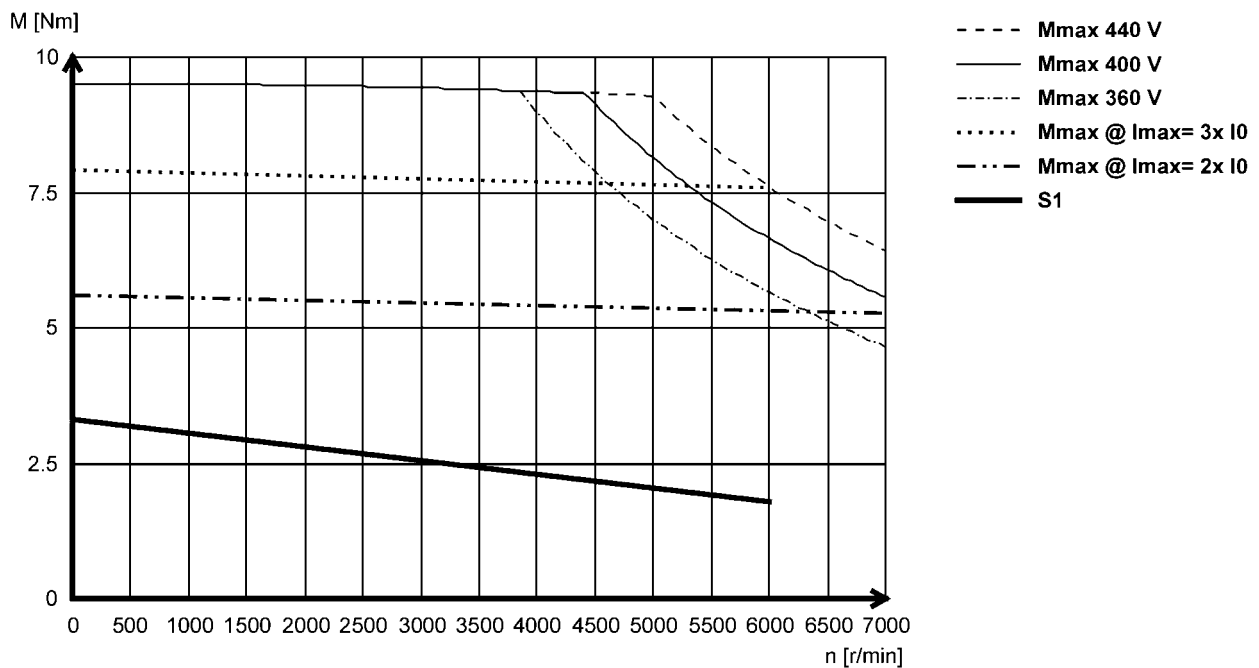
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09D41- (non-ventilated)



5.1

MCS09D60- (non-ventilated)



MCS synchronous servo motors

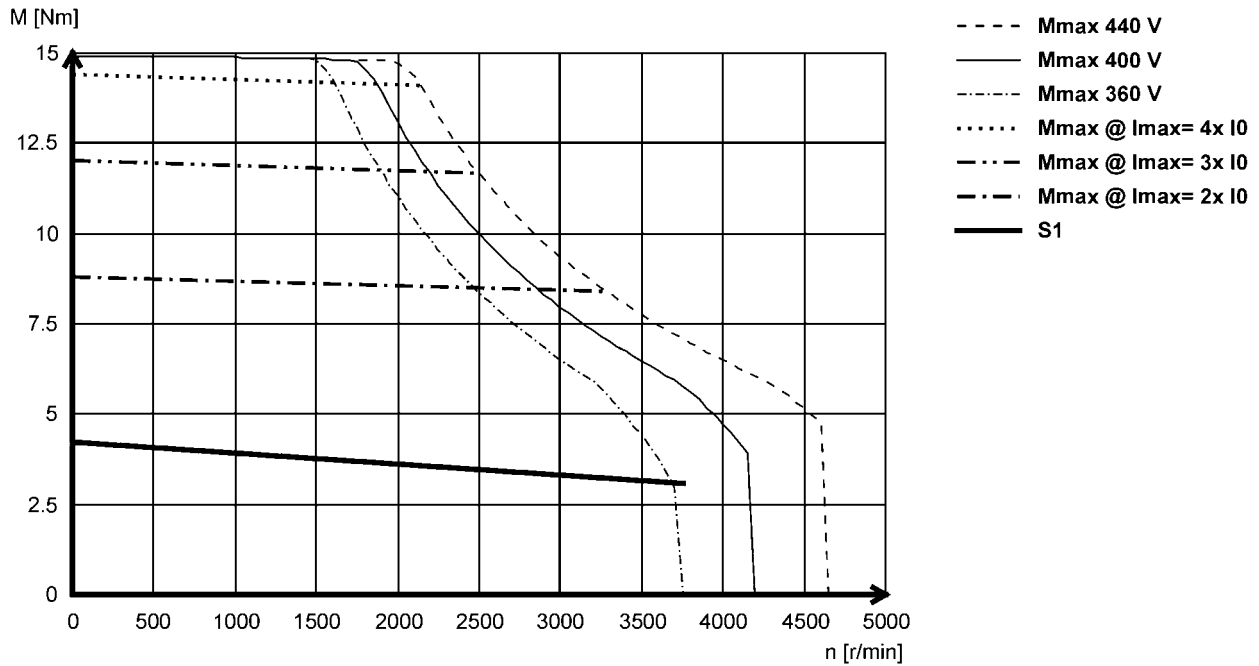
Technical data



Torque characteristics

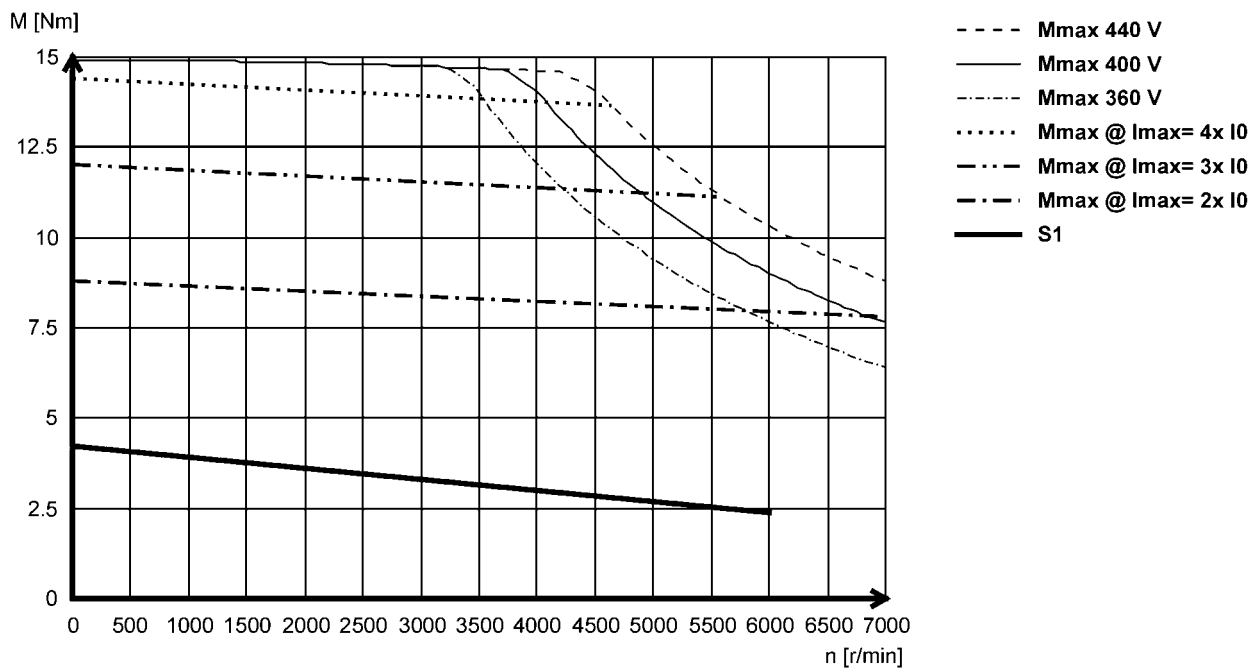
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09F38- (non-ventilated)



5.1

MCS09F60- (non-ventilated)



MCS synchronous servo motors

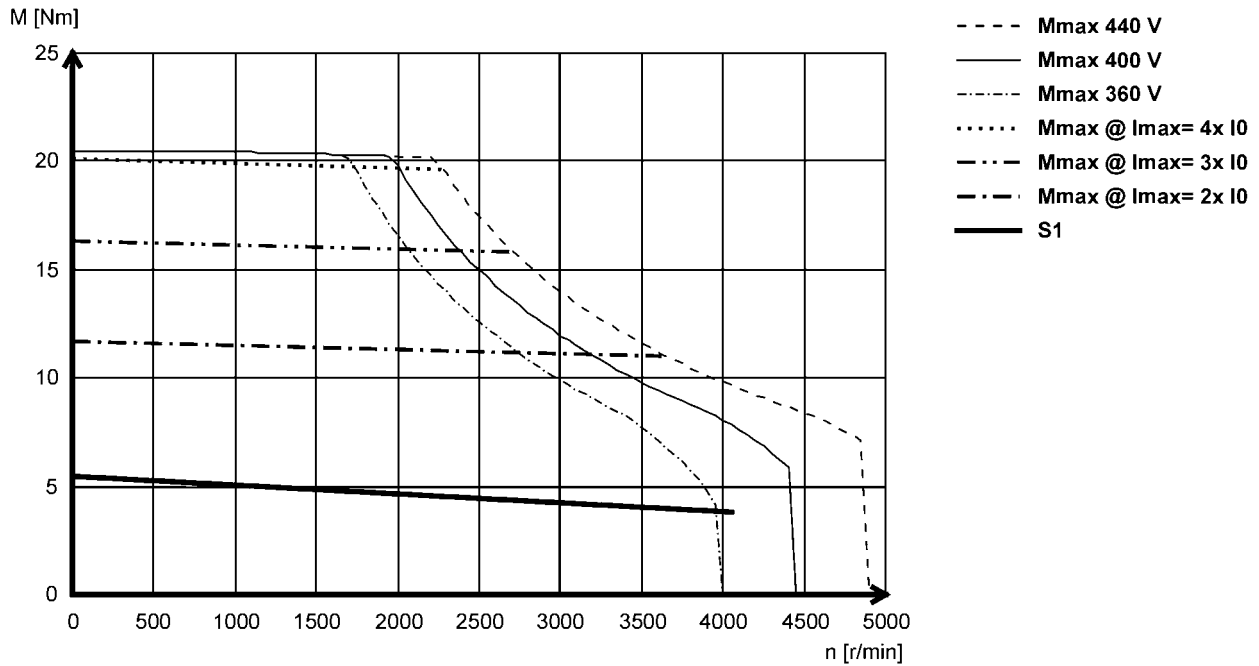
Technical data



Torque characteristics

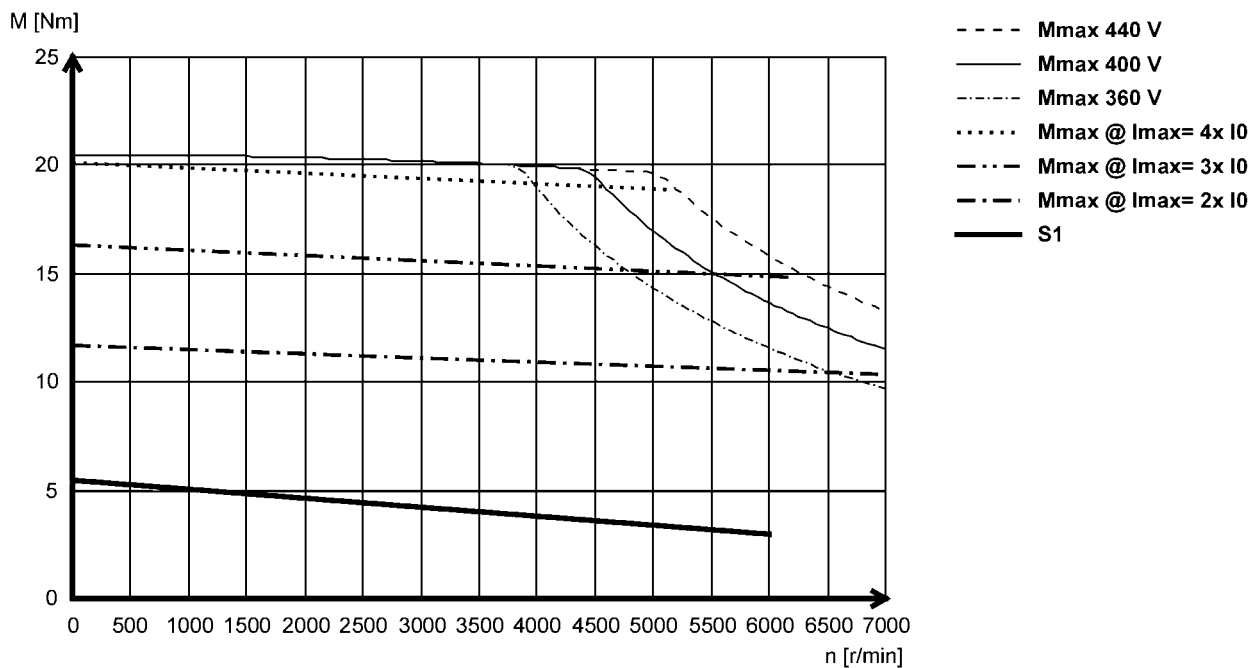
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09H41- (non-ventilated)



5.1

MCS09H60- (non-ventilated)



MCS synchronous servo motors

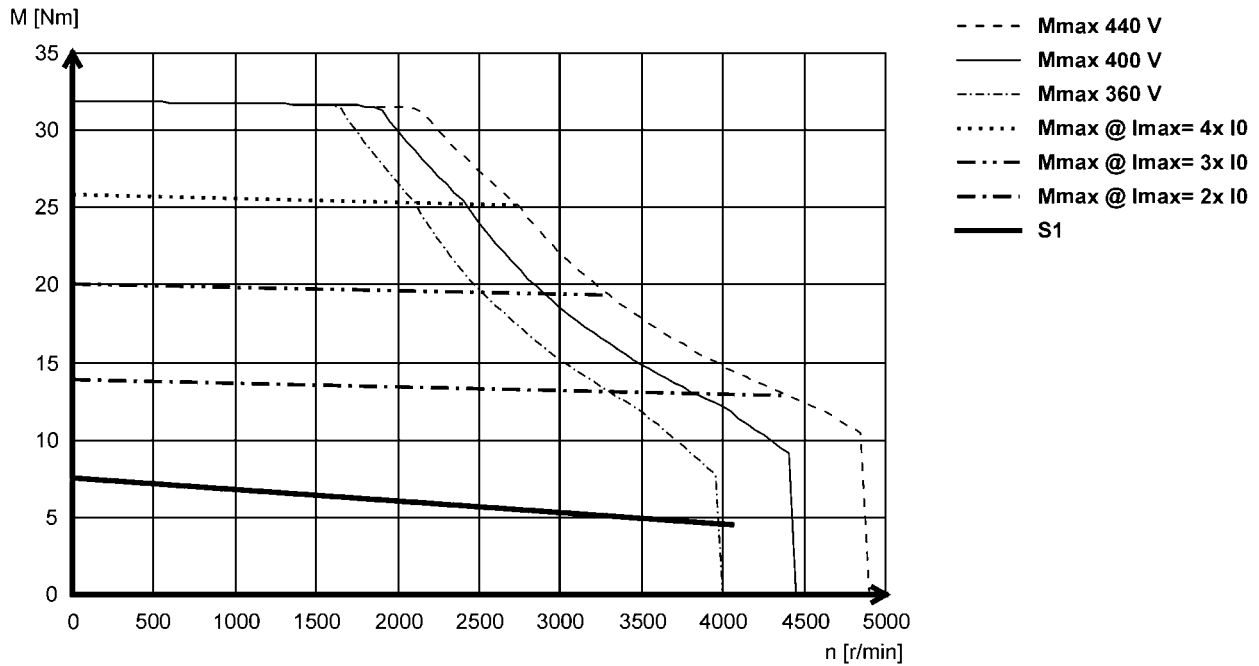
Technical data



Torque characteristics

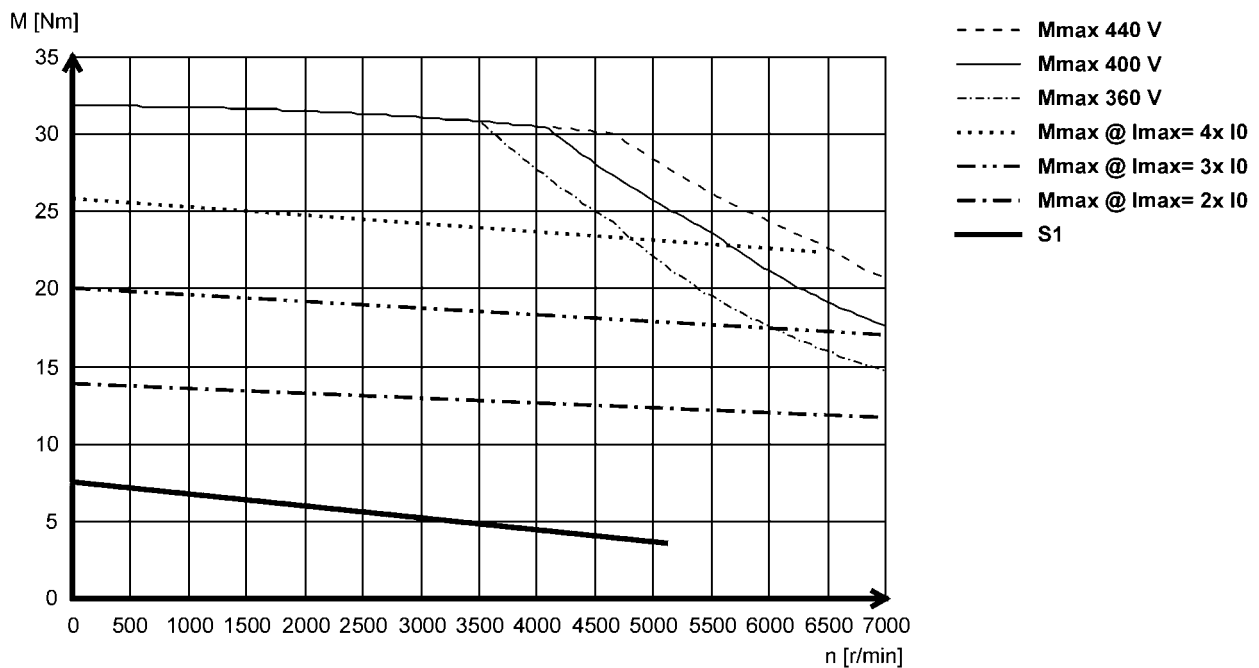
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09L41- (non-ventilated)



5.1

MCS09L51- (non-ventilated)



MCS synchronous servo motors

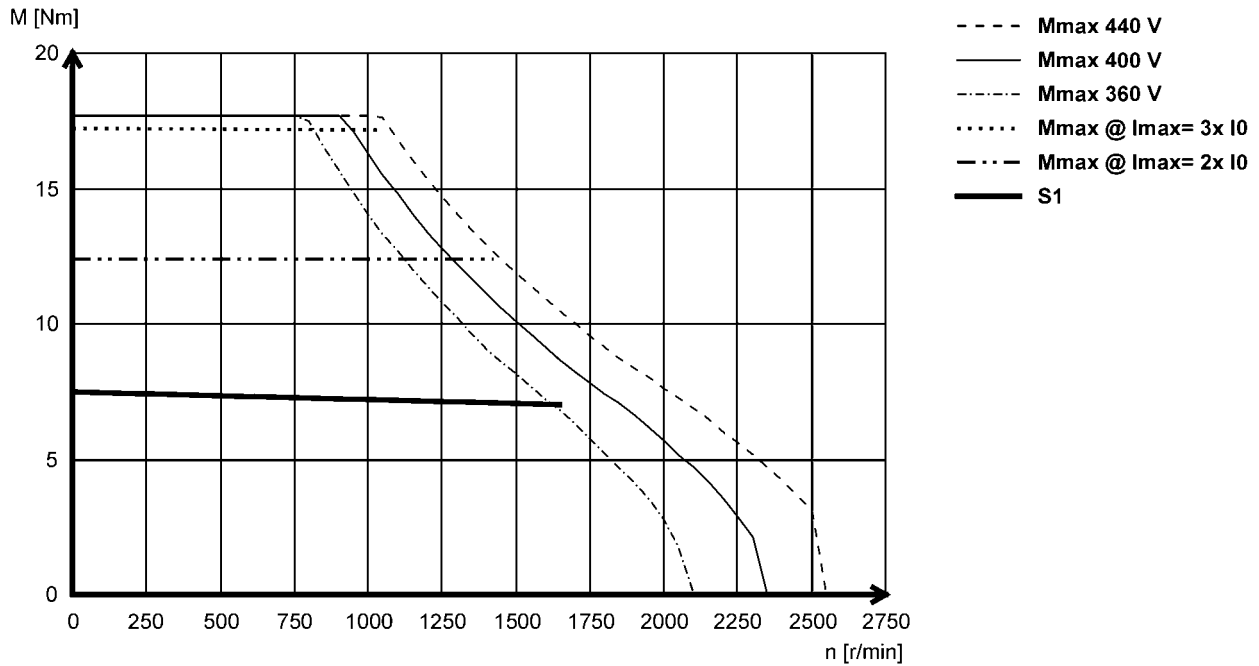
Technical data



Torque characteristics

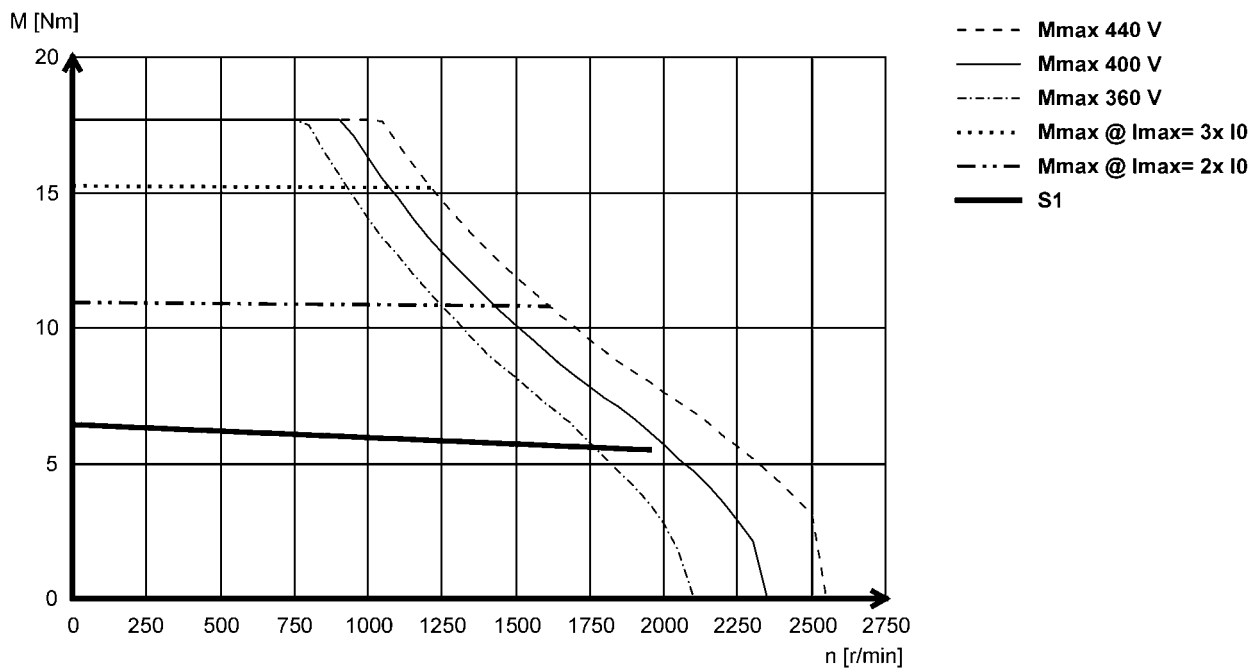
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12D17 (forced ventilated)



5.1

MCS12D20- (non-ventilated)



MCS synchronous servo motors

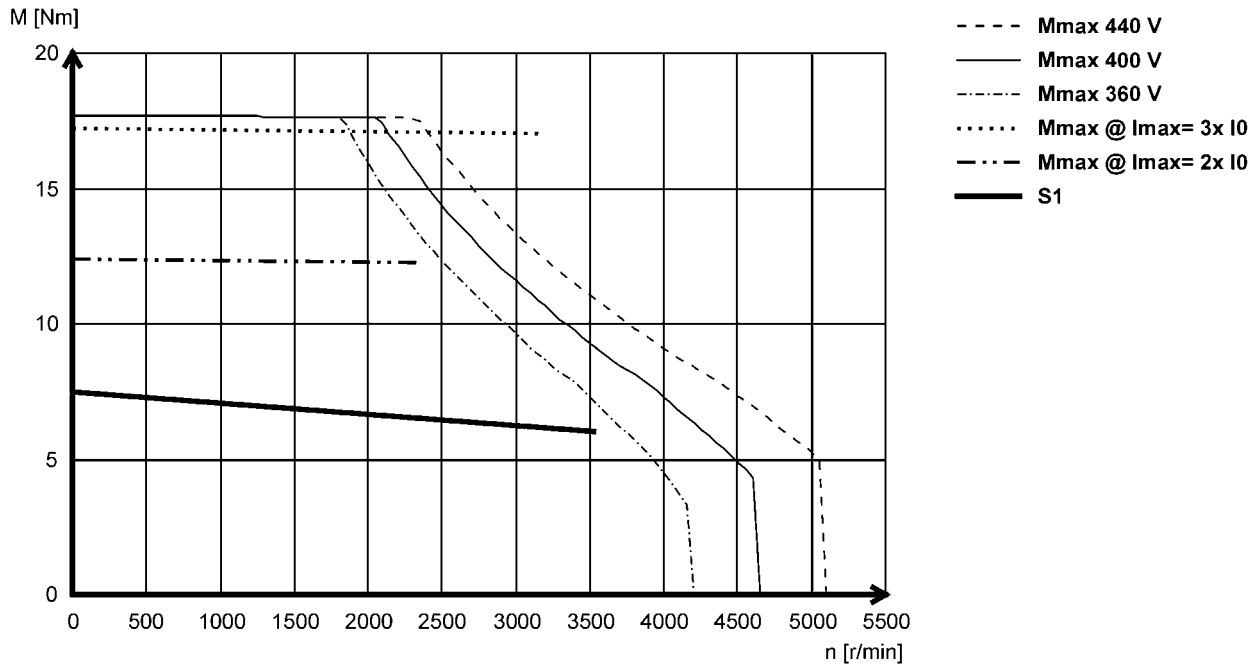
Technical data



Torque characteristics

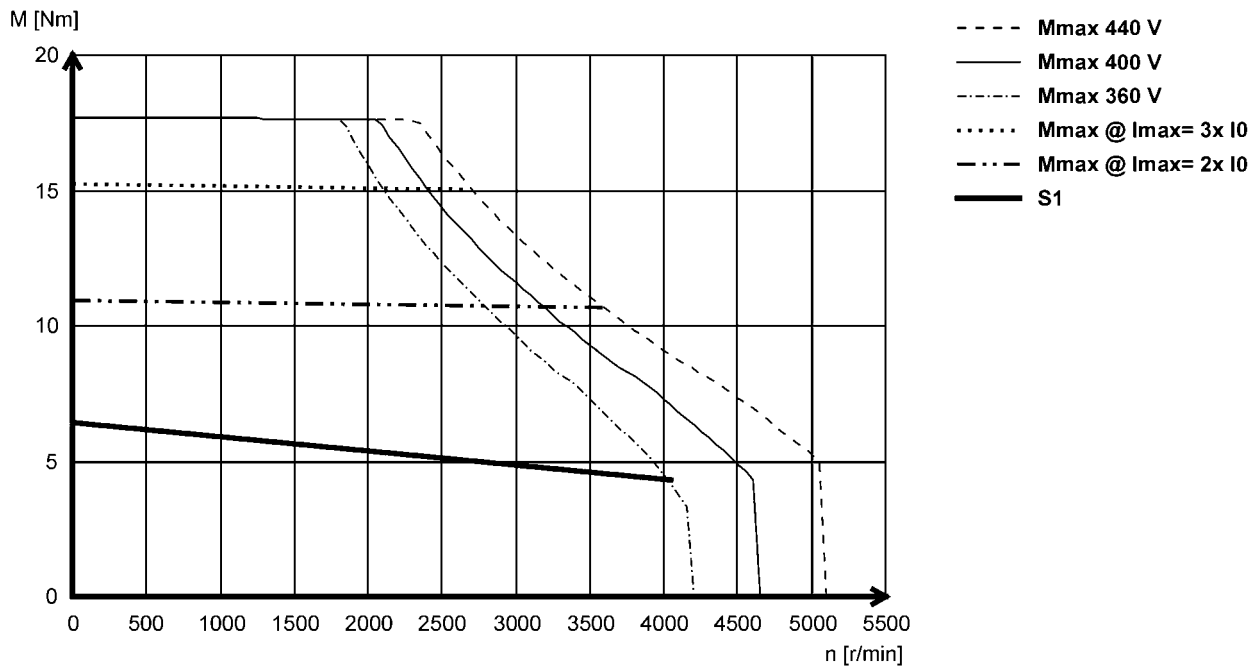
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12D35- (forced ventilated)



5.1

MCS12D41- (non-ventilated)



MCS synchronous servo motors

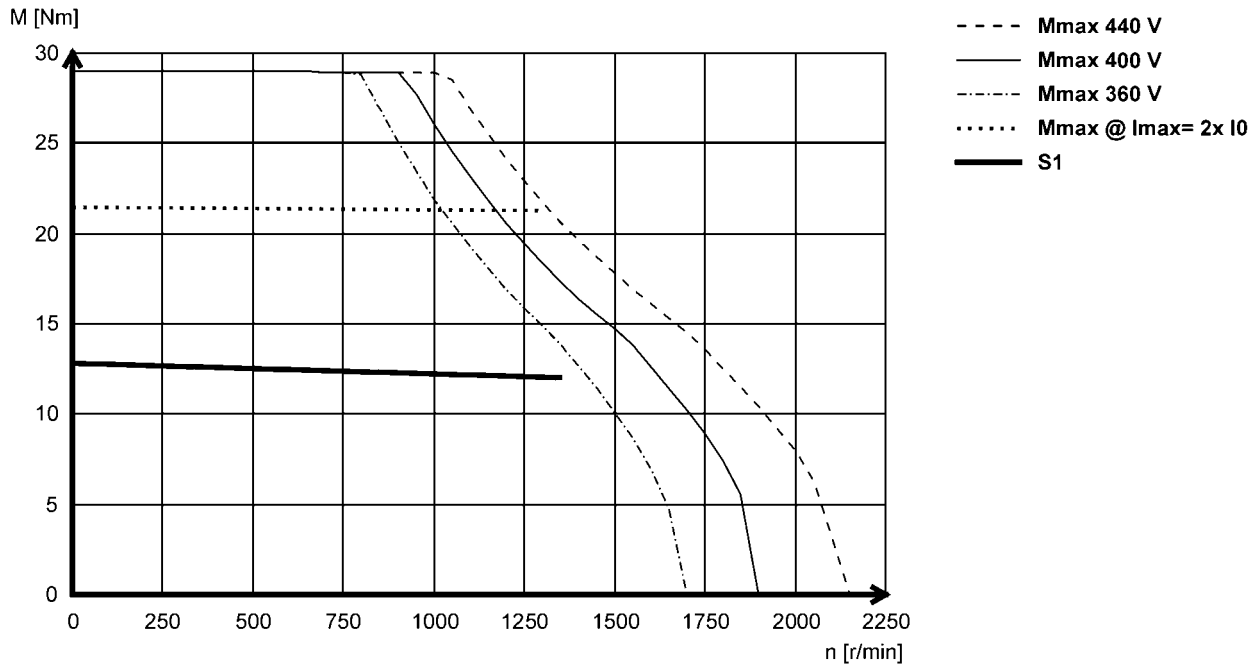
Technical data



Torque characteristics

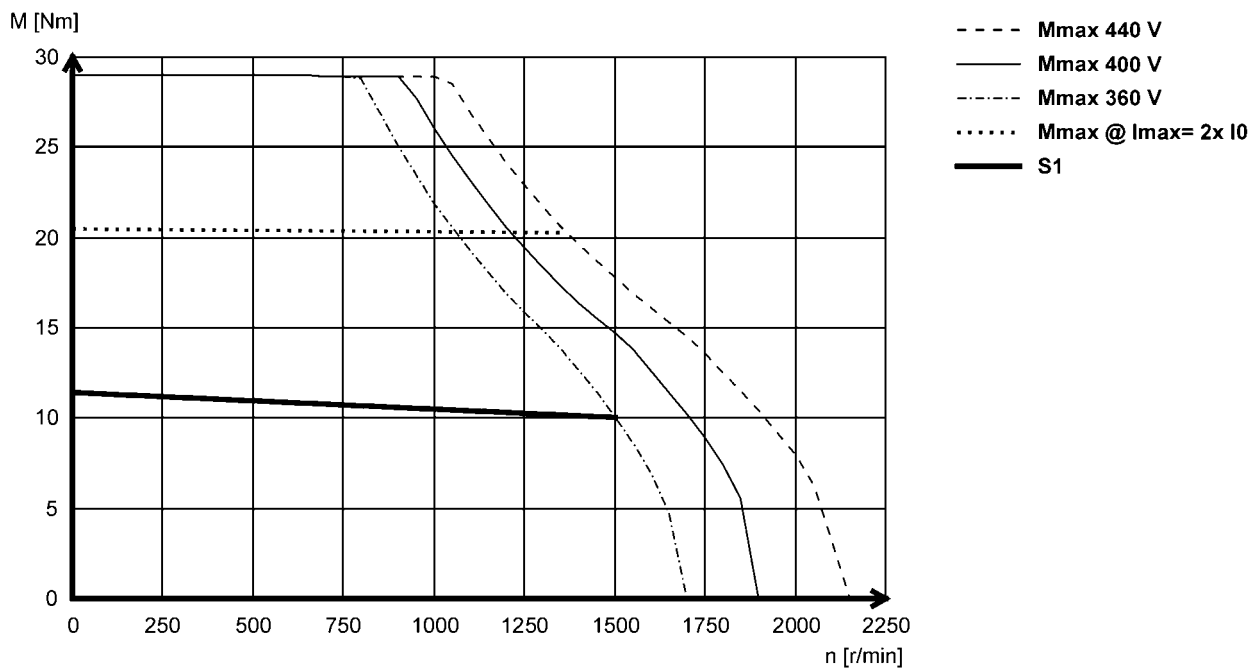
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12H14- (forced ventilated)



5.1

MCS12H15- (non-ventilated)



MCS synchronous servo motors

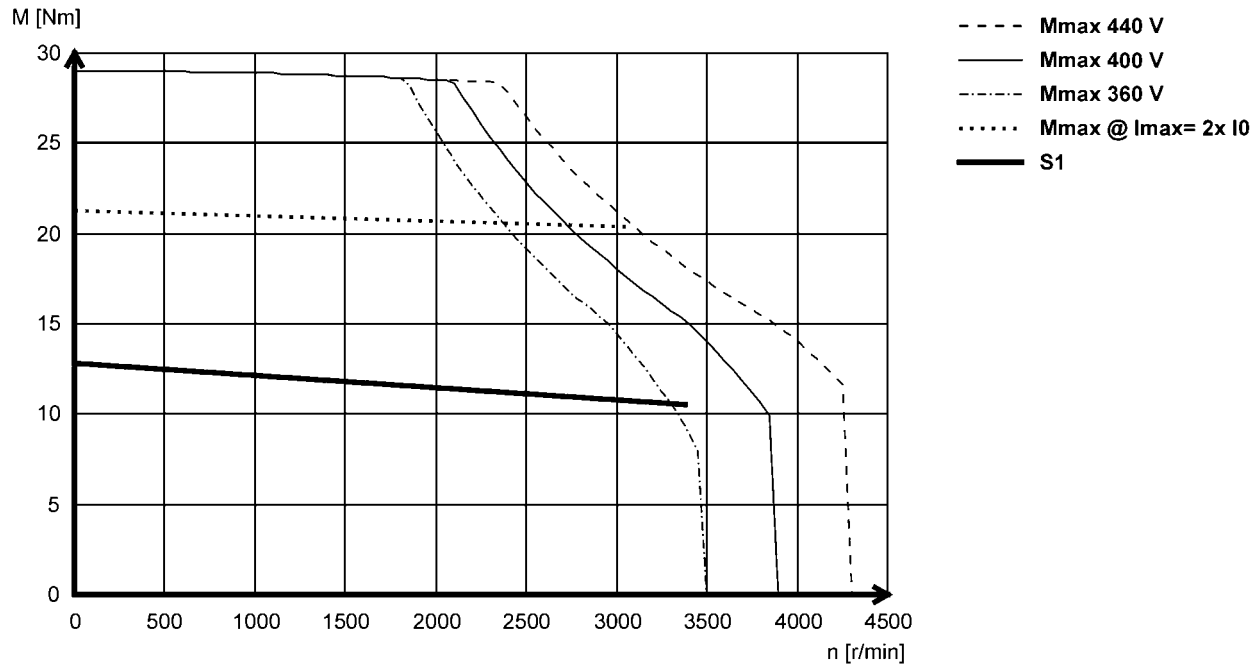
Technical data



Torque characteristics

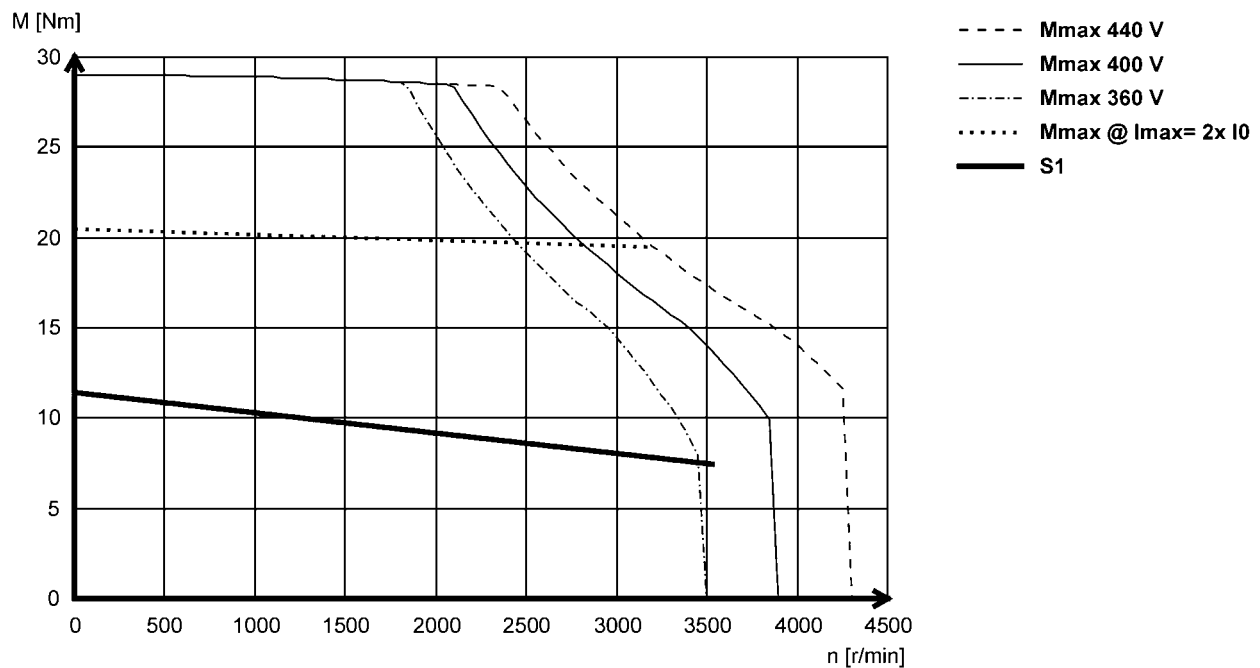
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12H34- (forced ventilated)



5.1

MCS12H35- (non-ventilated)



MCS synchronous servo motors

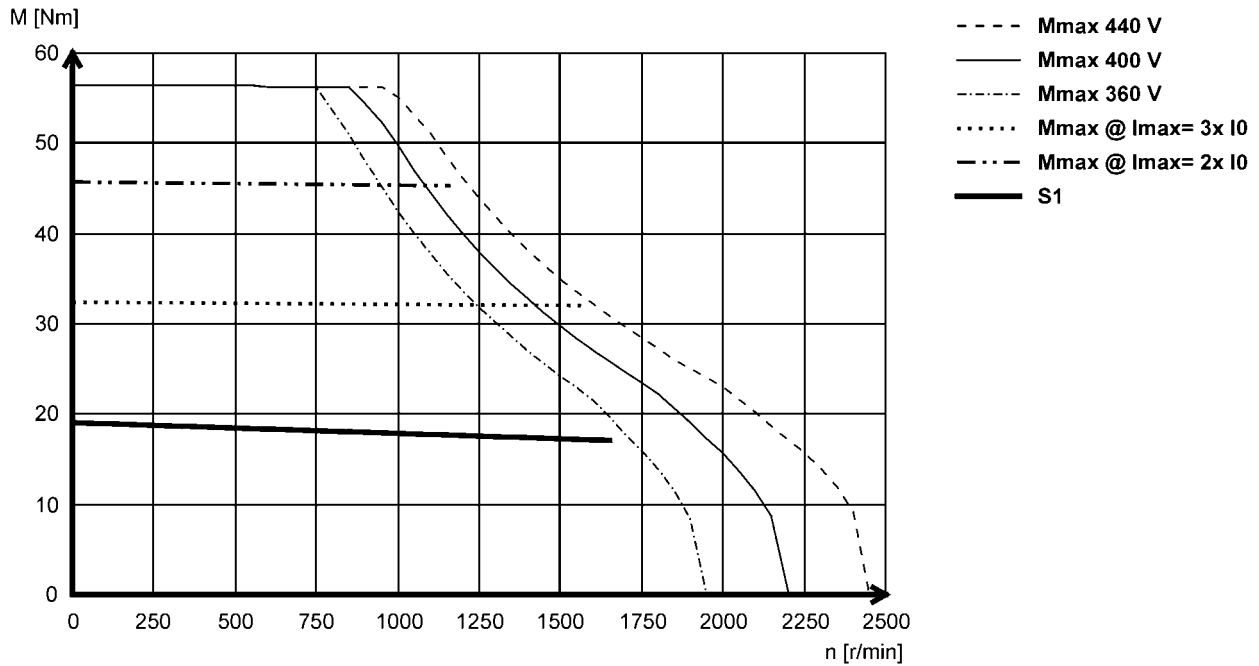
Technical data



Torque characteristics

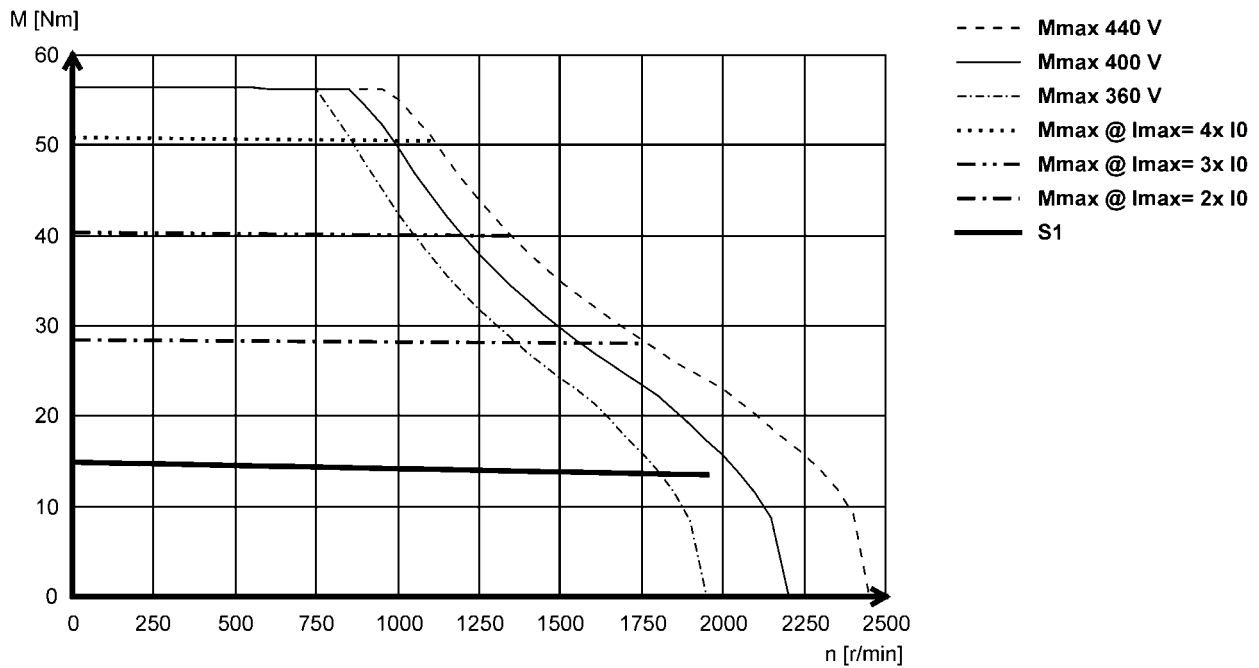
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12L17- (forced ventilated)



5.1

MCS12L20- (non-ventilated)



MCS synchronous servo motors

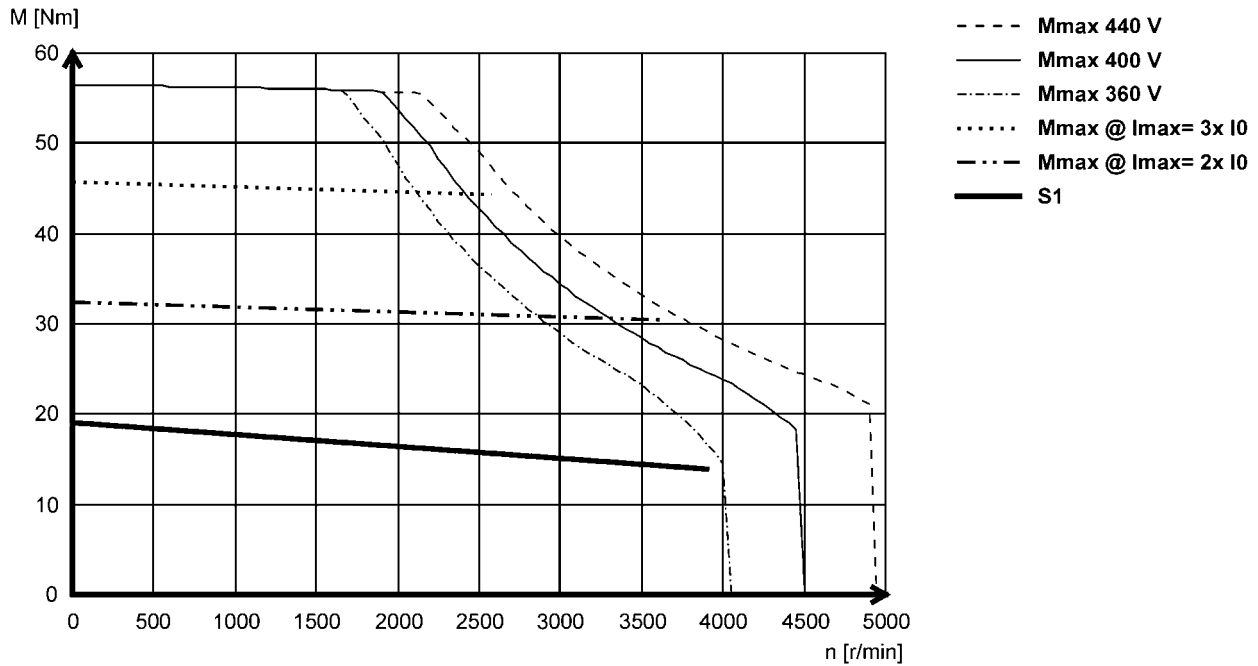
Technical data



Torque characteristics

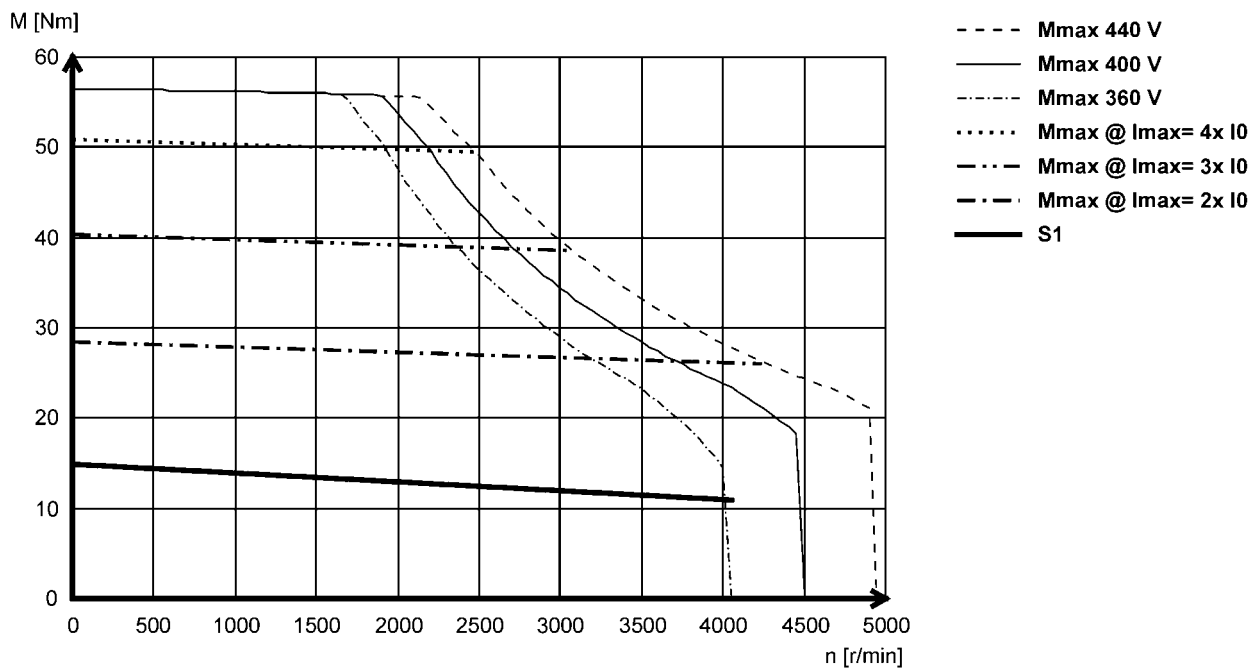
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12L39- (forced ventilated)



5.1

MCS12L41- (non-ventilated)



MCS synchronous servo motors

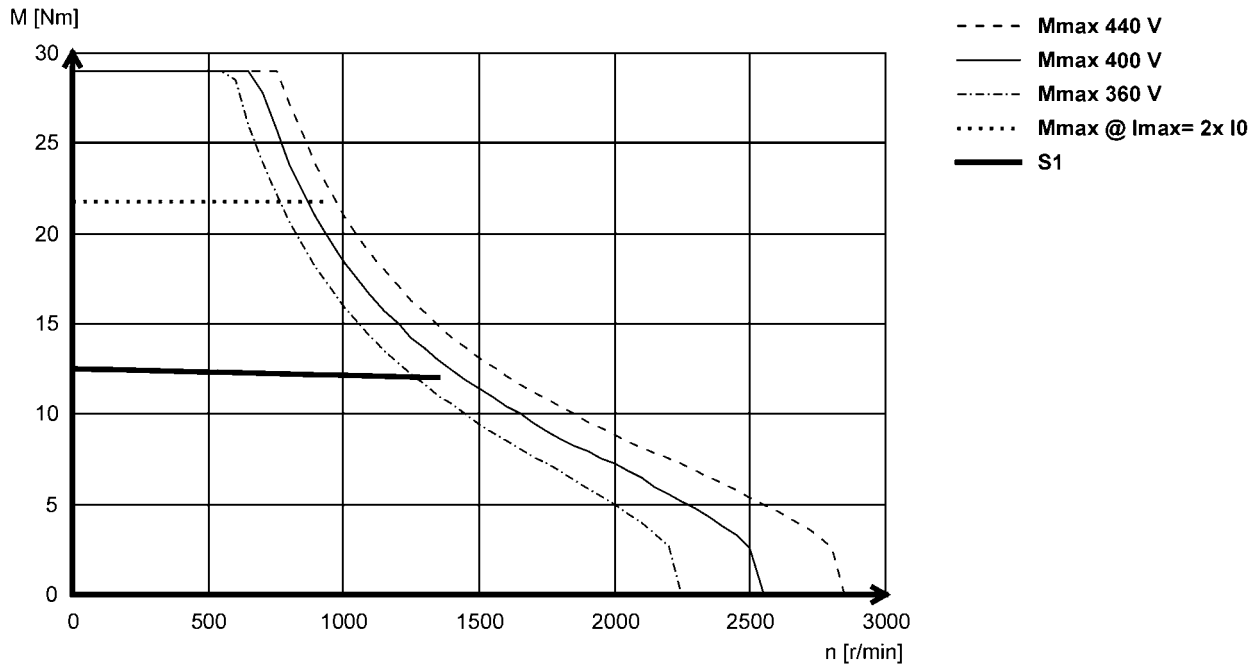
Technical data



Torque characteristics

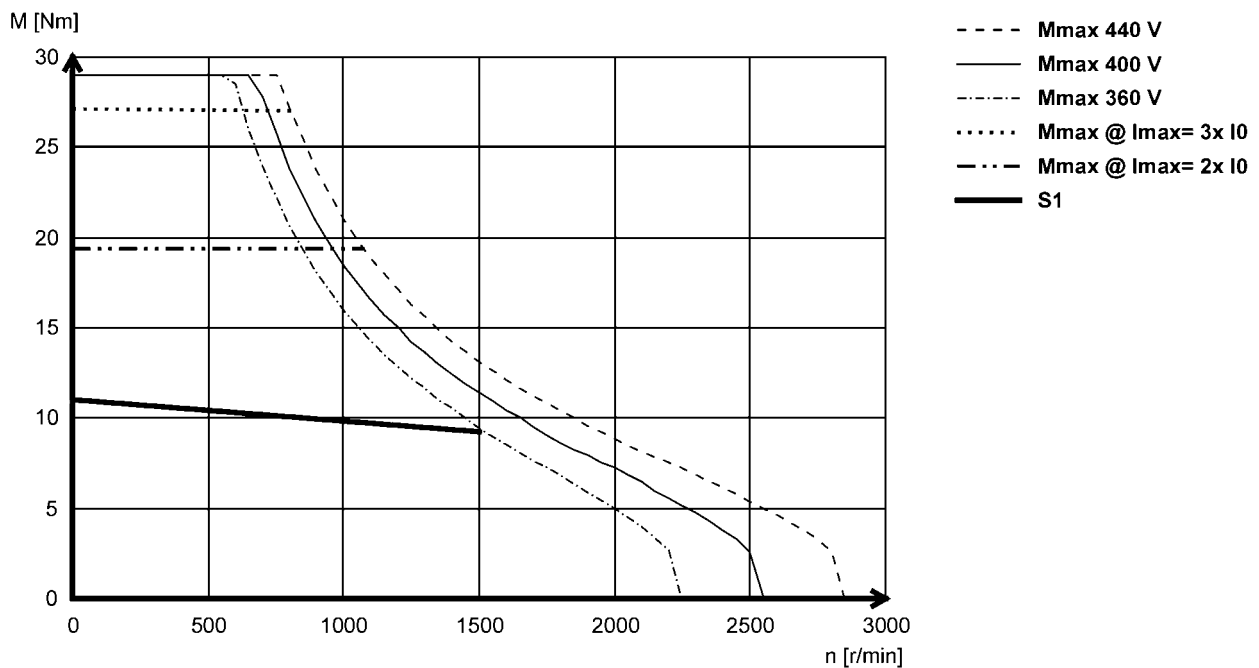
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14D14- (forced ventilated)



5.1

MCS14D15- (non-ventilated)



MCS synchronous servo motors

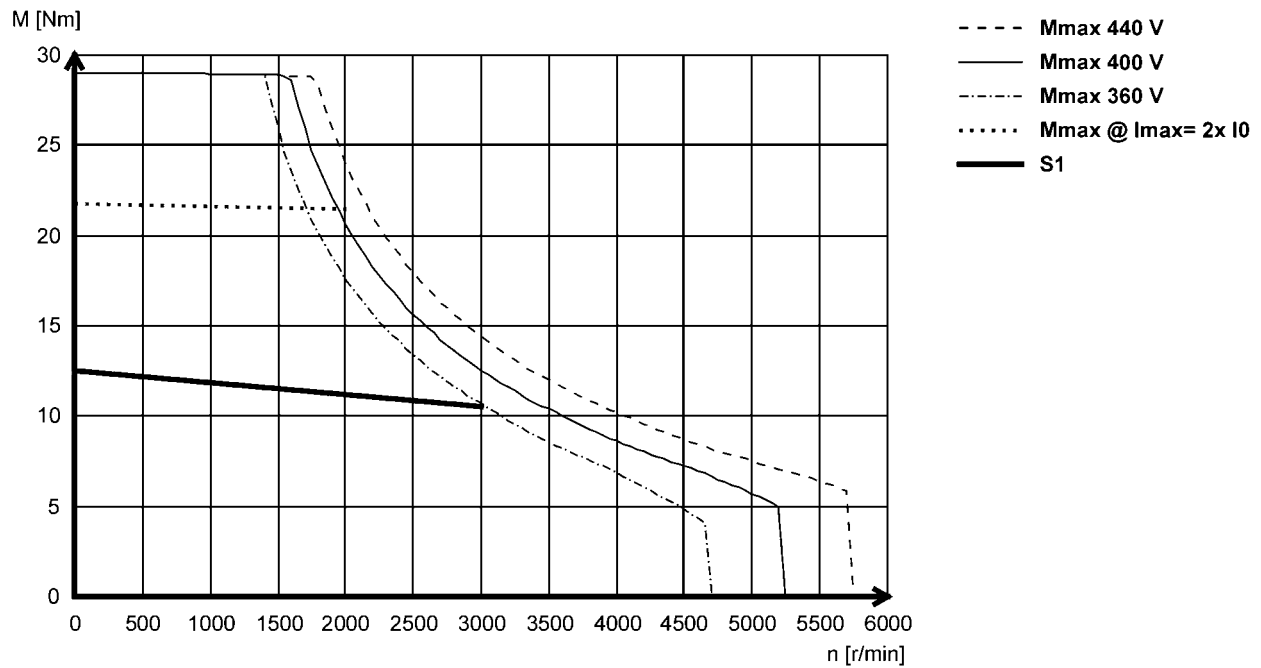
Technical data



Torque characteristics

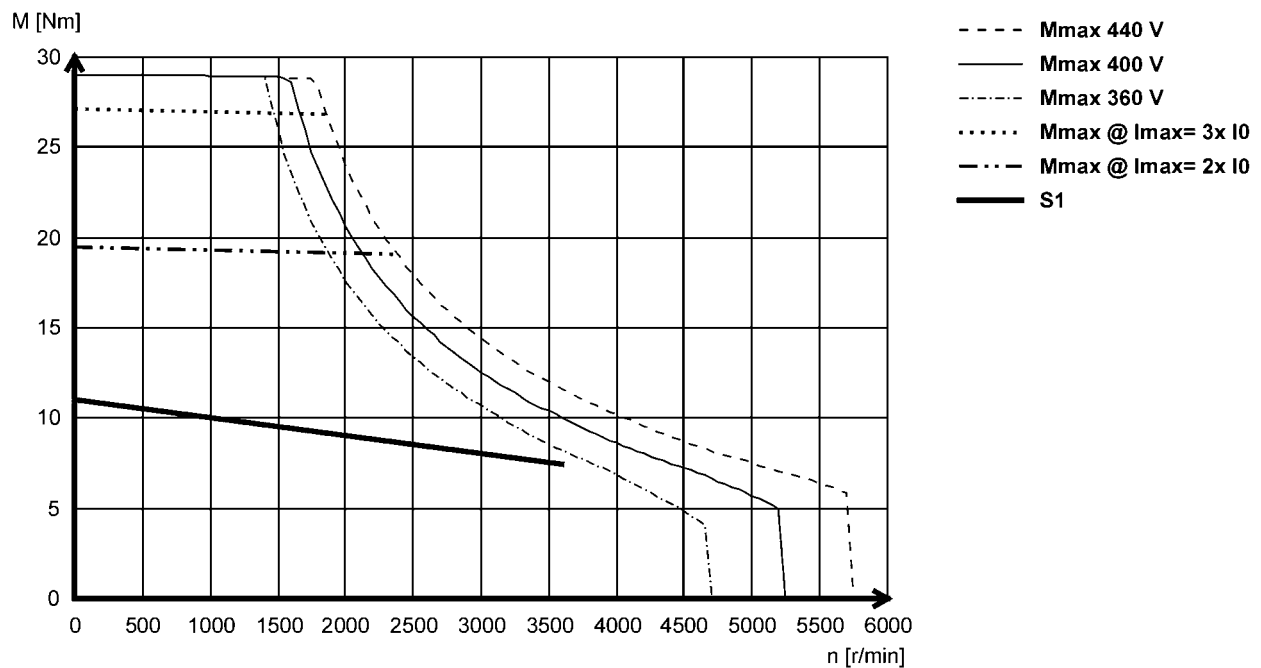
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14D30 (forced ventilated)



5.1

MCS14D36- (non-ventilated)



MCS synchronous servo motors

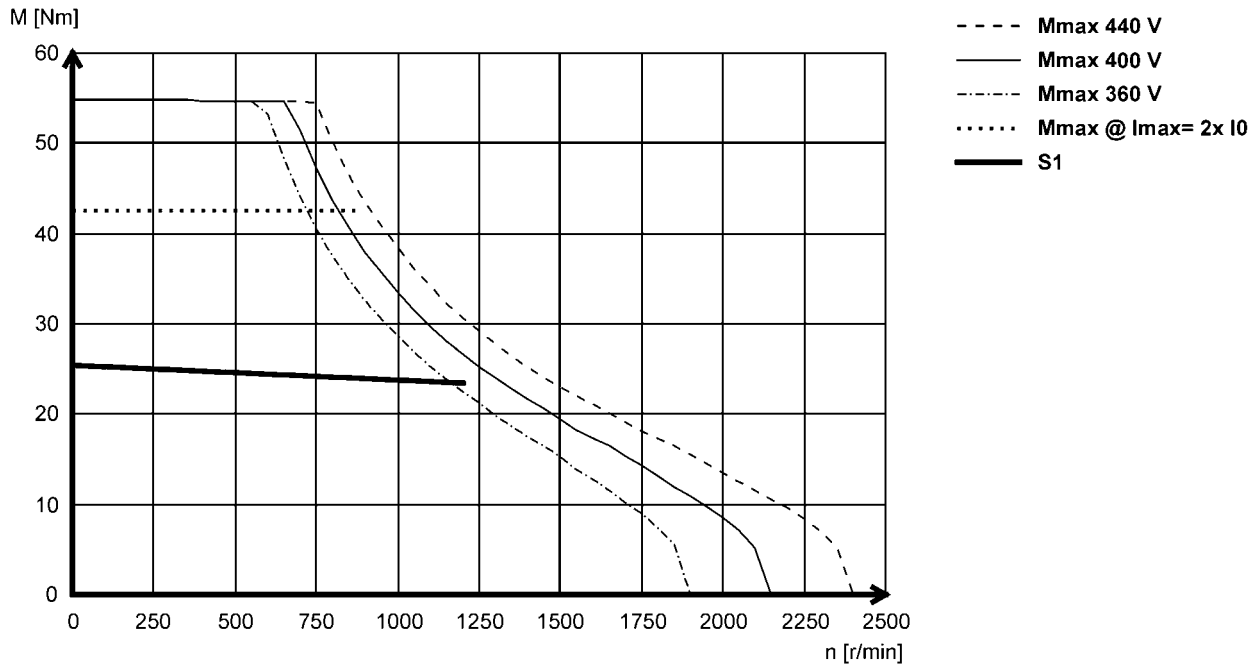
Technical data



Torque characteristics

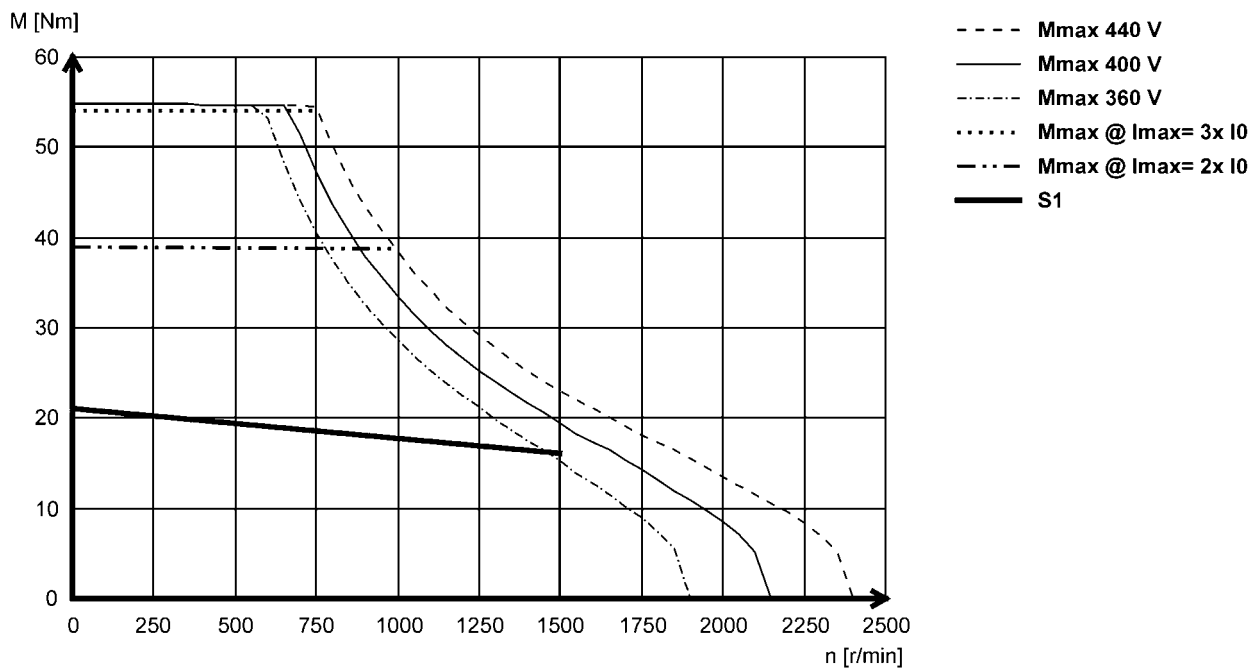
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14H12- (forced ventilated)



5.1

MCS14H15- (non-ventilated)



MCS synchronous servo motors

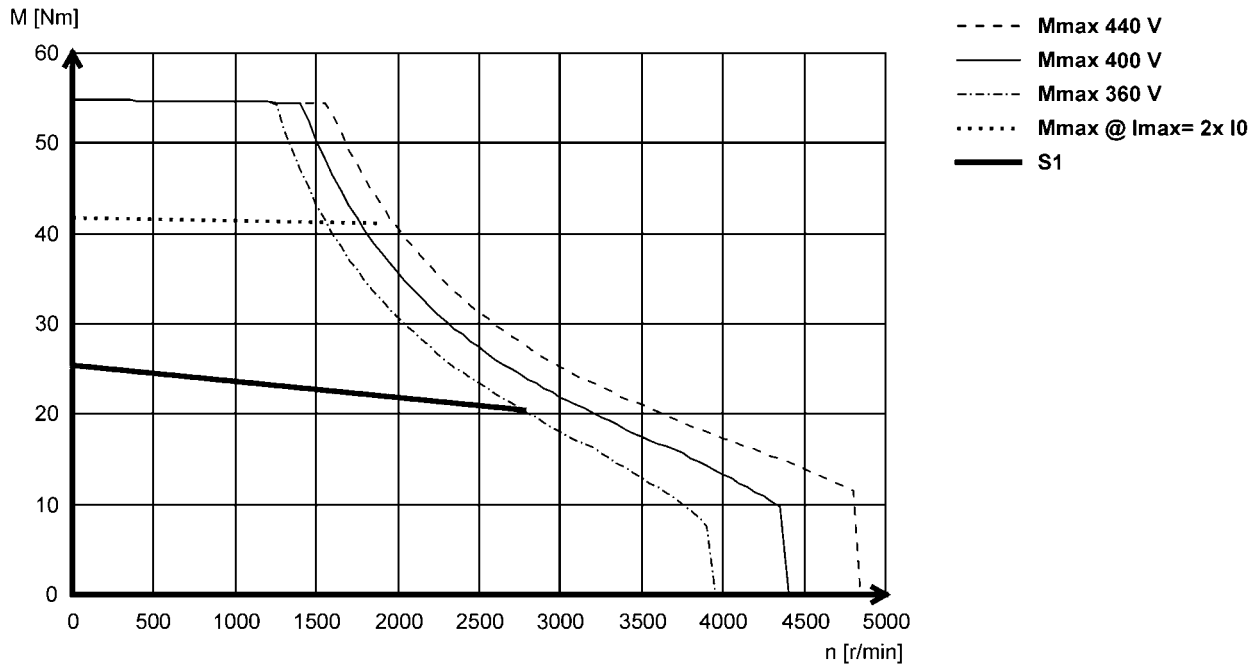
Technical data



Torque characteristics

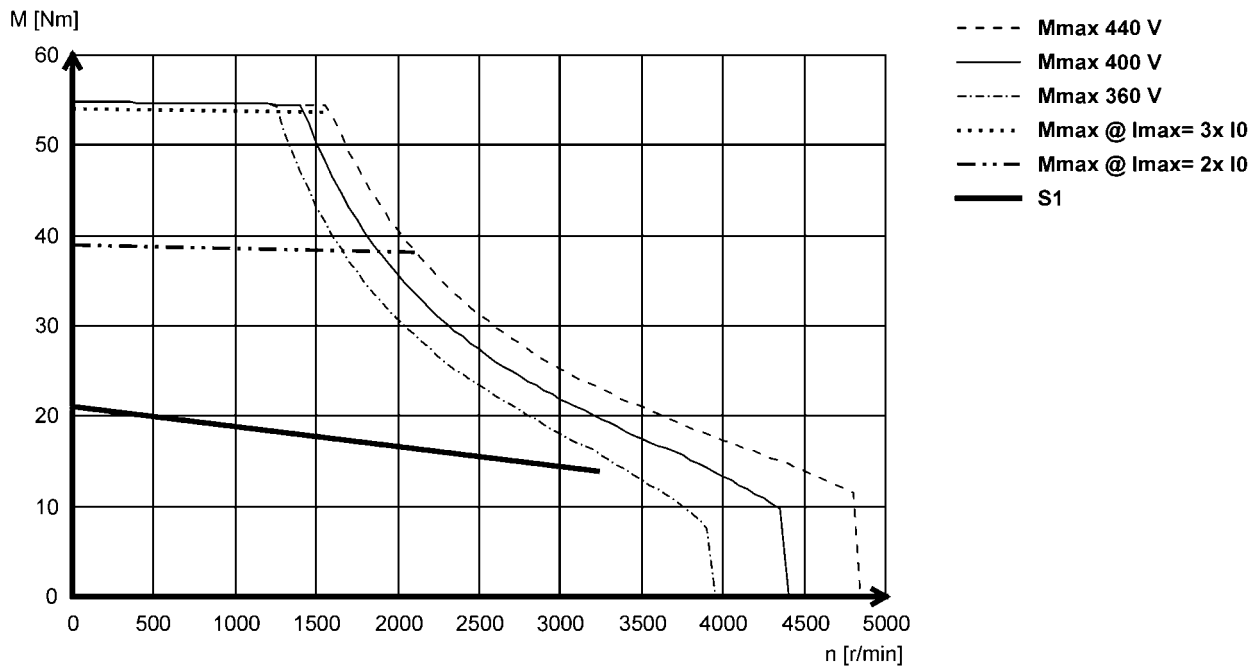
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14H28- (forced ventilated)



5.1

MCS14H32- (non-ventilated)



MCS synchronous servo motors

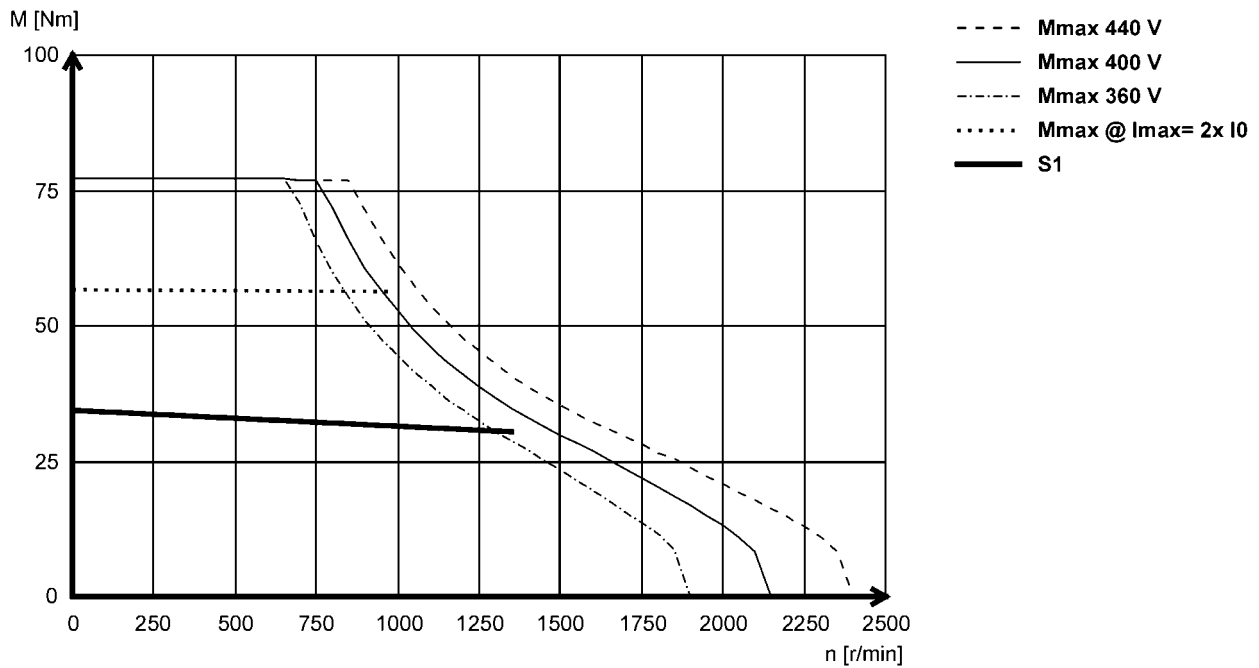
Technical data



Torque characteristics

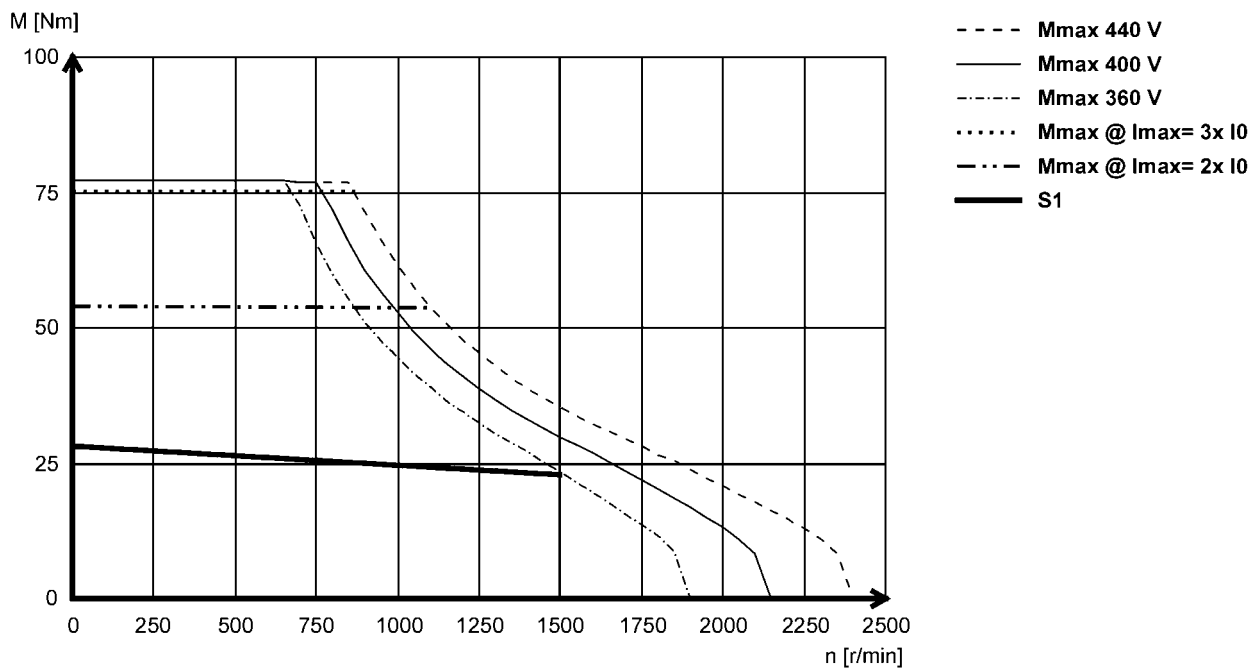
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14L14- (forced ventilated)



5.1

MCS14L15- (non-ventilated)



MCS synchronous servo motors

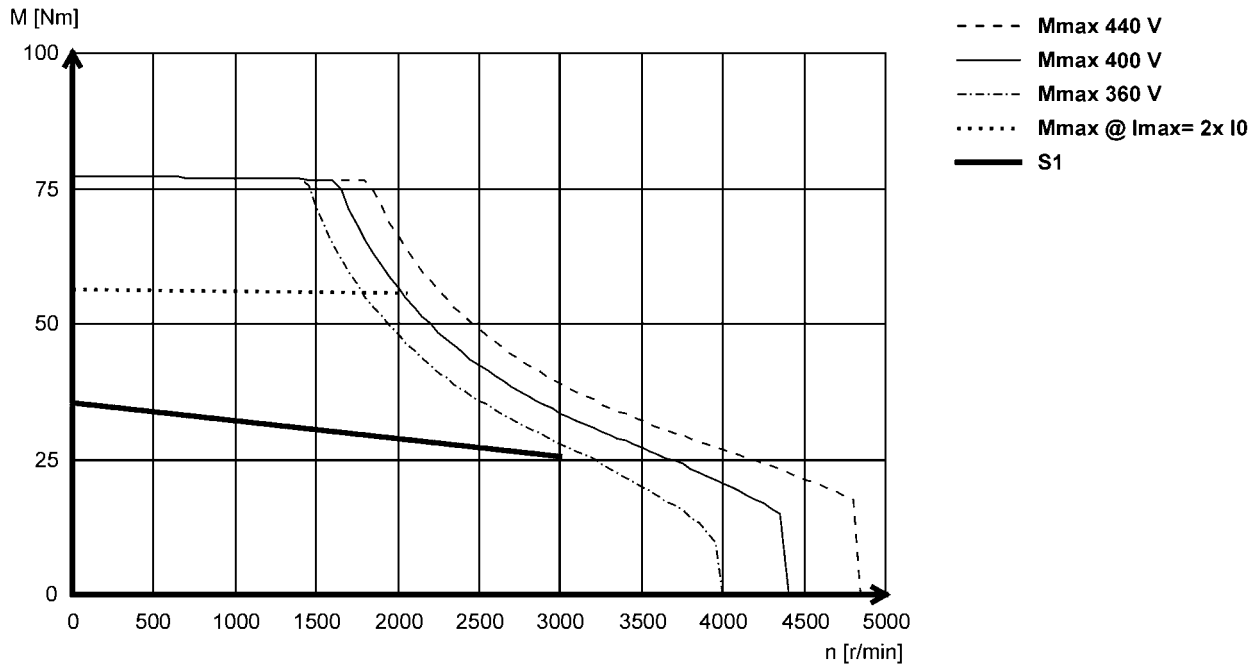
Technical data



Torque characteristics

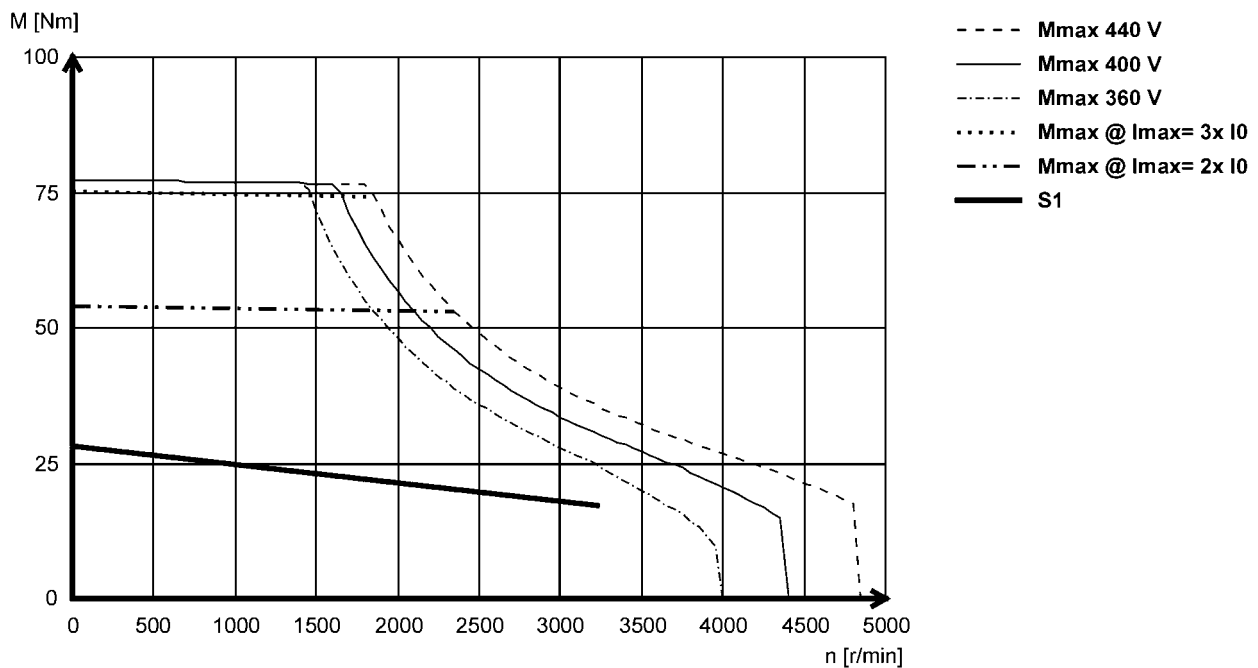
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14L30- (forced ventilated)



5.1

MCS14L32- (non-ventilated)



MCS synchronous servo motors

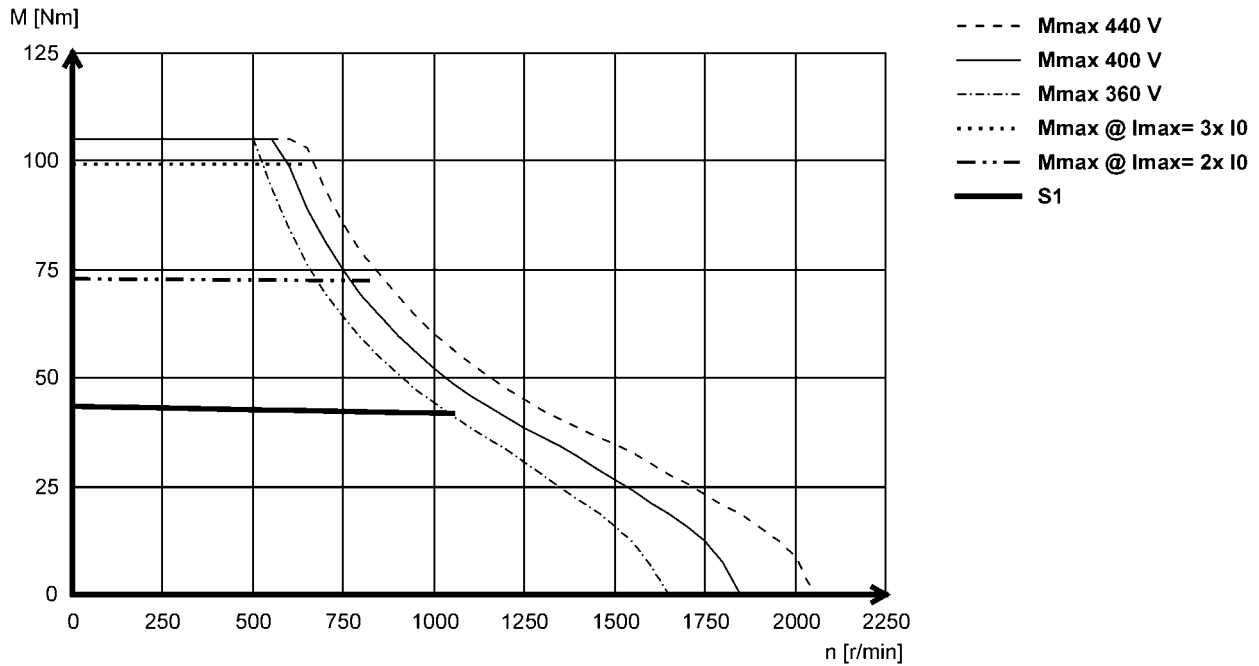
Technical data



Torque characteristics

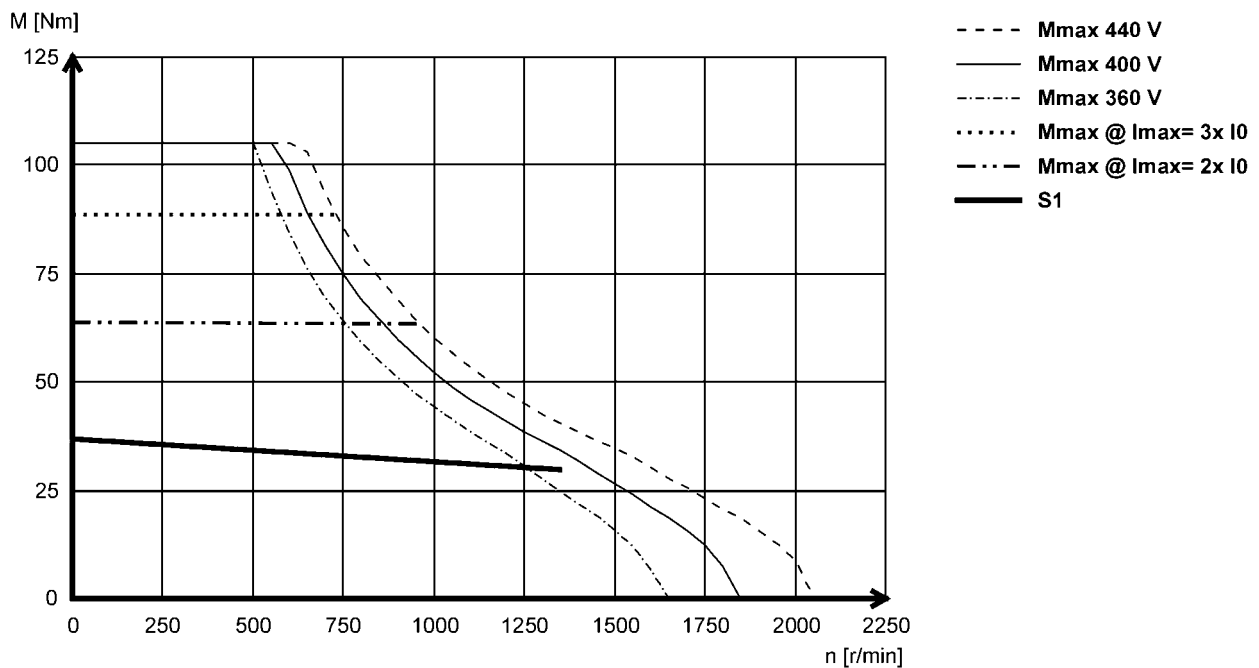
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14P11- (forced ventilated)



5.1

MCS14P14- (non-ventilated)



MCS synchronous servo motors

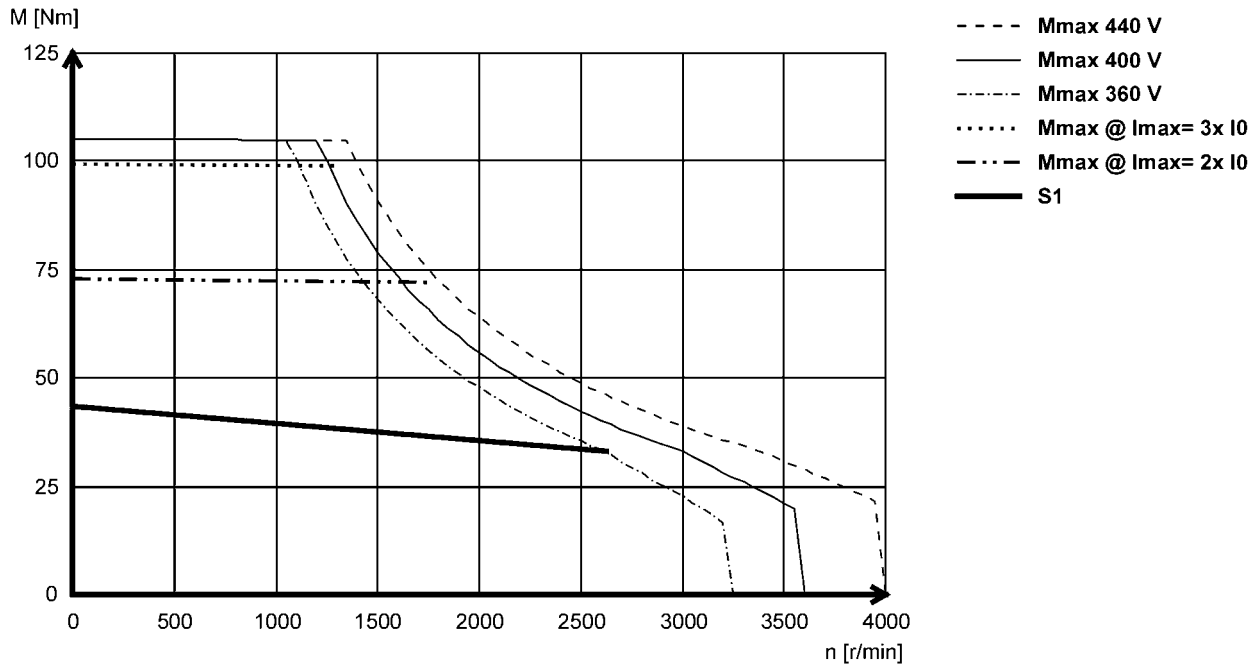
Technical data



Torque characteristics

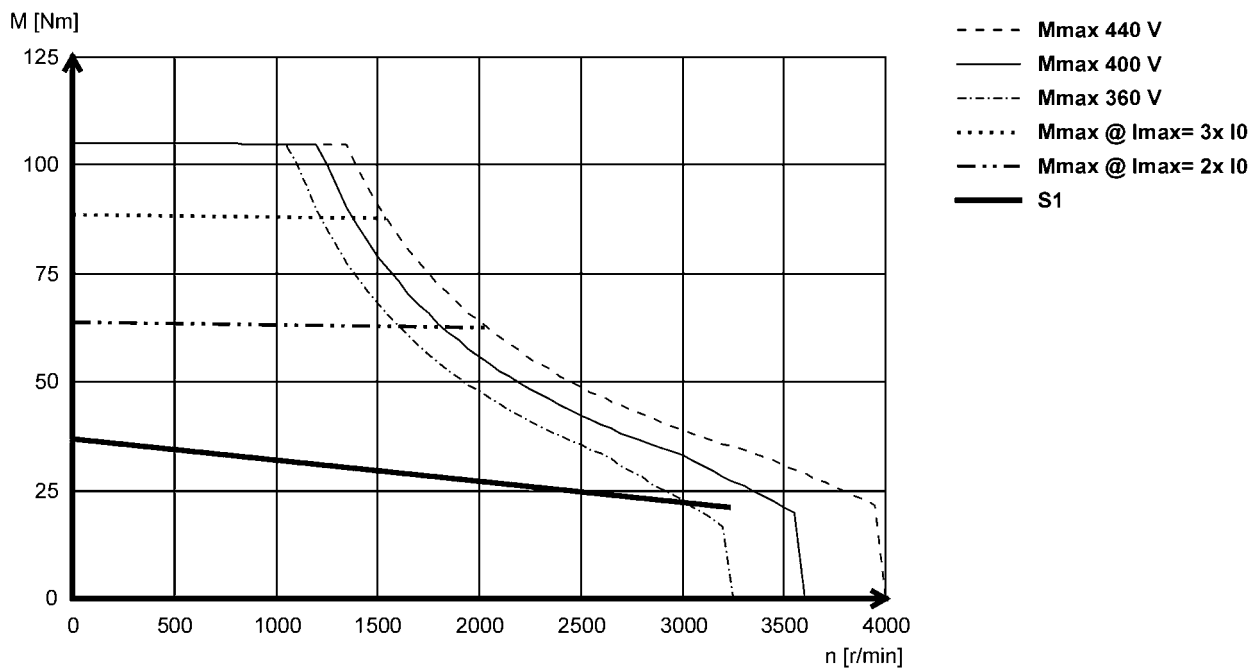
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS14P26- (forced ventilated)



5.1

MCS14P32- (non-ventilated)



MCS synchronous servo motors

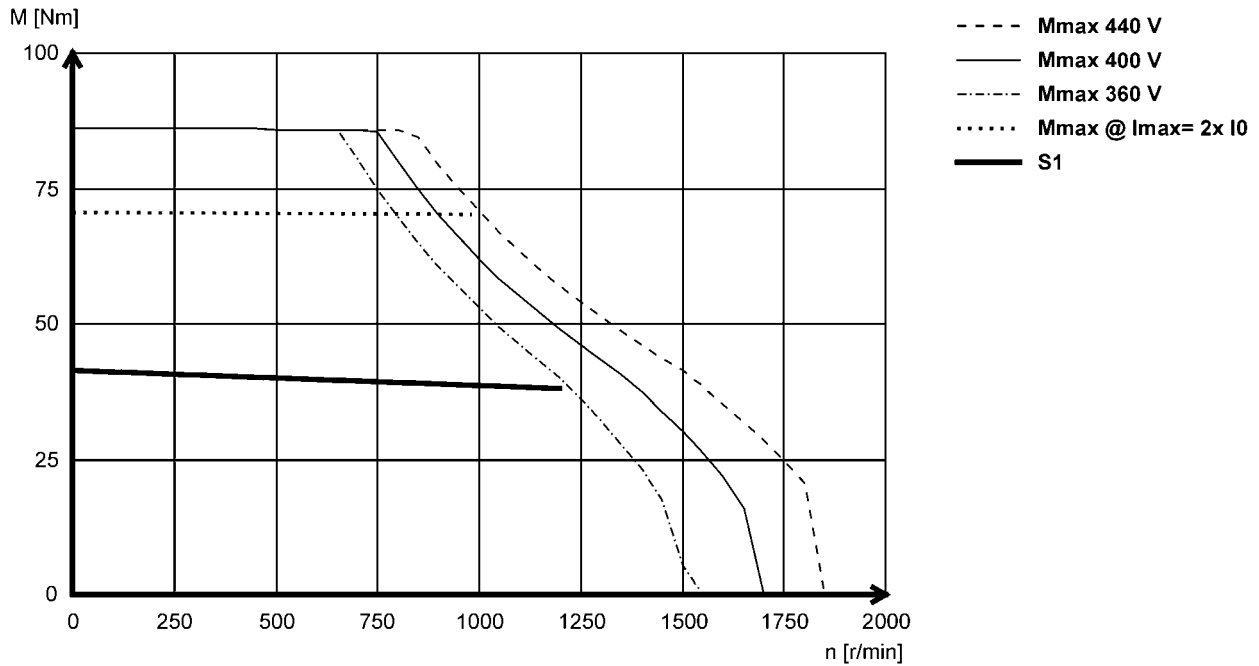
Technical data



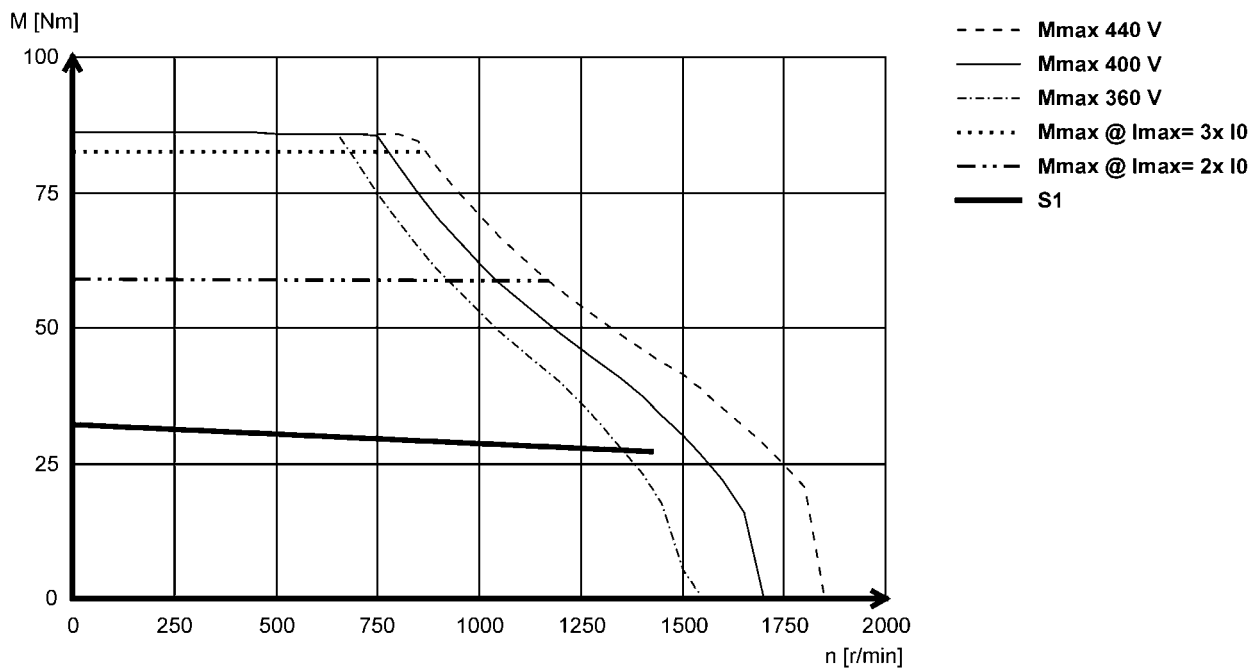
Torque characteristics

- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS19F12- (forced ventilated)



MCS19F14- (non-ventilated)



MCS synchronous servo motors

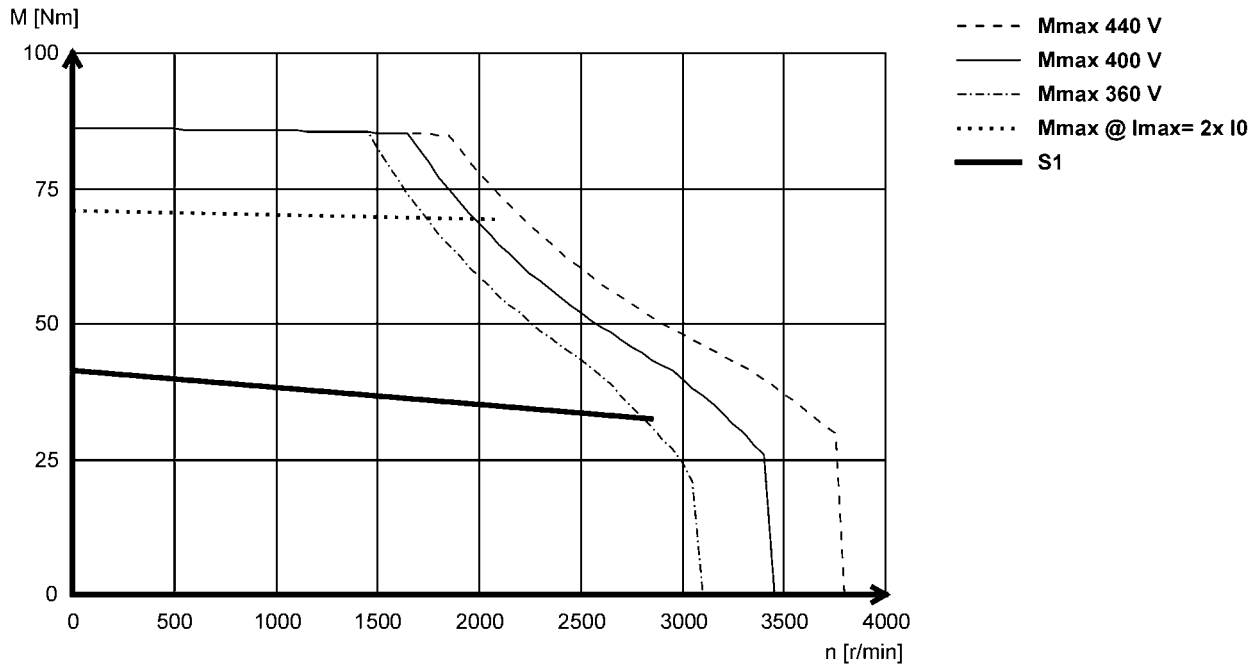
Technical data



Torque characteristics

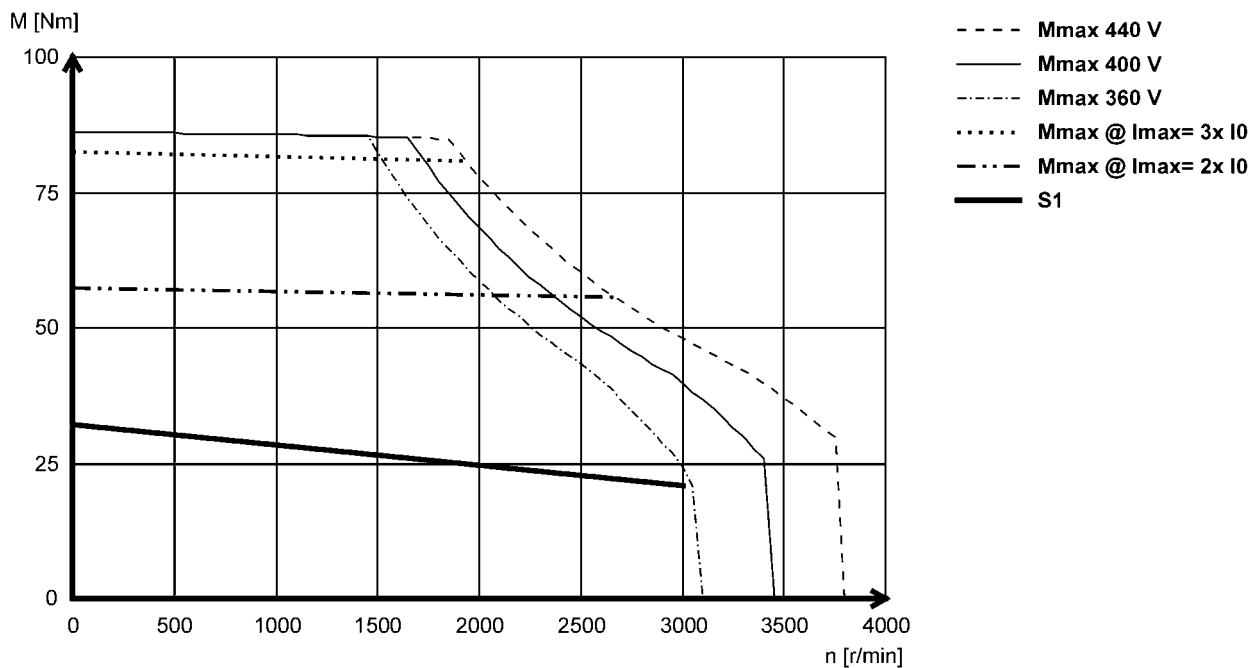
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS19F29- (forced ventilated)



5.1

MCS19F30- (non-ventilated)



MCS synchronous servo motors

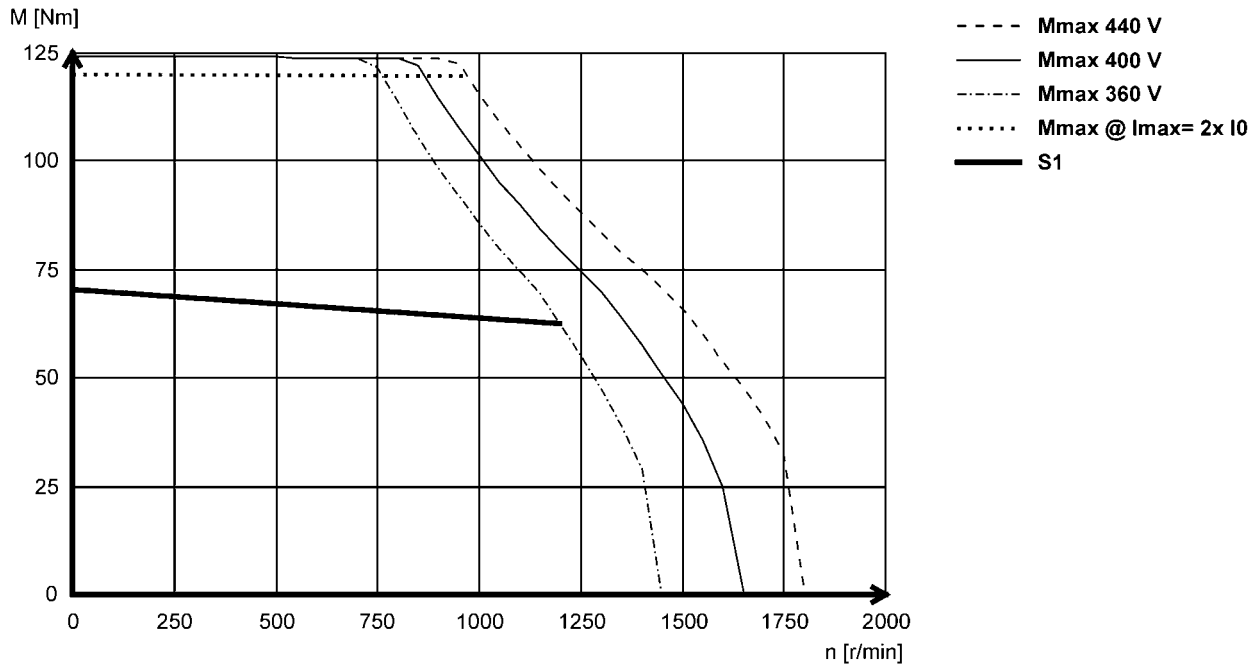
Technical data



Torque characteristics

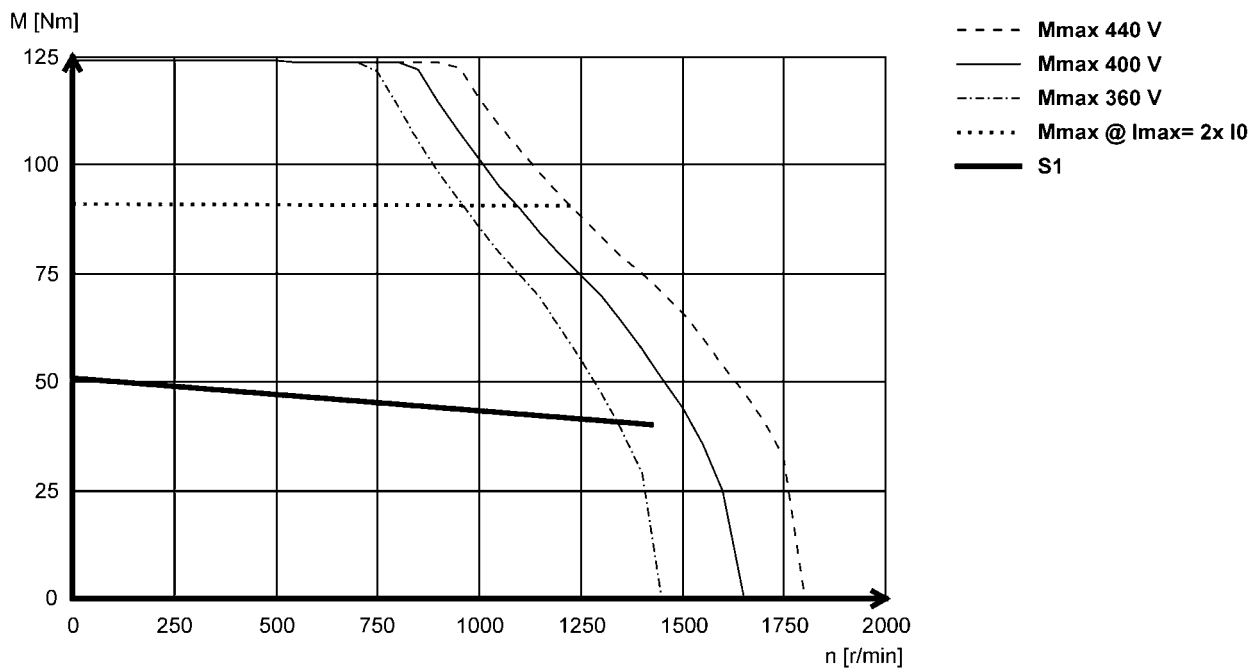
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS19J12- (forced ventilated)



5.1

MCS19J14- (non-ventilated)



MCS synchronous servo motors

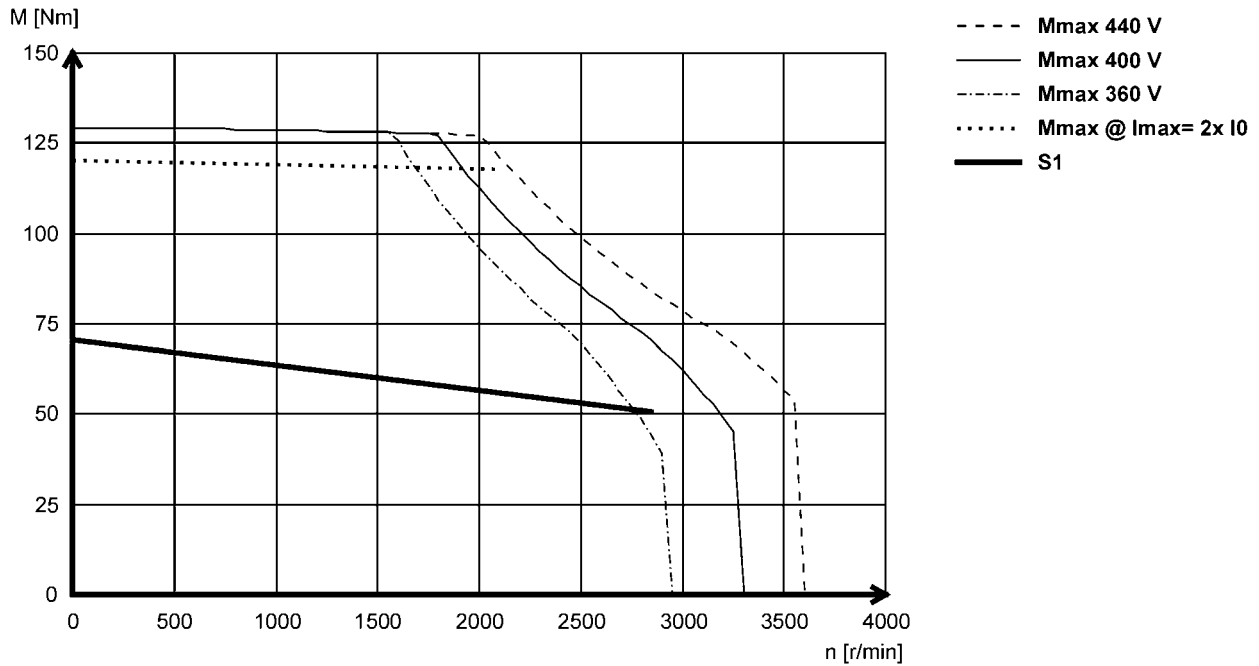
Technical data



Torque characteristics

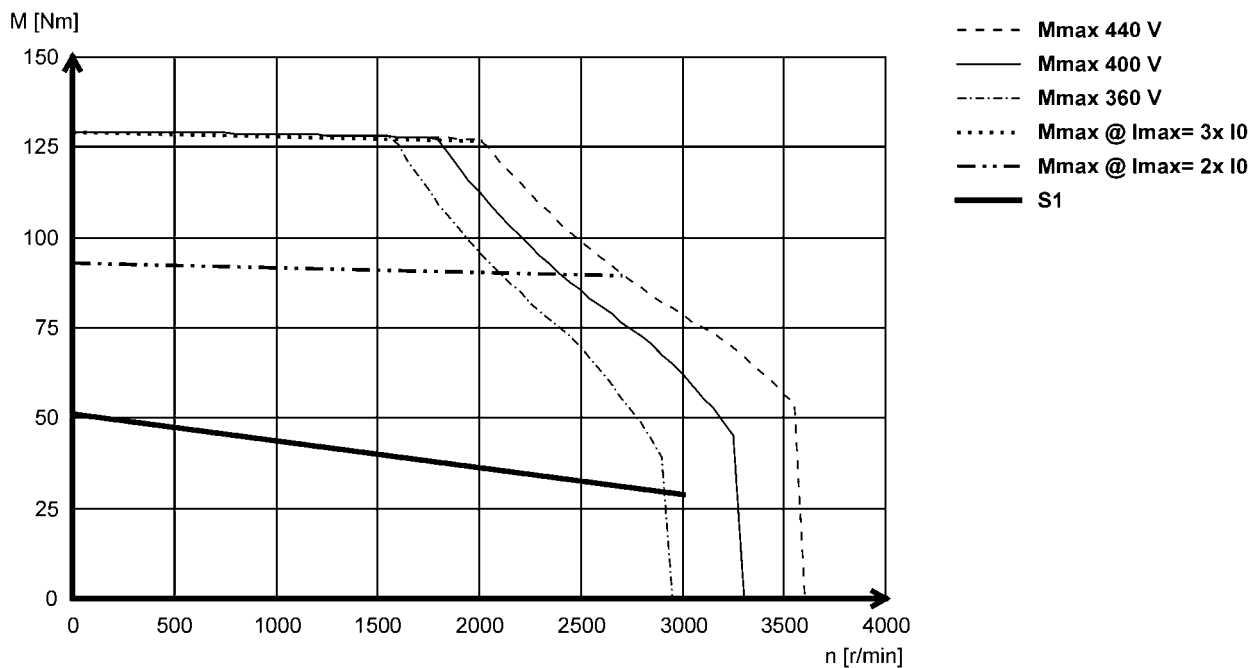
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS19J29- (forced ventilated)



5.1

MCS19J30- (non-ventilated)



MCS synchronous servo motors

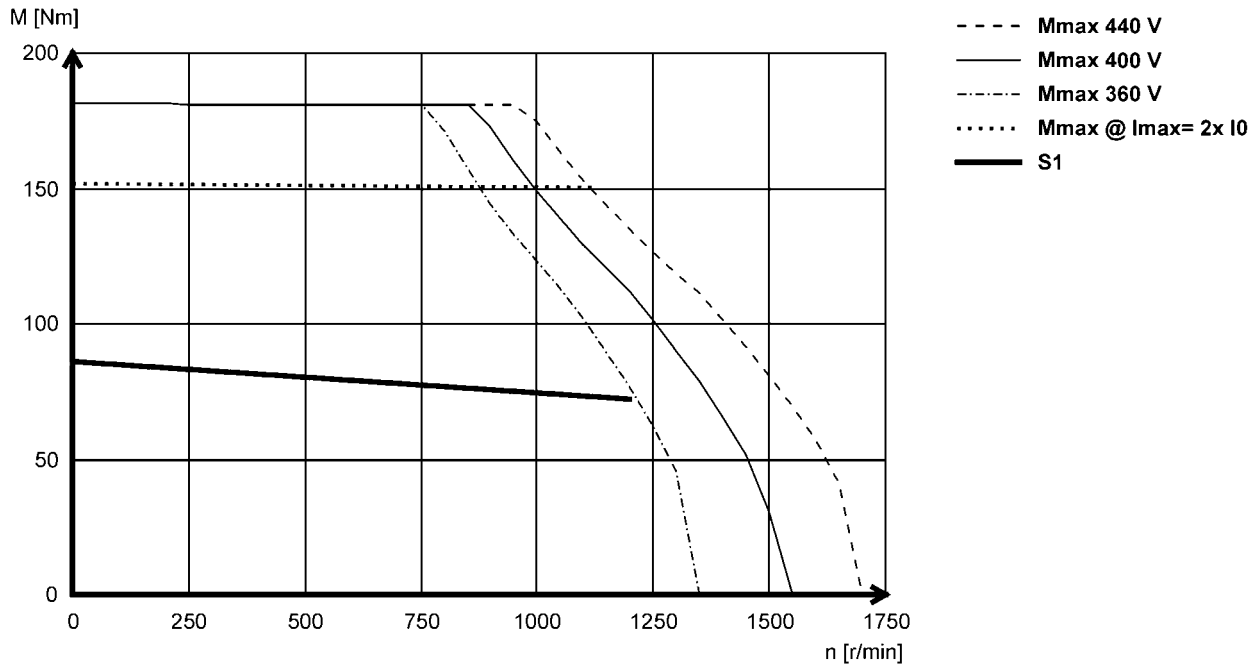
Technical data



Torque characteristics

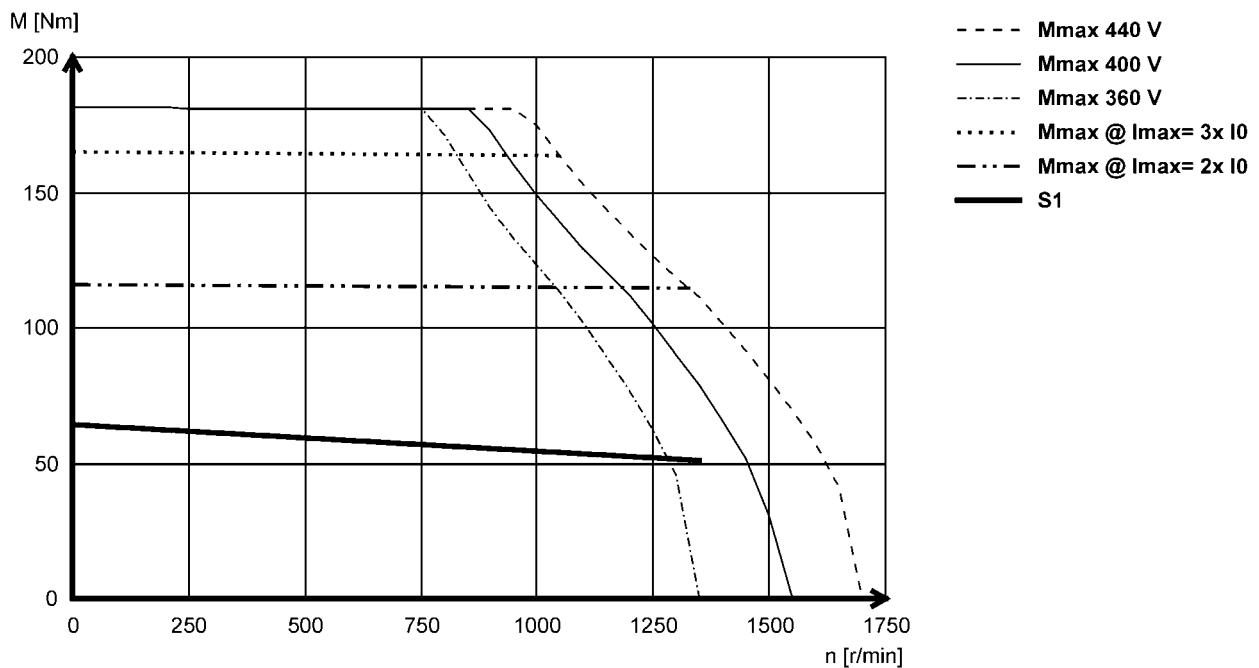
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS19P12 (forced ventilated)



5.1

MCS19P14- (non-ventilated)



MCS synchronous servo motors

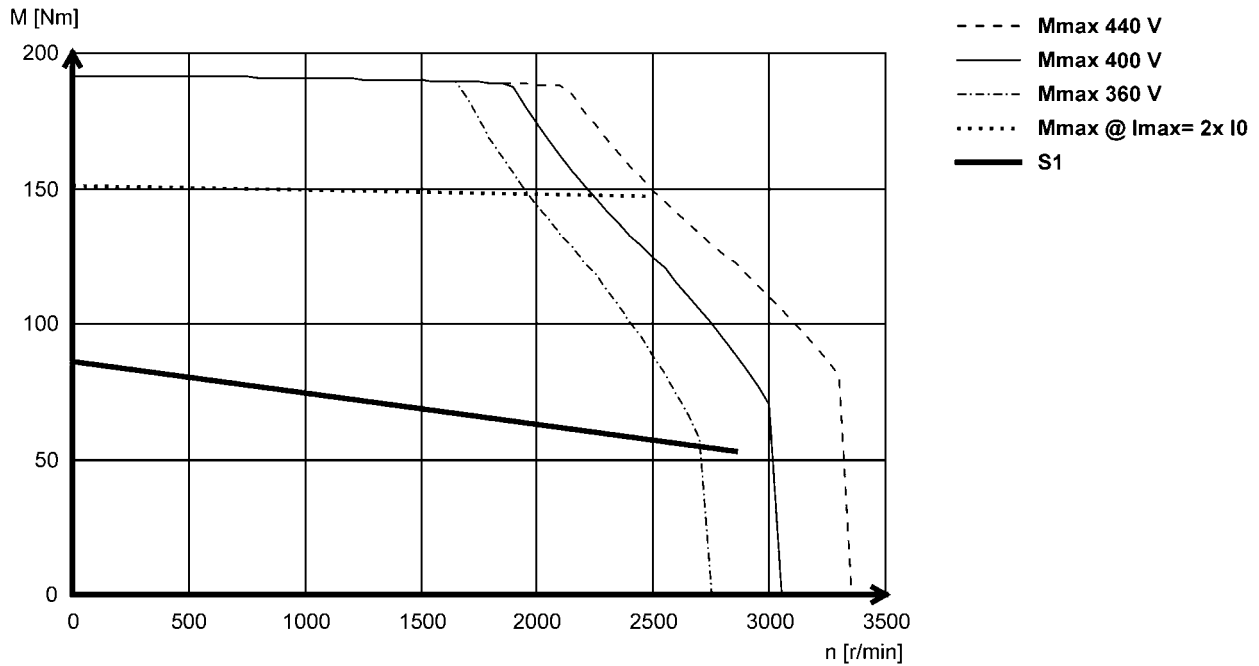
Technical data



Torque characteristics

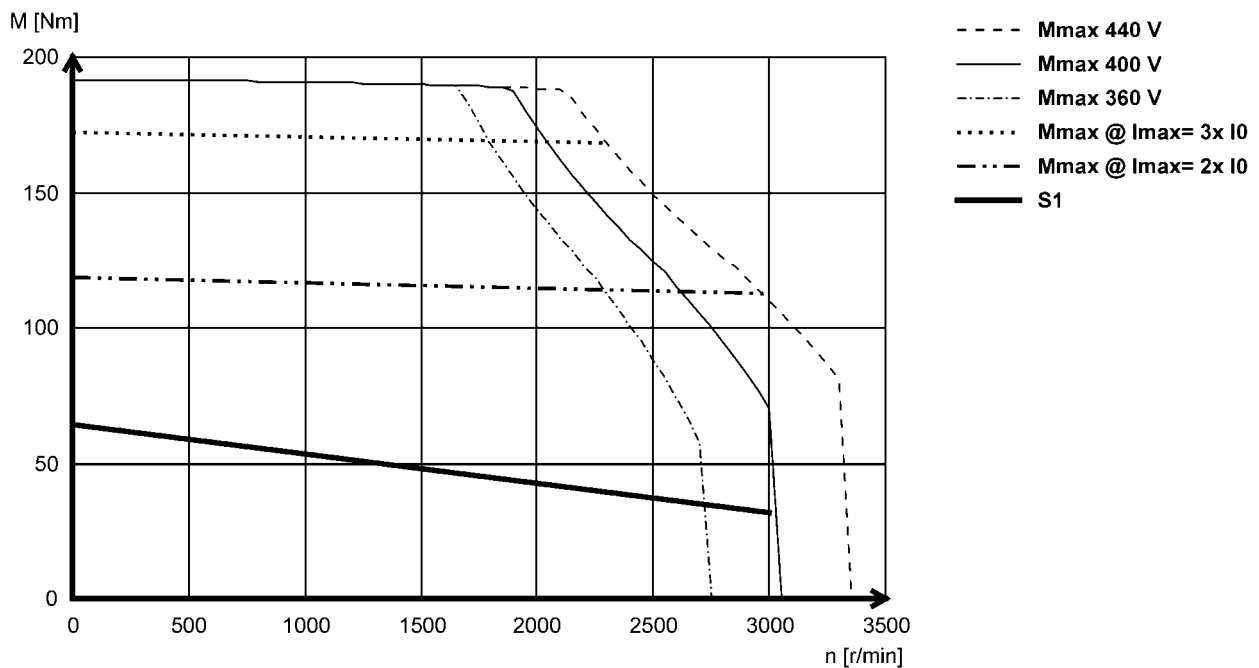
- ▶ The data applies to a mains connection voltage of 3 x 400 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS19P29- (forced ventilated)



5.1

MCS19P30- (non-ventilated)



MCS synchronous servo motors

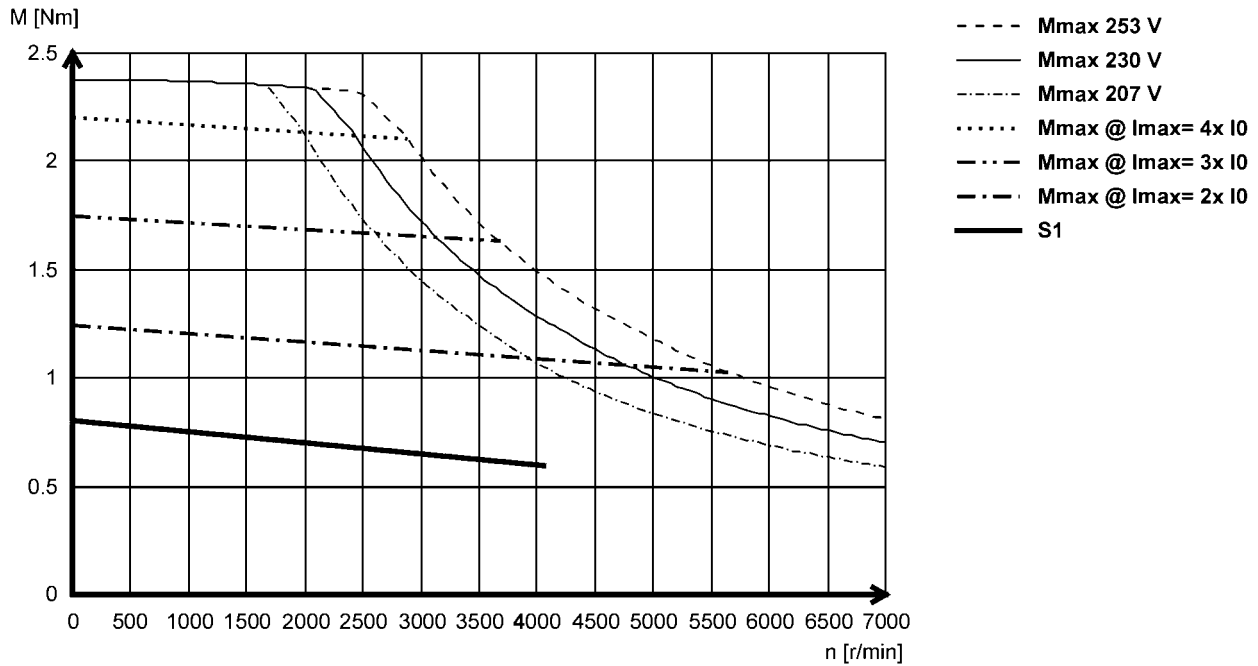
Technical data



Torque characteristics

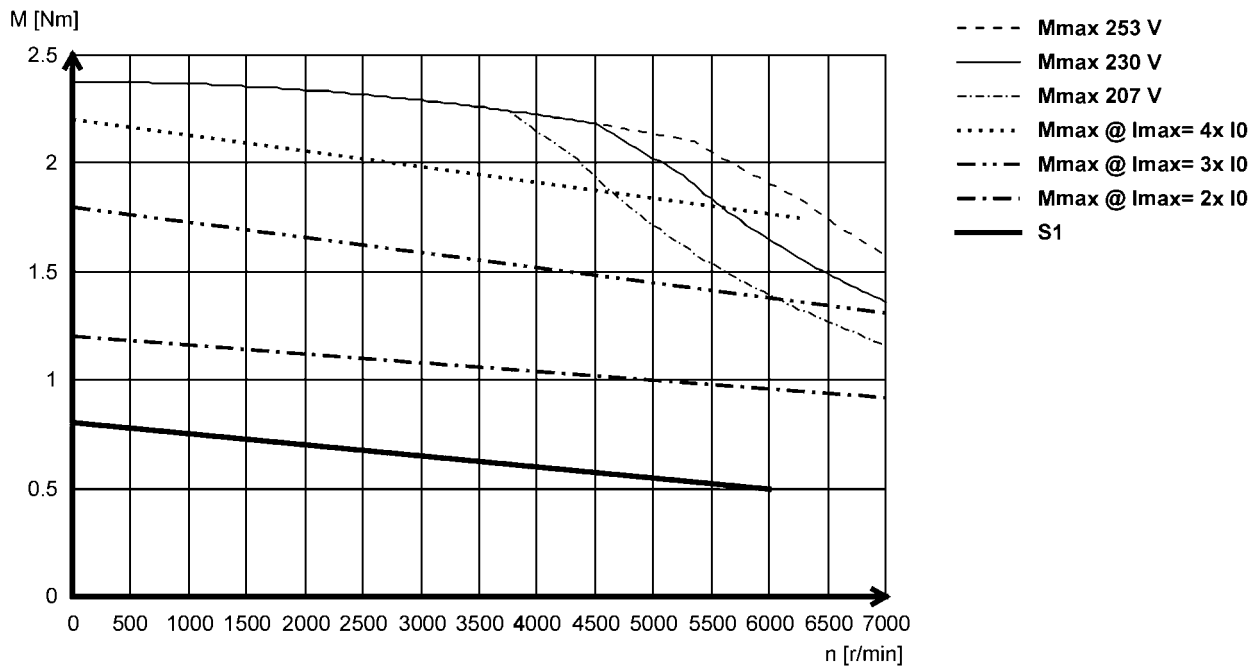
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS06C41L (non-ventilated)



5.1

MCS06C60L (non-ventilated)



MCS synchronous servo motors

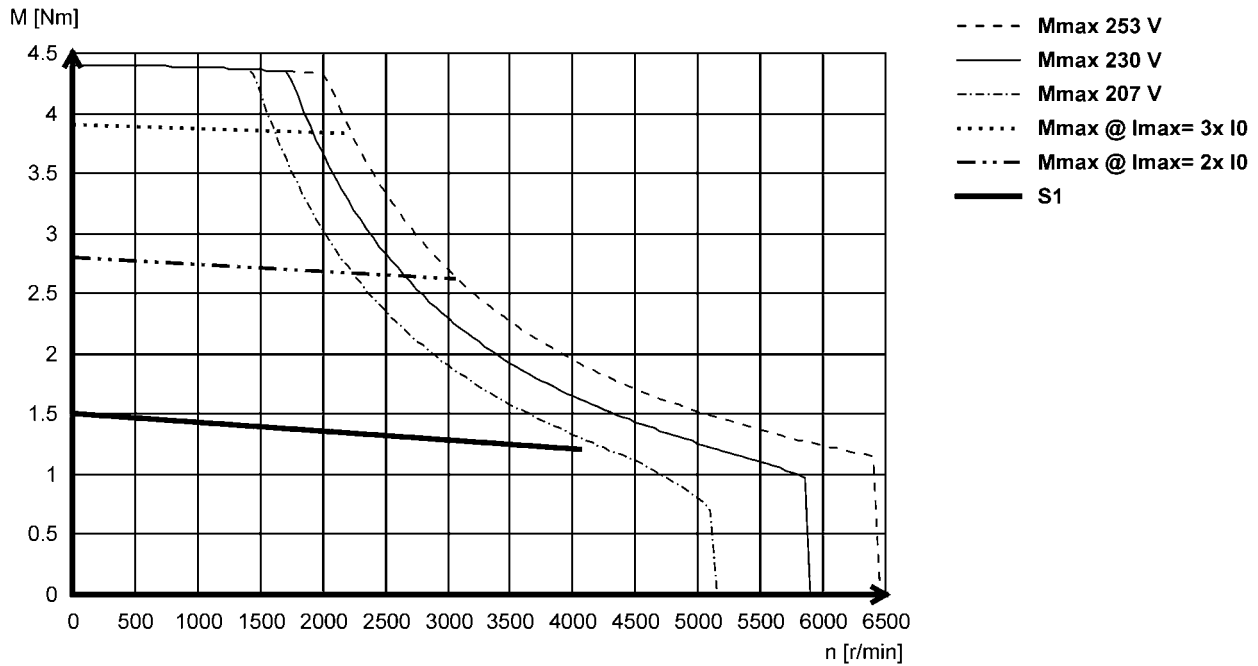
Technical data



Torque characteristics

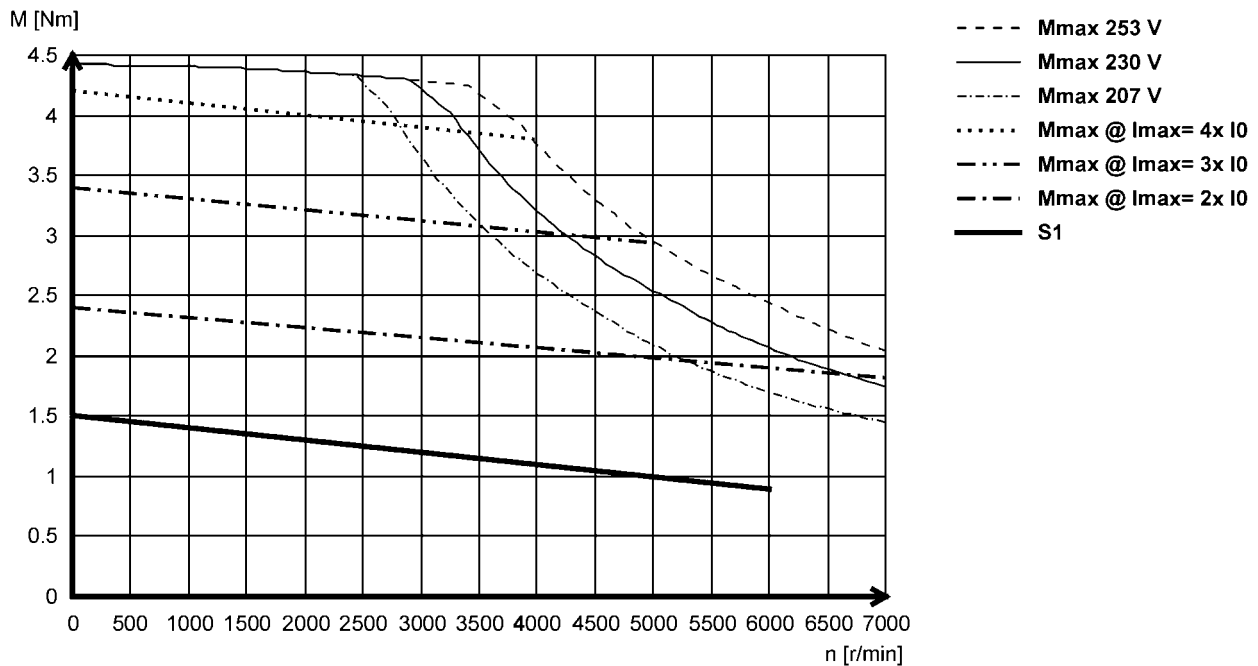
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS06F41L (non-ventilated)



5.1

MCS06F60L (non-ventilated)



MCS synchronous servo motors

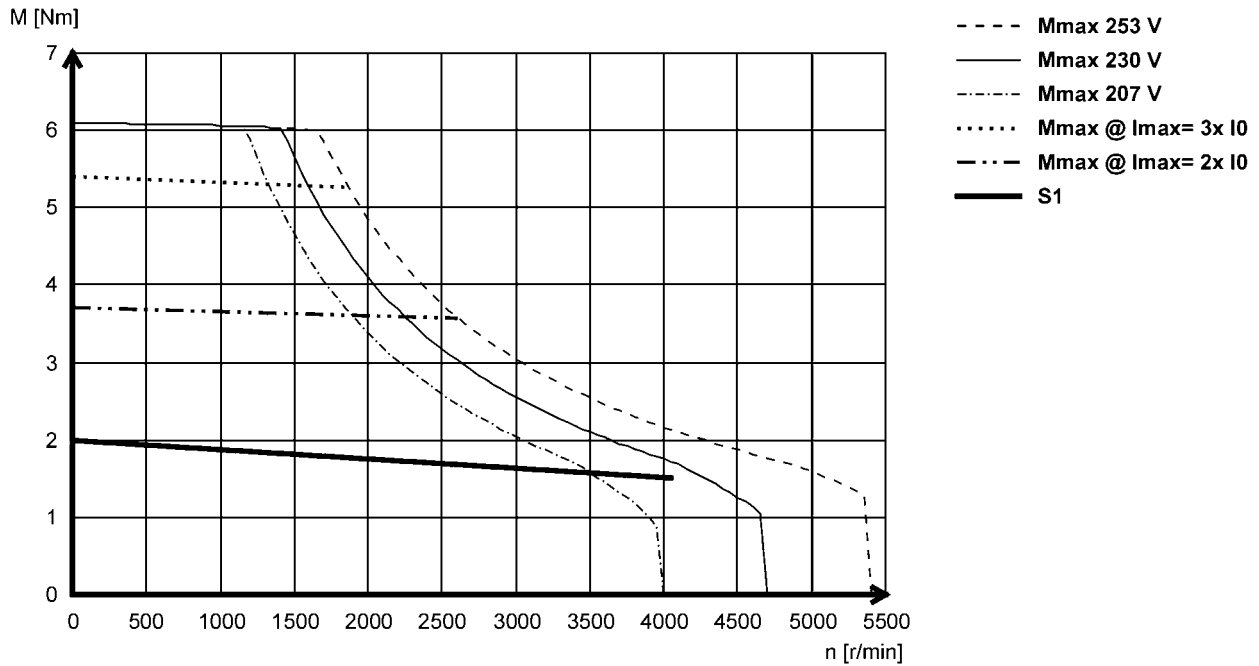
Technical data



Torque characteristics

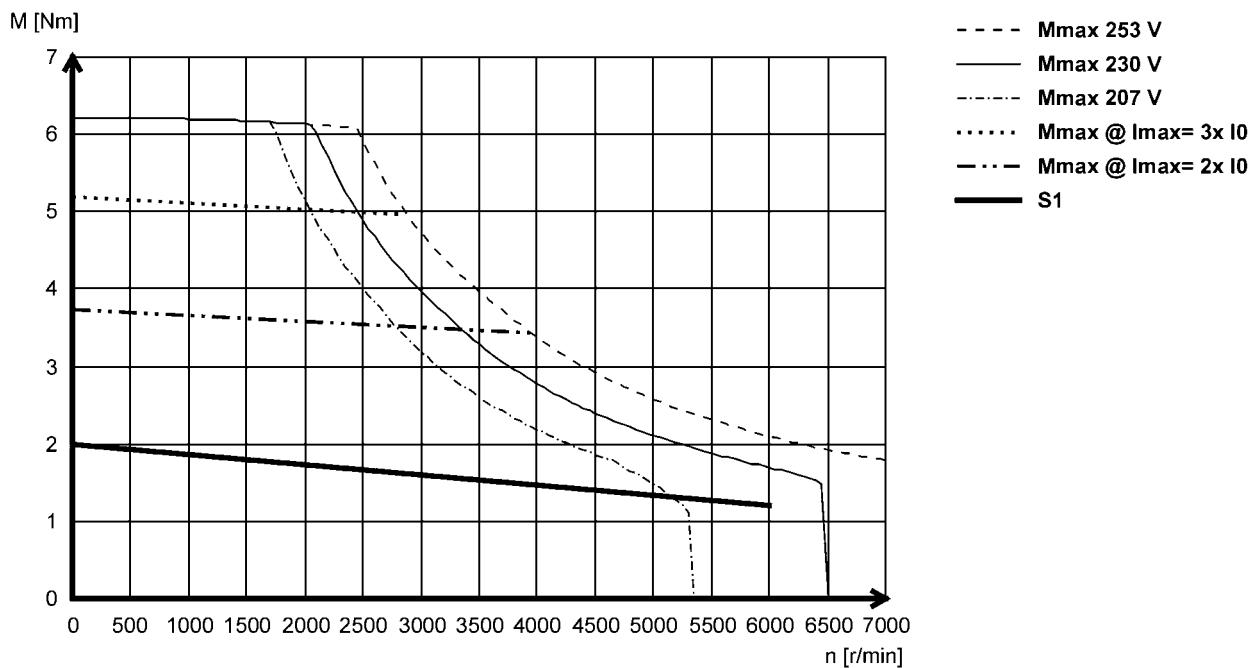
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS06I41L (non-ventilated)



5.1

MCS06I60L (non-ventilated)



MCS synchronous servo motors

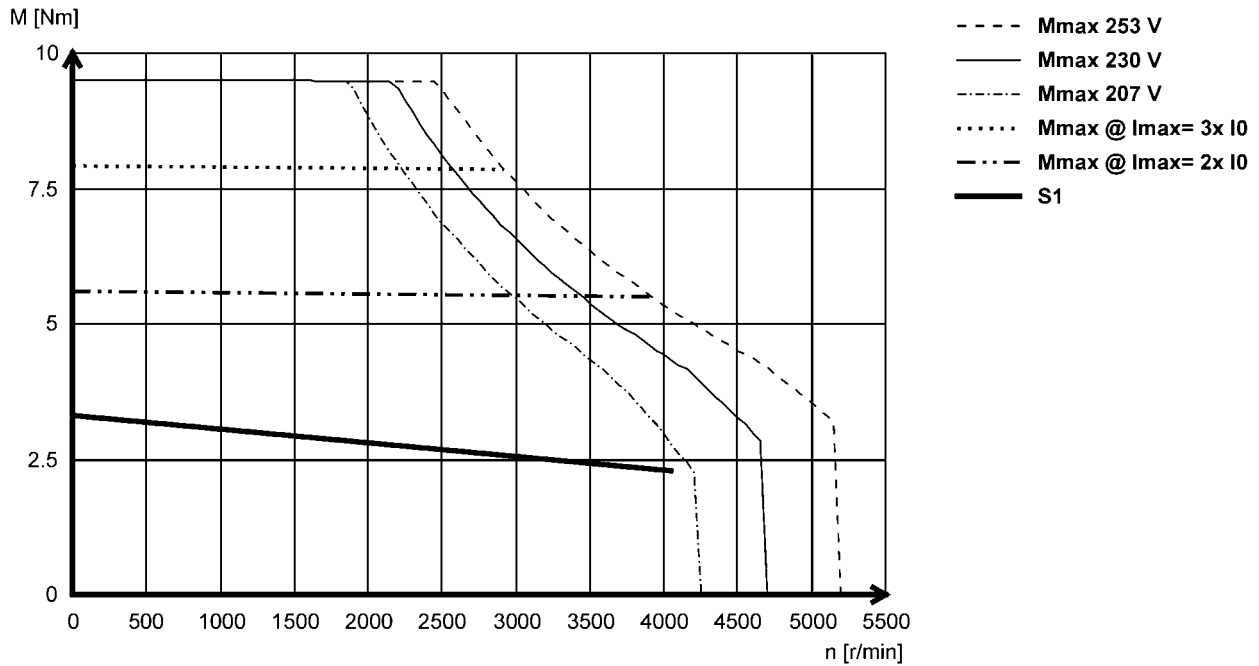
Technical data



Torque characteristics

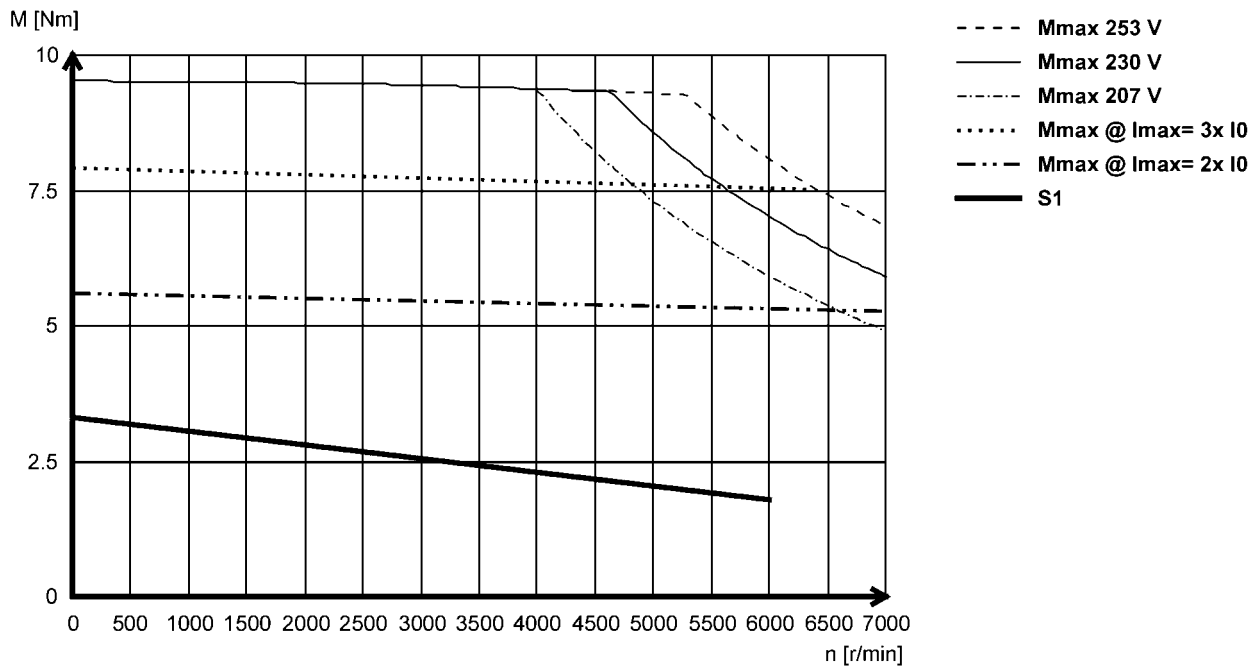
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09D41L (non-ventilated)



5.1

MCS09D60L (non-ventilated)



MCS synchronous servo motors

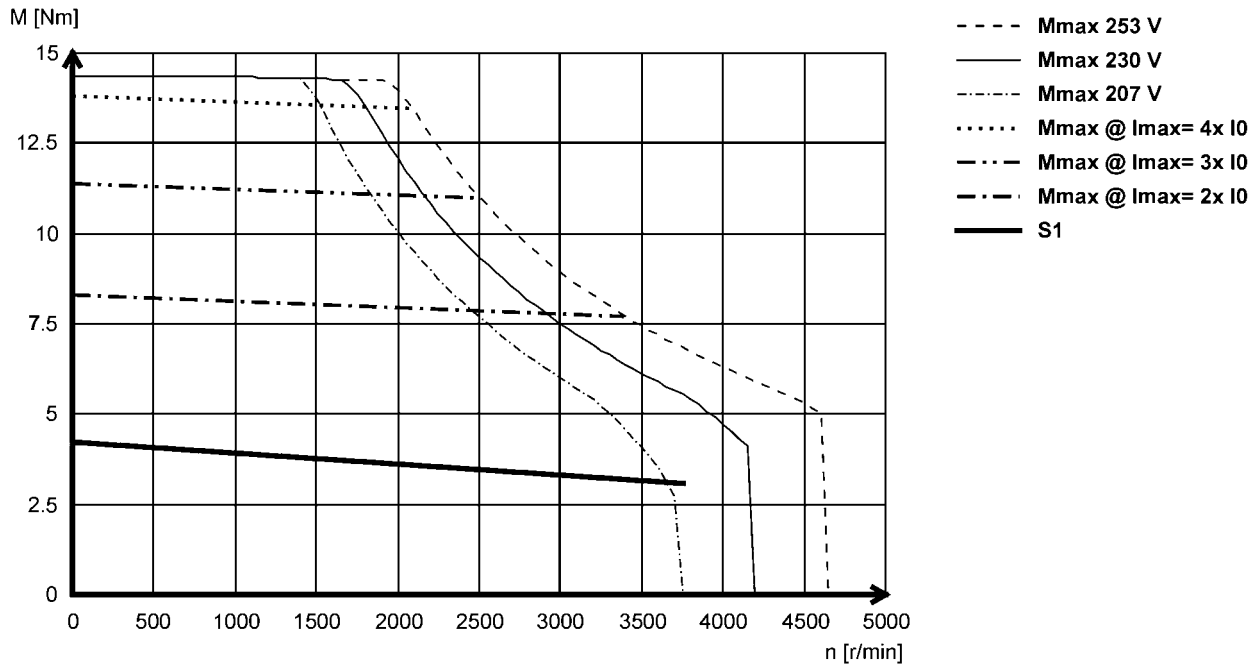
Technical data



Torque characteristics

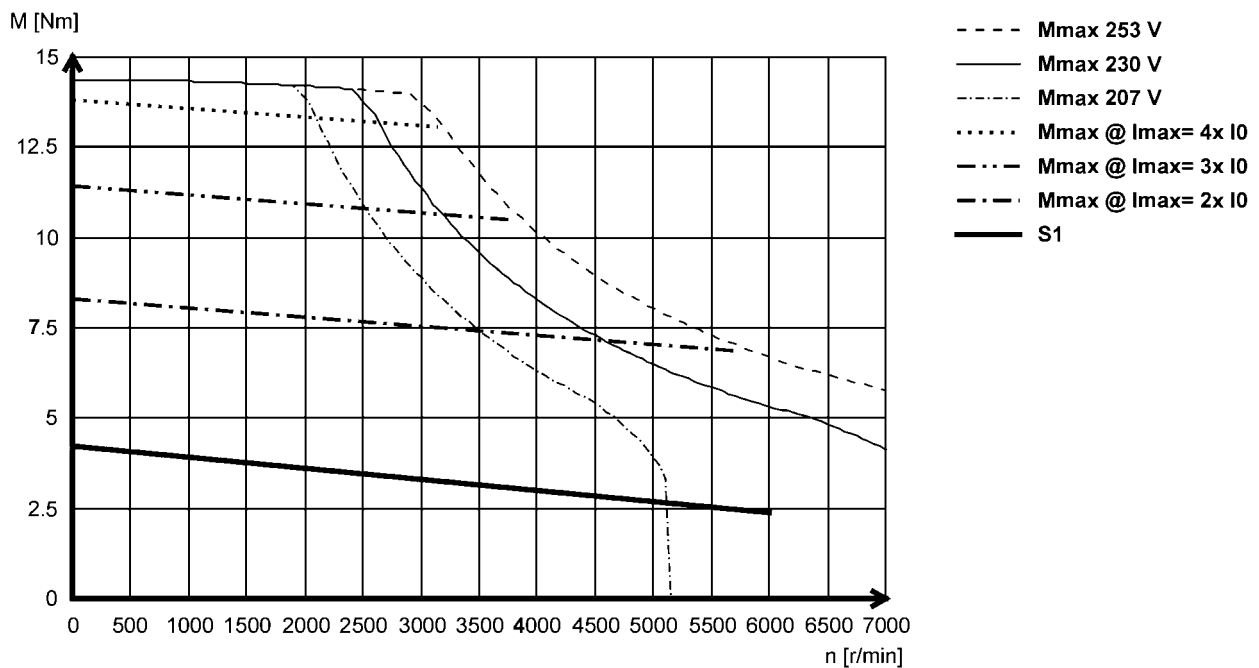
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09F38L (non-ventilated)



5.1

MCS09F60L (non-ventilated)



MCS synchronous servo motors

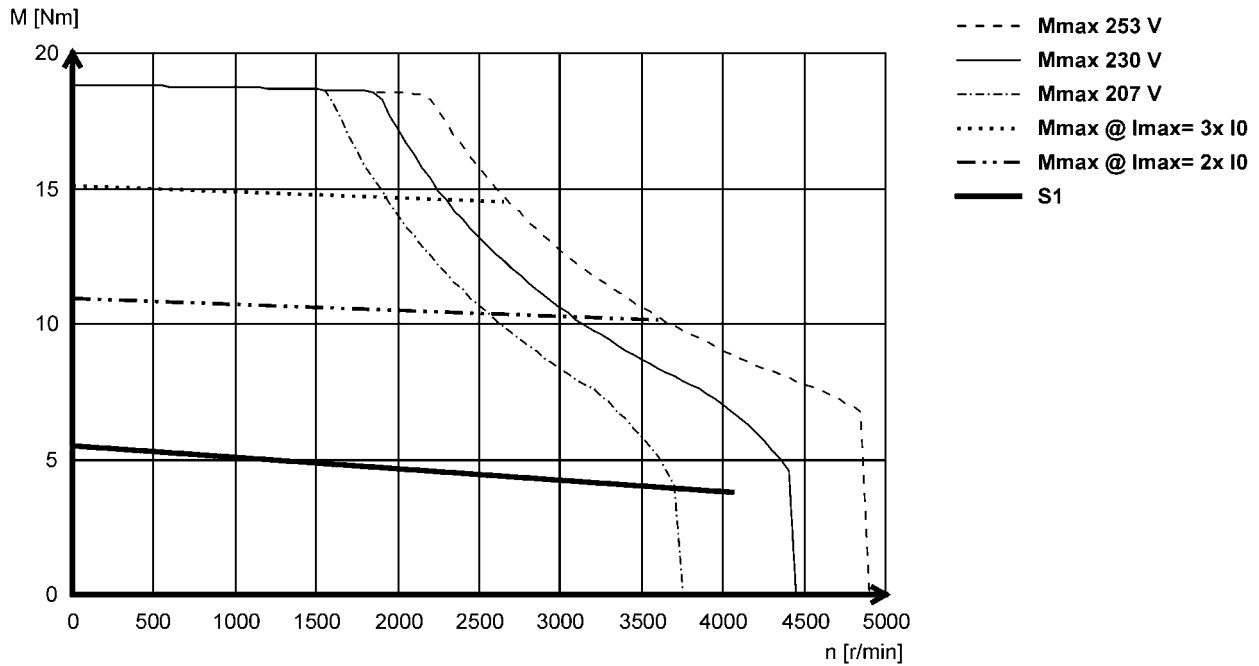
Technical data



Torque characteristics

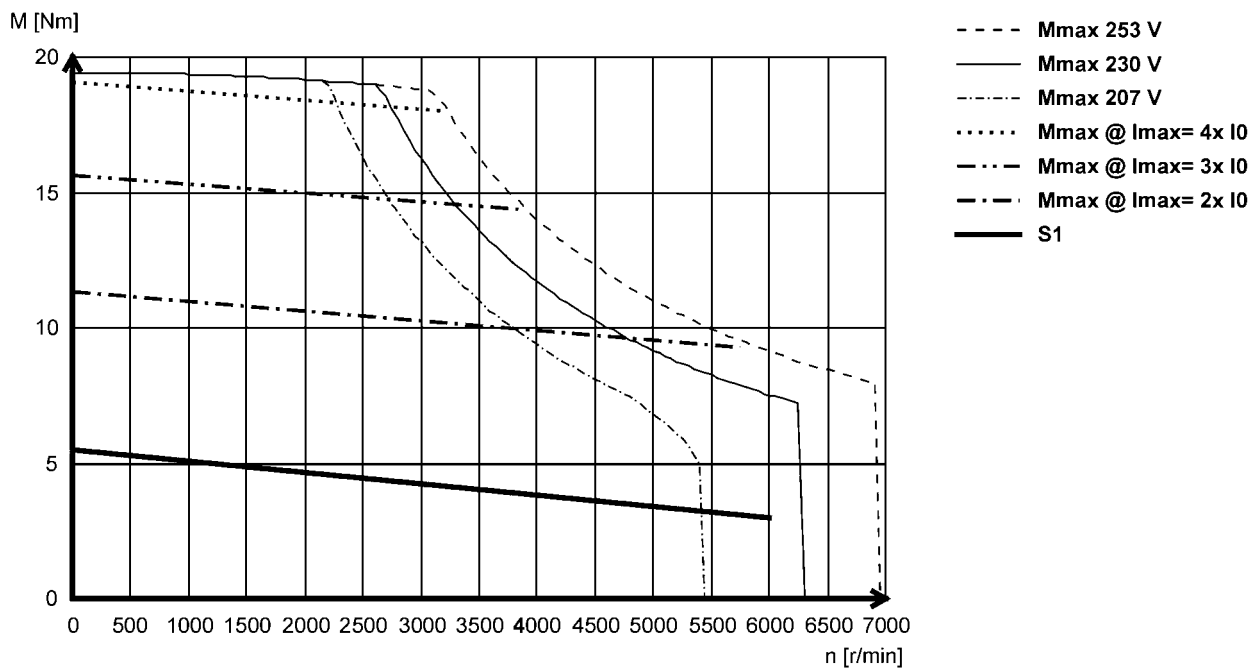
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09H41L (non-ventilated)



5.1

MCS09H60L (non-ventilated)



MCS synchronous servo motors

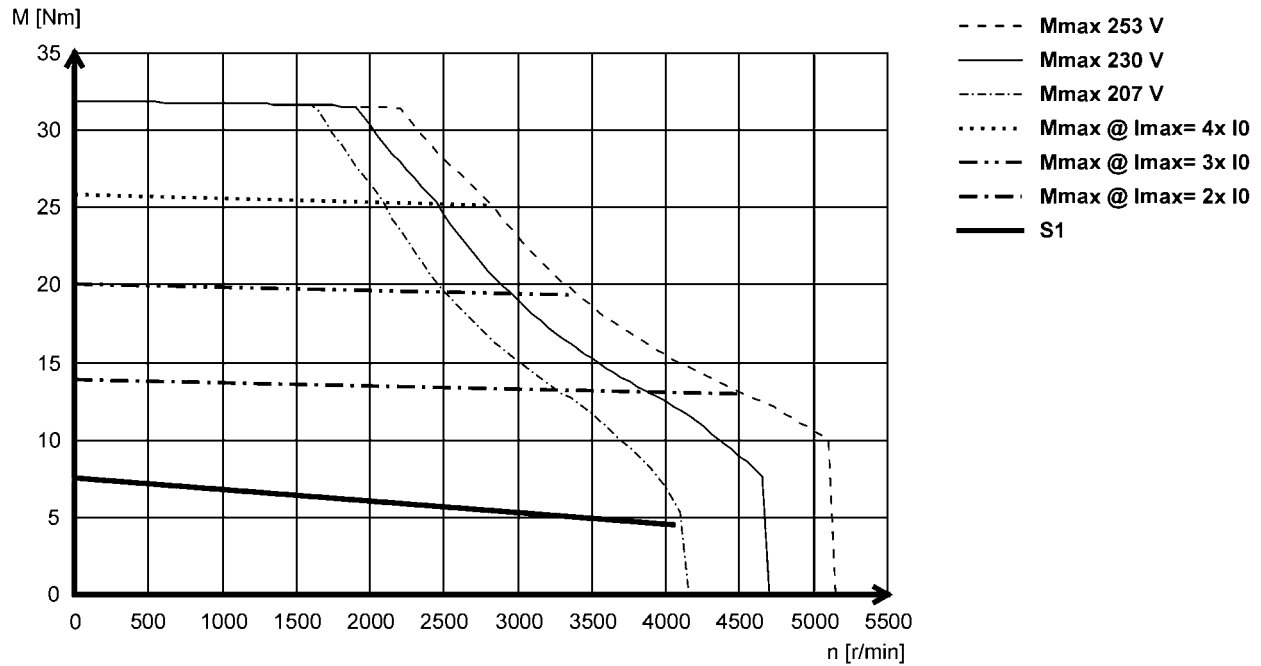
Technical data



Torque characteristics

- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS09L41L (non-ventilated)



5.1

MCS synchronous servo motors

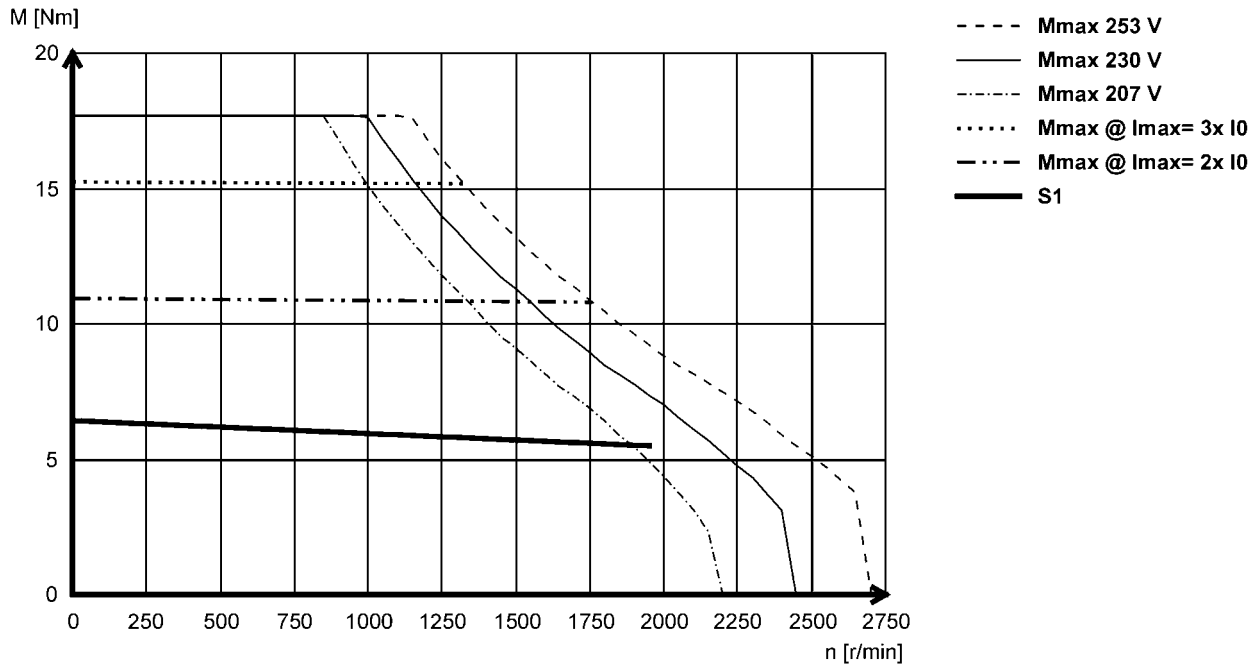
Technical data



Torque characteristics

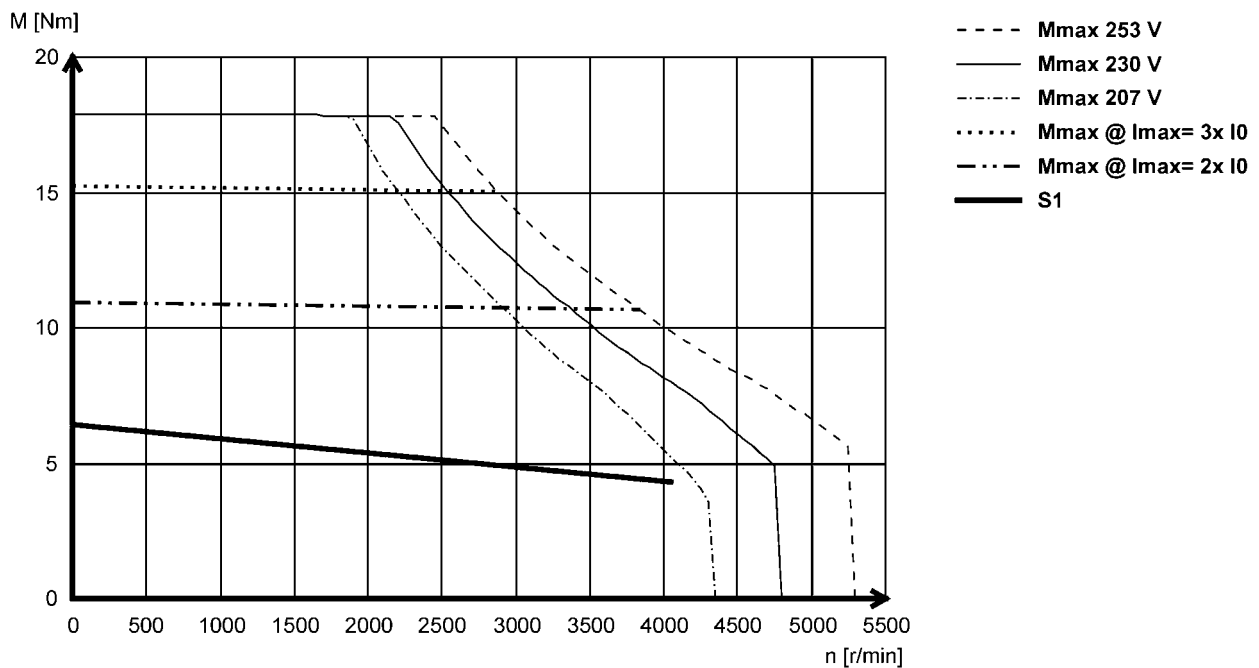
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12D20L (non-ventilated)



5.1

MCS12D41L (non-ventilated)



MCS synchronous servo motors

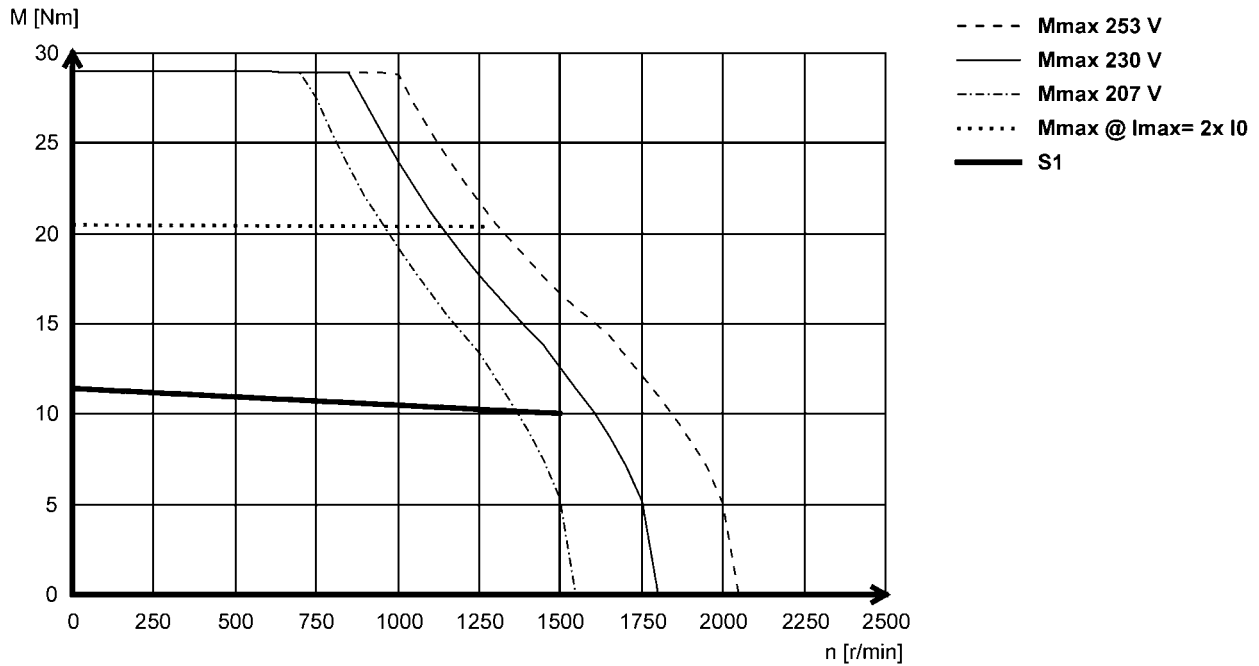
Technical data



Torque characteristics

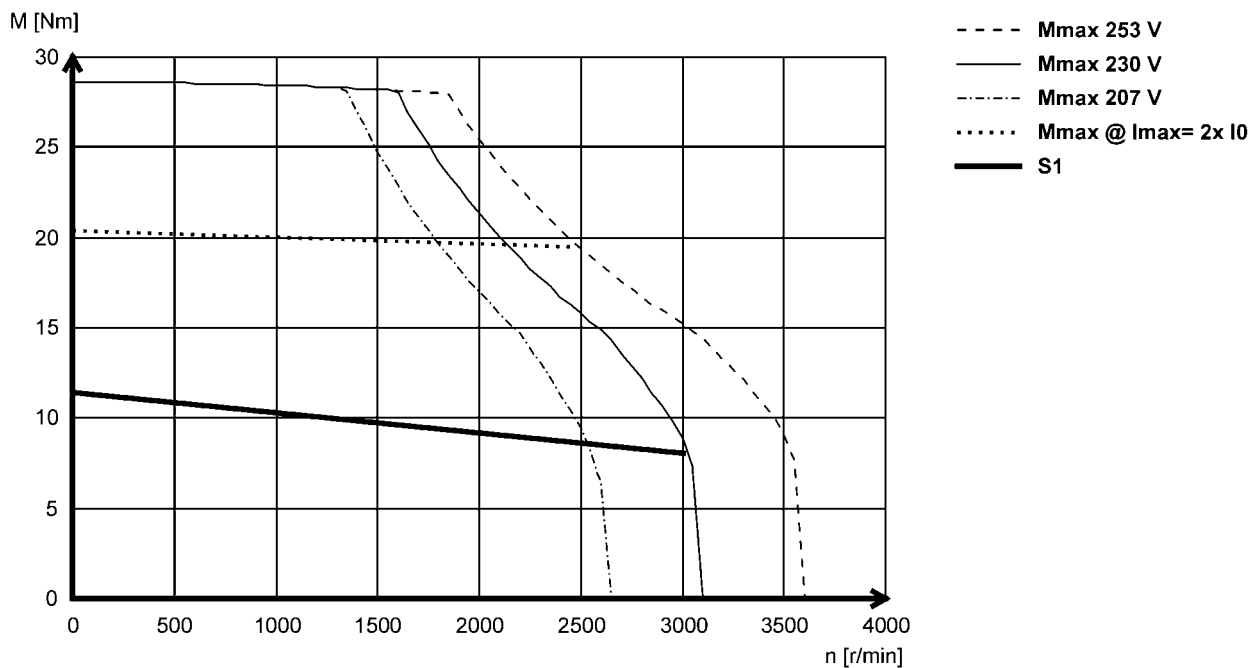
- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12H15L (non-ventilated)



5.1

MCS12H30L- (non-ventilated)



MCS synchronous servo motors

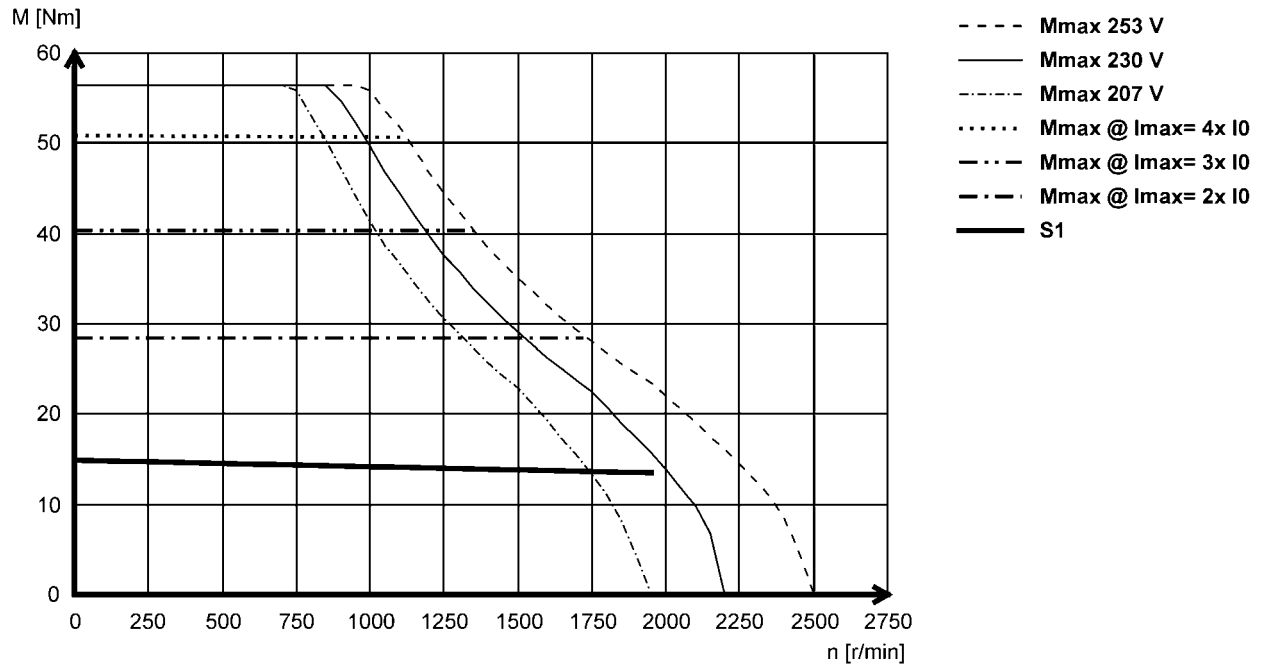
Technical data



Torque characteristics

- ▶ The data applies to a mains connection voltage of 3 x 230 V.
- ▶ You can find further torque characteristics at www.lenze.de/dsc.

MCS12L20L (non-ventilated)

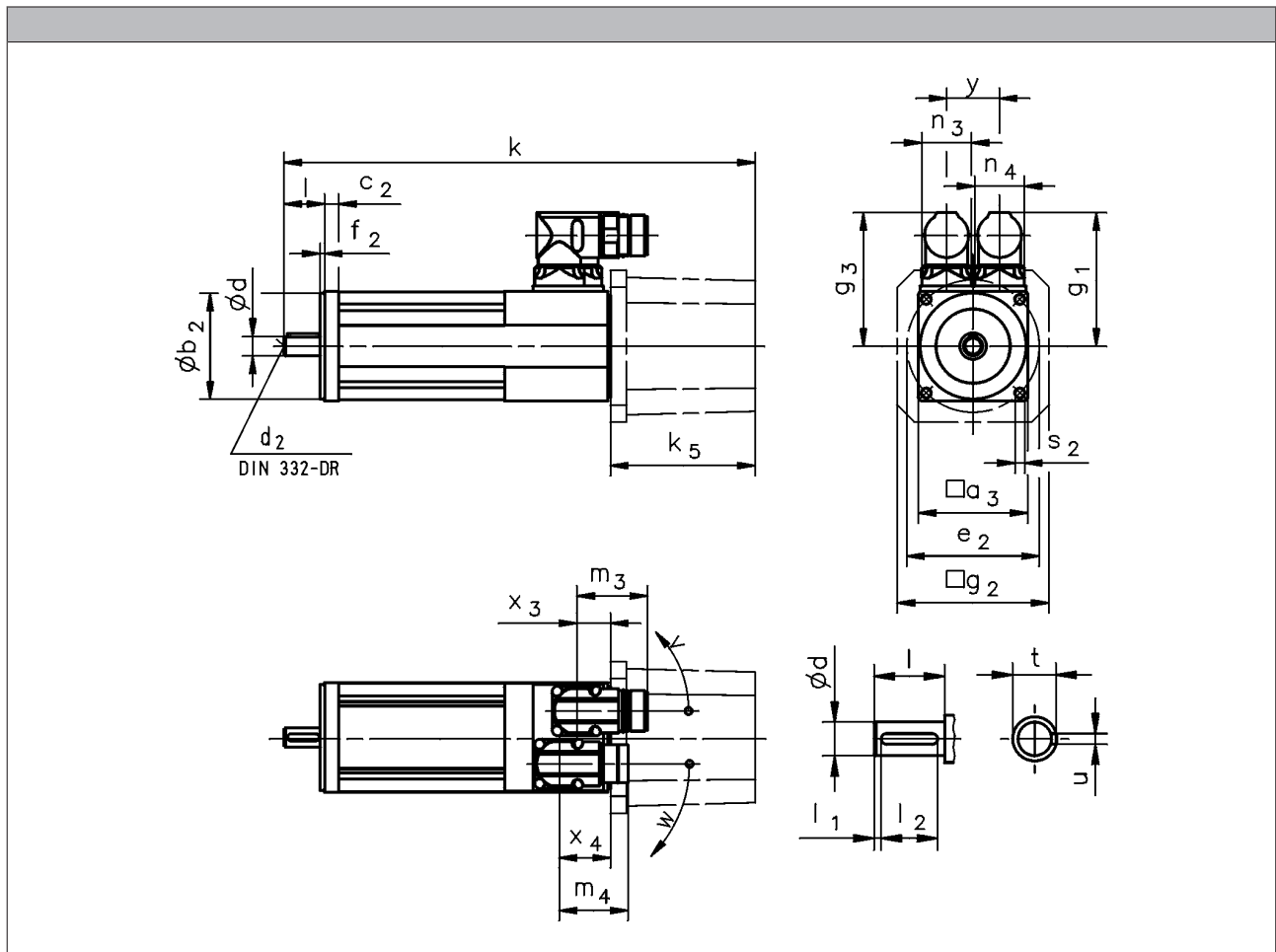


MCS synchronous servo motors

Technical data



Dimensions, self-ventilated



5.1

			MCS06C	MCS06F	MCS06I
R□□ / C40 B0	k	[mm]	155	185	215
R□□ / C40 P□	k	[mm]	174	204	233
SR□ / SV□ / E□□ B0	k	[mm]	237	266	297
SR□ / SV□ / E□□ P□	k	[mm]	255	285	315
SR□ / SV□ / E□□	k_5	[mm]		82.0	
	g_2	[mm]		86.0	
SKM B0	k	[mm]	190	220	250
SKM P□	k	[mm]	209	239	268
SKM	k_5	[mm]		35.0	
	g_2	[mm]		62.0	

- ▶ Speed / angle sensor: R□□ / C□□ / S□□ / E□□
- ▶ Brake: B0 / P□

MCS synchronous servo motors

Technical data



Dimensions, self-ventilated

	g ₁	g ₃	x ₃	x ₄	m ₃	m ₄	n ₃	n ₄	y	v	w
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]
MCS06	77	77	19	29	40	40	28	28	30	190	230

	d	d ₂	l	l ₁	l ₂	u	t
	k6		-0.7 ... 0.3				
	[mm]	[mm]		[mm]	[mm]	[mm]	[mm]
MCS06	11	M4	23	2.0	18	4.0	12.5

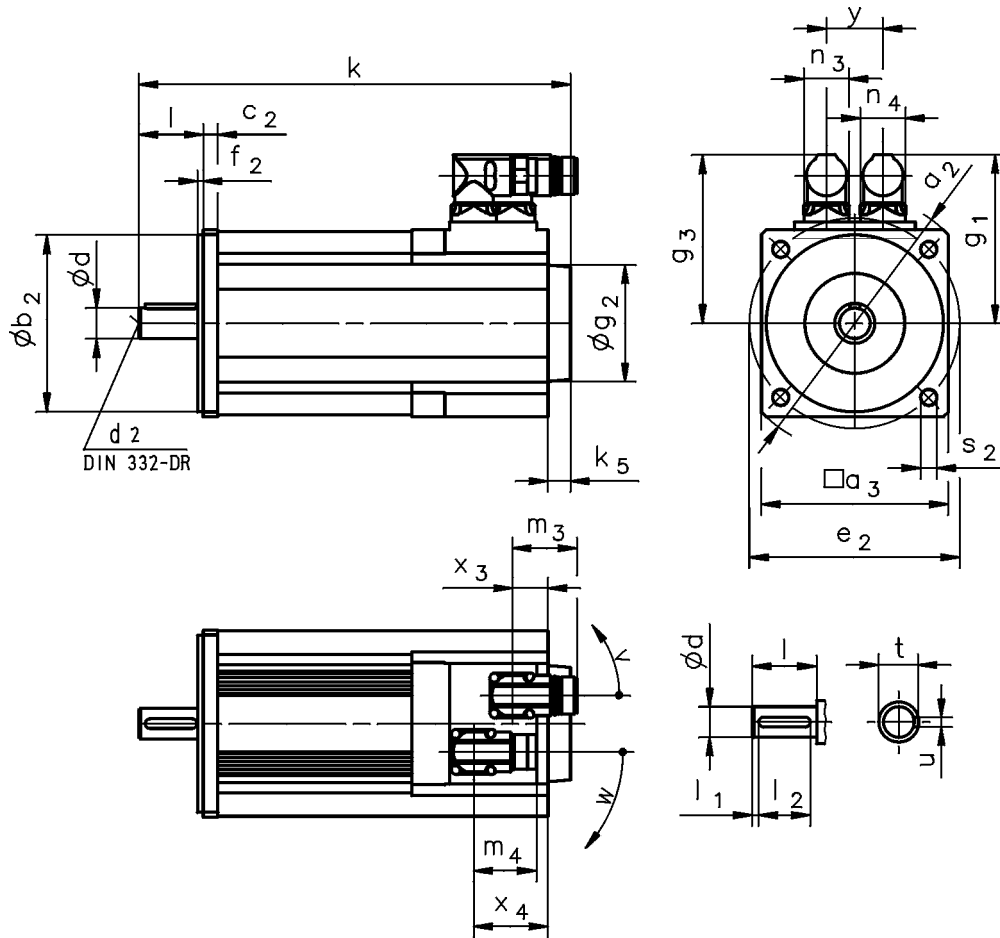
	a ₃	b ₂	c ₂	e ₂	f ₂	s ₂
		j6				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCS06	62	60	8	75	2.5	5.5

MCS synchronous servo motors

Technical data



Dimensions, self-ventilated



5.1

			MCS09D	MCS09F	MCS09H	MCS09L	MCS12D	MCS12H	MCS12L	
R□□ / C40 B0	k	[mm]	213	233	253	293	228	268	308	
R□□ / C40 P□	k	[mm]	233	253	273	313	248	288	328	
R□□ / C40	k_5	[mm]	13				14			
	g_2	[mm]	67				72			
S□□ / E□□ B0	k	[mm]	264	284	304	344	277	317	357	
S□□ / E□□ P□	k	[mm]	284	304	324	364	297	337	377	
S□□ / E□□	k_5	[mm]	64				63			
	g_2	[mm]	81				89			

			MCS14D	MCS14H	MCS14L	MCS14P	MCS19F	MCS19J	MCS19P	
R□□ / C40 B0	k	[mm]	251	291	331	371	280	320	380	
R□□ / C40 P□	k	[mm]	279	319	359	399	314	364	424	
R□□ / C40	k_5	[mm]	24				15			
	g_2	[mm]	78							
S□□ / E□□ B0	k	[mm]	301	341	381	421	329	369	429	
S□□ / E□□ P□	k	[mm]	329	369	409	449	363	413	473	
S□□ / E□□	k_5	[mm]	74				64			
	g_2	[mm]	101							

- Speed / angle sensor: R□□ / C□□ / S□□ / E□□
- Brake: B0 / P□

MCS synchronous servo motors

Technical data



Dimensions, self-ventilated

	g ₁	g ₃	x ₃	x ₄	m ₃	m ₄	n ₃	n ₄	y	v	w
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]
MCS09	90	90	20	44	40	40	28	28	35	195	260
MCS12	105	105	22	46							

	g ₁	g ₃	x ₃	x ₄	m ₃	m ₄	n ₃	n ₄	y	v	w
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]
MCS14D15-	117	117	24	48	40	40	28	28	35	195	260
MCS14D36-											
MCS14H15-											
MCS14H32-											
MCS14L15-											
MCS14L32-	146	126	29	36		75		45		180	205
MCS14P14-	117	117	24	48		40		28		195	260
MCS14P32-	146	126	29	36		75		45		180	205
MCS19F14-	142	142	24 51 ¹⁾	48 75 ¹⁾		40		28		195	260
MCS19F30-	171	151	29 56 ¹⁾	36 63 ¹⁾		75		45		180	205
MCS19J14-	142	142	24 51 ¹⁾	48 75 ¹⁾	40	28	195	260			
MCS19J30-	171	151	29 56 ¹⁾	36 63 ¹⁾	75	45	180	205			
MCS19P14-	142	142	24 51 ¹⁾	48 75 ¹⁾	40	28	195	260			
MCS19P30-	171	151	29 56 ¹⁾	36 63 ¹⁾	75	45	180	205			

5.1

	d	d ₂	l	l ₁	l ₂	u	t
	k6		-0.7 ... 0.3				
	[mm]	[mm]		[mm]	[mm]	[mm]	[mm]
MCS09	14	M5	30	2.5	25	5.0	16.0
MCS12	19	M6	40	4.0	32	6.0	21.5
MCS14	24	M8	50	5.0	40	8.0	27.0
MCS19	28	M10	60		50		31.0

	a ₂	a ₃	b ₂	c ₂	e ₂	f ₂	s ₂
			j6				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCS09	120	89	80	8	100	3.0	7.0
MCS12	160	116	110	9	130	3.5	10.0
MCS14	188	143	130	13	165		12.0
MCS19	250	192	180	11	215	4.0	14.0

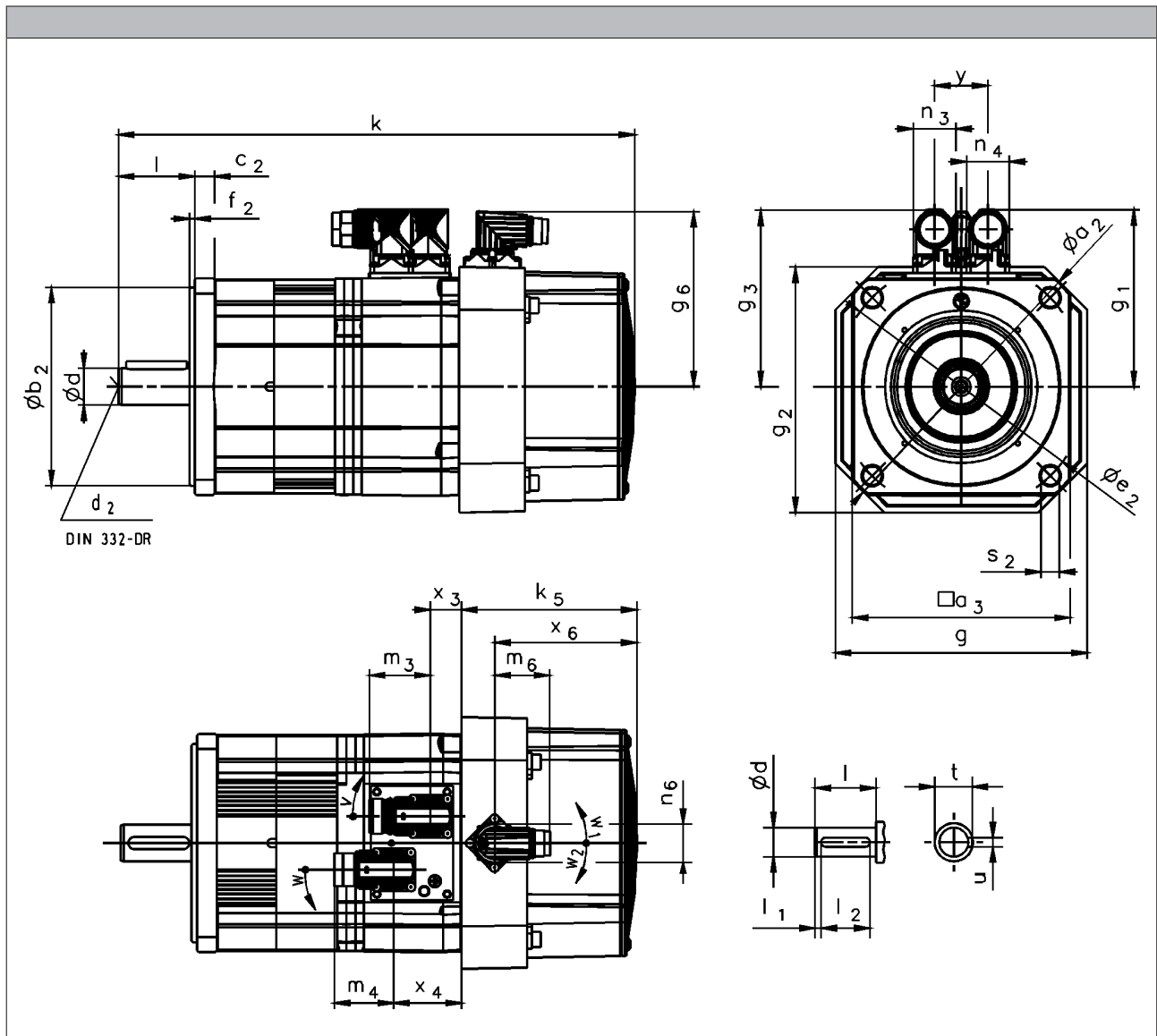
¹⁾ On version with brake (P□)

MCS synchronous servo motors

Technical data



Dimensions, forced ventilated



5.1

			MCS12D	MCS12H	MCS12L	MCS14D	MCS14H	MCS14L	MCS14P	MCS19F	MCS19J	MCS19P
R□□ / C40 B0	k	[mm]	301	341	381	339	379	419	459	387	427	487
R□□ / C40 P□	k	[mm]	321	361	401	368	408	448	488	421	471	531
R□□ / C40	k ₅	[mm]		92				115			126	
S□□ / E□□ B0	k	[mm]	344	384	424	392	432	472	512	425	465	525
S□□ / E□□ P□	k	[mm]	364	404	444	421	461	501	541	459	509	569
S□□ / E□□	k ₅	[mm]		135				169			165	
	g	[mm]		140				167			212	
	g ₂	[mm]		140				163			210	

- ▶ Speed / angle sensor: R□□ / C□□ / S□□ / E□□
- ▶ Brake: B0 / P□

MCS synchronous servo motors

Technical data



Dimensions, forced ventilated

	g ₁	g ₃	g ₆	x ₃	x ₄	x ₆	m ₃	m ₄	m ₆	n ₃	n ₄	n ₆	y	v	w	w ₁	w ₂																			
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]	[°]	[°]																			
MCS12D17	105	105	107	16	40	67		40																												
MCS12D35																																				
MCS12H14																																				
MCS12H34																																				
MCS12L17																																				
MCS12L39																																				
MCS14D14	117	117	115	20	44	93	40	40	37	28																										
MCS14D30																																				
MCS14H12																																				
MCS14H28	146	126		24	31		96												40	75	37	28														
MCS14L14	117	117																													20	44				
MCS14L30	146	126																															24	31		
MCS14P11	117	117	20	44	40	75		37	28																											
MCS14P26	146	126																24	31																	
MCS19F12	142	142	142	19	43	96		40	75	37	28																									
MCS19F29				46 ¹⁾	70 ¹⁾																															
MCS19J12				171	151		142											24	31	96	40	75	37	28												
MCS19J29																																			51 ¹⁾	58 ¹⁾
MCS19P12																																				
MCS19P29																																				

5.1

	d	d ₂	l	l ₁	l ₂	u	t
	k6		-0.7 ... 0.3				
	[mm]	[mm]		[mm]	[mm]	[mm]	[mm]
MCS12	19	M6	40	4.0	32	6.0	21.5
MCS14	24	M8	50	5.0	40	8.0	27.0
MCS19	28	M10	60		50		31.0

	a ₂	a ₃	b ₂	c ₂	e ₂	f ₂	s ₂
			j6				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCS12	160	116	110	9	130	3.5	10.0
MCS14	188	143	130	13	165		12.0
MCS19	250	192	180	11	215	4.0	14.0

¹⁾ On version with brake (P□)

MCS synchronous servo motors

Technical data





Permanent magnet holding brake

The synchronous servo motor can be fitted with integral permanent magnet holding brakes.

In the case of permanent magnet brakes, the rated torque applies solely as holding torque at standstill. This is due to the nature of their design. During braking from full motor speed, e.g. in the event of emergency stops, the braking torque is significantly reduced.

As such, they may not be used as safety elements (particularly with lifting axes) without additional measures being implemented.

The brakes are activated when the supply voltage is disconnected (closed-circuit principle). When using the brakes purely as holding brakes, virtually no wear occurs on the friction surfaces.

For traversing axes, adherence to the permissible load/brake motor (J_L / J_{MB}) moment of inertia ensures that the permissible maximum switching rate of the brake will not be exceeded and at least 2,000 emergency stop functions can be performed from a speed of 3,000 rpm.

For lifting axes, the load torque resulting from the weight acts additionally. In this case the specifications for J_L / J_{MB} do not apply.

Caution:

The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot l_{lg}[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate.

The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.



Permanent magnet holding brake



Permanent magnet holding brake

Rated data with standard braking torque

	$U_{N,DC}^{3,5)}$	M_N	M_N	M_{av}	$I_N^{2)}$	J	$t_1^{1)}$	$t_2^{1)}$	$Q_E^{4)}$	m	J_{MB}	J_L/J_{MB}
		20 °C	120 °C	120 °C								
	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm ²]	[ms]	[ms]	[J]	[kg]	[kgcm ²]	
MCS06C	24	2.20	2.00	0.60	0.34	0.12	15.0	30.0	30.0	0.30	0.26	22.1
MCS06F											0.34	16.6
MCS06I											0.42	13.3
MCS09D		8.00	6.00	4.50	0.65	1.07	20.0	40.0	400	0.80	2.17	36.4
MCS09F											2.57	30.5
MCS09H											2.97	26.3
MCS09L											3.87	19.9
MCS12D		12.0	10.0	7.00	0.65	1.07	13.0	43.0	400	0.90	5.07	15.0
MCS12H											8.40	8.70
MCS12L											11.7	5.90
MCS14D		22.0	18.0	8.00	0.88	3.20	15.0	150	640	1.90	11.3	10.5
MCS14H											17.4	6.50
MCS14L											26.6	3.90
MCS14P											37.9	2.40
MCS19F		37.0	32.0	15.0	0.93	12.4	96.0	113	2350	3.10	77.4	5.20

Rated data with increased braking torque

	$U_{N,DC}^{3,5)}$	M_N	M_N	M_{av}	$I_N^{2)}$	J	$t_1^{1)}$	$t_2^{1)}$	$Q_E^{4)}$	m	J_{MB}	J_L/J_{MB}
		20 °C	120 °C	120 °C								
	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm ²]	[ms]	[ms]	[J]	[kg]	[kgcm ²]	
MCS09D	24	12.0	10.0	7.00	0.65	1.07	20.0	40.0	400	0.80	2.17	36.4
MCS09F											2.57	30.5
MCS09H											2.97	26.3
MCS09L											3.87	19.9
MCS12D		24.0	19.0	12.0	0.71	3.13	16.0	90.0	890	1.20	7.10	24.3
MCS12H											10.4	16.3
MCS12L											13.7	12.1
MCS14D		37.0	32.0	15.0	0.93	12.4	96.0	113	2350	3.10	20.5	22.2
MCS14H											26.6	16.9
MCS14L											35.8	12.3
MCS14P											47.1	9.10
MCS19J		100	80.0	43.0	1.29	30.0	30.0	90.0	2100	4.30	135	2.20
MCS19P											190	1.20

1) Engagement and disengagement times are valid for rated voltage ($\pm 0\%$) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.

2) The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

3) With 24V DC brake: smoothed DC voltage, ripple $\leq 1\%$.

4) Maximum switching energy per emergency stop at $n = 3000$ r/min for at least 2000 emergency stops.

5) Voltage tolerance: -10% to $+5\%$

MCS synchronous servo motors

Accessories



Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.

Speed/angle sensor				RS0	RV0
	1)				
Product key				RS0	RV03
Resolution					
Angle			[°]	0.80	
Accuracy			[°]	-10 ... 10	
Absolute positioning				1 revolution	
Max. speed		n_{max}	[r/min]	8000	
Max. input voltage					
DC	$U_{in,max}$		[V]	10.0	
Max. input frequency		$f_{in,max}$	[kHz]	4.00	
Ratio					
Stator / rotor			± 5 %	0.30	
Rotor impedance		Z_{ro}	[Ω]	51 + j90	
Stator impedance		Z_{so}	[Ω]	102 + j150	
Impedance		Z_{rs}	[Ω]	44 + j76	
Min. insulation resistance					
At DC 500 V	R		[MΩ]	10.0	
Number of pole pairs				1	
Max. angle error			[°]	-10 ... 10	
Inverter assignment				E84AVTC E94A ECS EVS93	

1) 6 - Product key > speed/angle sensor

Speed-dependent safety functions

Suitable for safety function			No	Yes
Max. permissible angular acceleration				
MCS06	α	[rad/s ²]		56 000
MCS09 ... MCS19 ²⁾	α	[rad/s ²]		19 000
Functional safety				
IEC 61508				SIL3
EN 13849-1				Up to Performance Level e

2) 10 - Single encoder concepts with resolvers



Incremental encoder and SinCos absolute value encoder

Encoder type			TTL incremental	SinCos absolute value		
Speed/angle sensor			C40	EQI	SRS	SVS
Product key			IK4096-5V-T	AM32-5V-E	AS1024-8V-H	AS1024-8V-K2
Encoder type			Single-turn	Multi-turn	Single-turn	
Pulses			4096	32	1024	
Output signals			TTL	1 Vss		
Interfaces				EnDat	Hiperface	
Absolute revolutions			0	4096	1	
Resolution						
Angle ²⁾		[°]	1.30	0.40		
Accuracy						
		[°]	-1 ... 1	-5 ... 5	-0.8 ... 0.8	
Min. input voltage						
DC	U _{in,min}	[V]	4.50	4.75	7.00	
Max. input voltage						
DC	U _{in,max}	[V]	5.50	5.25	12.0	
Max. speed						
	n _{max}	[r/min]	7324	12000	6000	
Max. current consumption						
	I _{max}	[A]	0.075	0.17	0.080	
Limit frequency						
	f _{max}	[kHz]	500	6.00	200	
Inverter assignment						
			E94P	E94A	E84AVTC E94A ECS EVS93	

1) 6 - Product key > speed/angle sensor

2) Inverter-dependent.

Speed-dependent safety functions

Suitable for safety function			No	No	No	Yes
Max. permissible angular acceleration						
MCS06	α	[rad/s ²]				970000
MCS09 ... MCS19	α	[rad/s ²]				240000
Functional safety						
IEC 61508						SIL2
EN 13849-1						Up to Performance Level d

MCS synchronous servo motors

Accessories



Incremental encoder and SinCos absolute value encoder

Encoder type			SinCos absolute value				
Speed/angle sensor			SKM	SRM	SVM	ECN	EQN
Product key			AM128-8V-H	AM1024-8V-H	AM1024-8V-K2	AS2048-5V-E	AM2048-5V-E
Encoder type			Multi-turn			Single-turn	Multi-turn
Pulses			128	1024	2048		
Output signals			1 Vss				
Interfaces			Hiperface			EnDat	
Absolute revolutions			4096			1	4096
Resolution			0.40				
Angle			[°]				
Accuracy			-1.3 ... 1.3			-0.6 ... 0.6	
Min. input voltage			7.00				
DC			U _{in,min}			[V]	
Max. input voltage			12.0				
DC			U _{in,max}			[V]	
Max. speed			9000	6000	12000		
n _{max}			[r/min]				
Max. current consumption			0.060	0.080	0.15	0.25	
I _{max}			[A]				
Limit frequency			200				
f _{max}			[kHz]				
Inverter assignment			E84AVTC E94A ECS EVS93			E94A	

¹⁾ Inverter-dependent.

Speed-dependent safety functions

Suitable for safety function			No	No	Yes	No	No
Max. permissible angular acceleration							
MCS06			α			[rad/s ²]	
MCS09 ... MCS19			α			[rad/s ²]	
Functional safety							
IEC 61508			SIL2				
EN 13849-1			Up to Performance Level d				

MCS synchronous servo motors

Accessories



Blowers

Rated data for 50 Hz

		Enclosure	Number of phases	U_{min}	U_{max}	$U_{N, AC}$	P_N	I_N
				[V]	[V]	[V]	[kW]	[A]
MCS12	F10	IP54	1	210	240	230	0.019	0.12
	F50			104	122	115	0.018	0.22
MCS14	F10			210	240	230	0.040	0.25
	F50			104	122	115		0.53
MCS19	F10			210	240	230	0.060	0.26
	F50			104	122	115	0.047	0.45

Rated data for 60 Hz

		Enclosure	Number of phases	U_{min}	U_{max}	$U_{N, AC}$	P_N	I_N
				[V]	[V]	[V]	[kW]	[A]
MCS12	F10	IP54	1	210	240	230	0.019	0.12
	F50			104	122	115	0.018	0.22
MCS14	F10			210	240	230	0.040	0.25
	F50			104	122	115		0.53
MCS19	F10			210	240	230	0.060	0.26
	F50			104	122	115	0.047	0.45



Temperature monitoring

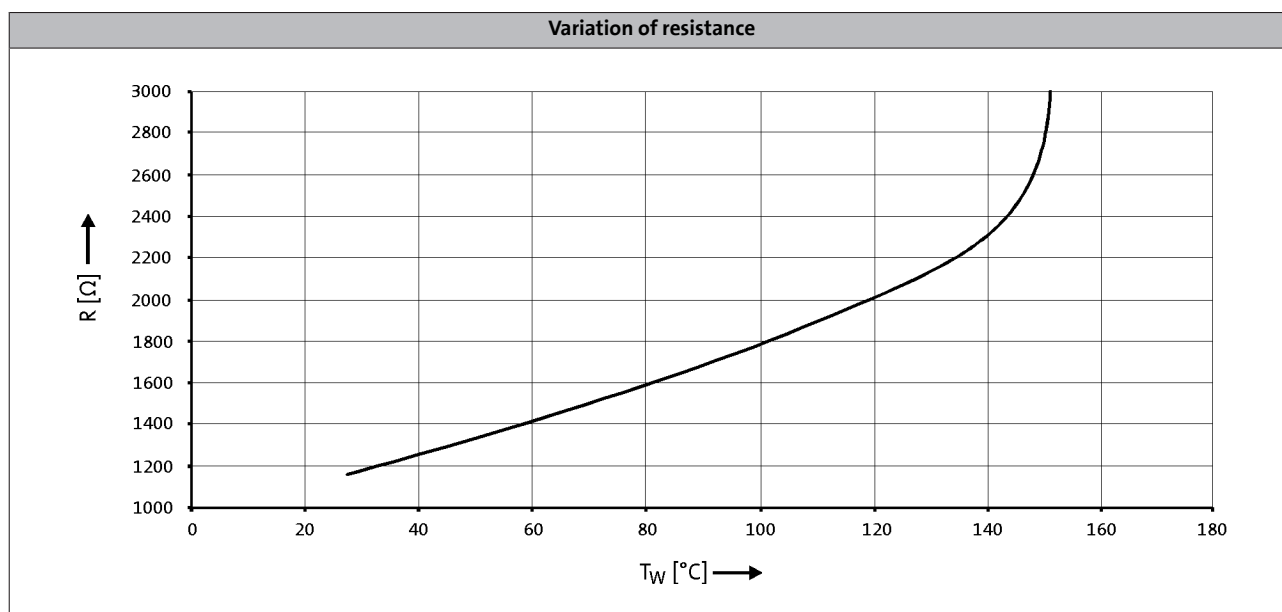
The thermal sensors used in the MCS motors continuously monitor the motor temperature. The temperature signal is transmitted over the system cable of the feedback system to the servo controller. Because of the different physical conditions, there are two temperature monitoring mechanisms on the MCS motors (there is no complete motor protection in either case)

MCS06

on this motor, the winding temperature of one winding phase is monitored with a KTY 83-110 type thermal sensor.

MCS09 to 19

These motors are monitored by three thermal sensors (1x KTY 83-110 + 2x PTC 150 °C) connected in series. This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in the event of overtemperature in one of the winding phases.



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- ▶ If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.

MCS synchronous servo motors

Accessories



Terminal box

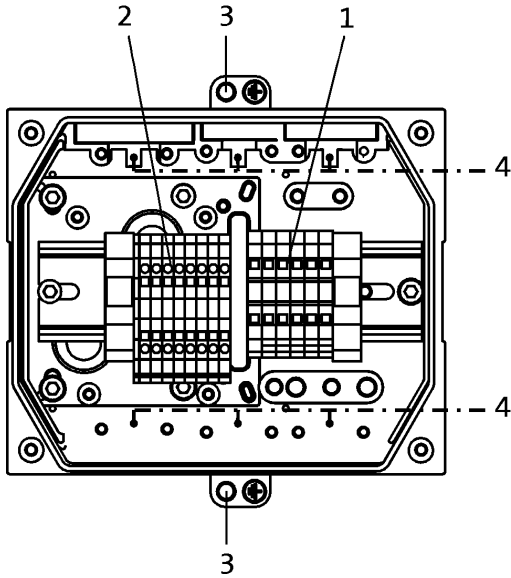
If a servo motor is to be connected to an existing cable or plug connectors are not to be used for other reasons, the connection can also be made via a terminal box.

The terminals are designed as tension spring terminals to ensure here the long-term vibration resistance of the cable contacts with adequate contact pressure required.

The terminal boxes have generously dimensioned space for the customer's own wiring and large surface shield connection areas to ensure a secure EMC-compliant connection. The cable outlet may be to the left or to the right, depending on requirements.

It is not possible to attach a terminal box to the MCS06 or to models with the blower.

Connections



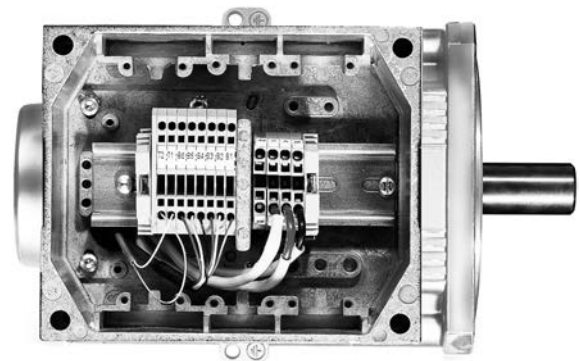
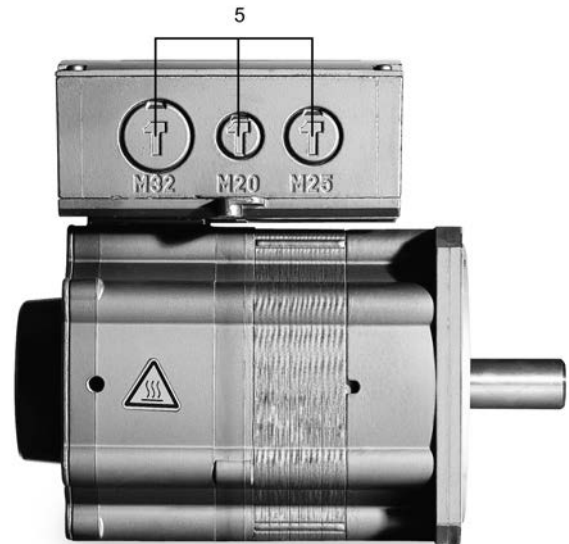
1: Power connection (terminals loadable up to 65 A) + brake connection.

2: Angle/speed sensor connection + thermal sensor connection.

3: PE connection.

4: Large area shield contact.

5: Openings for 2x M32, 2x M25, 2x M20 fittings. The openings are plugged and can be opened up as required by the customer.



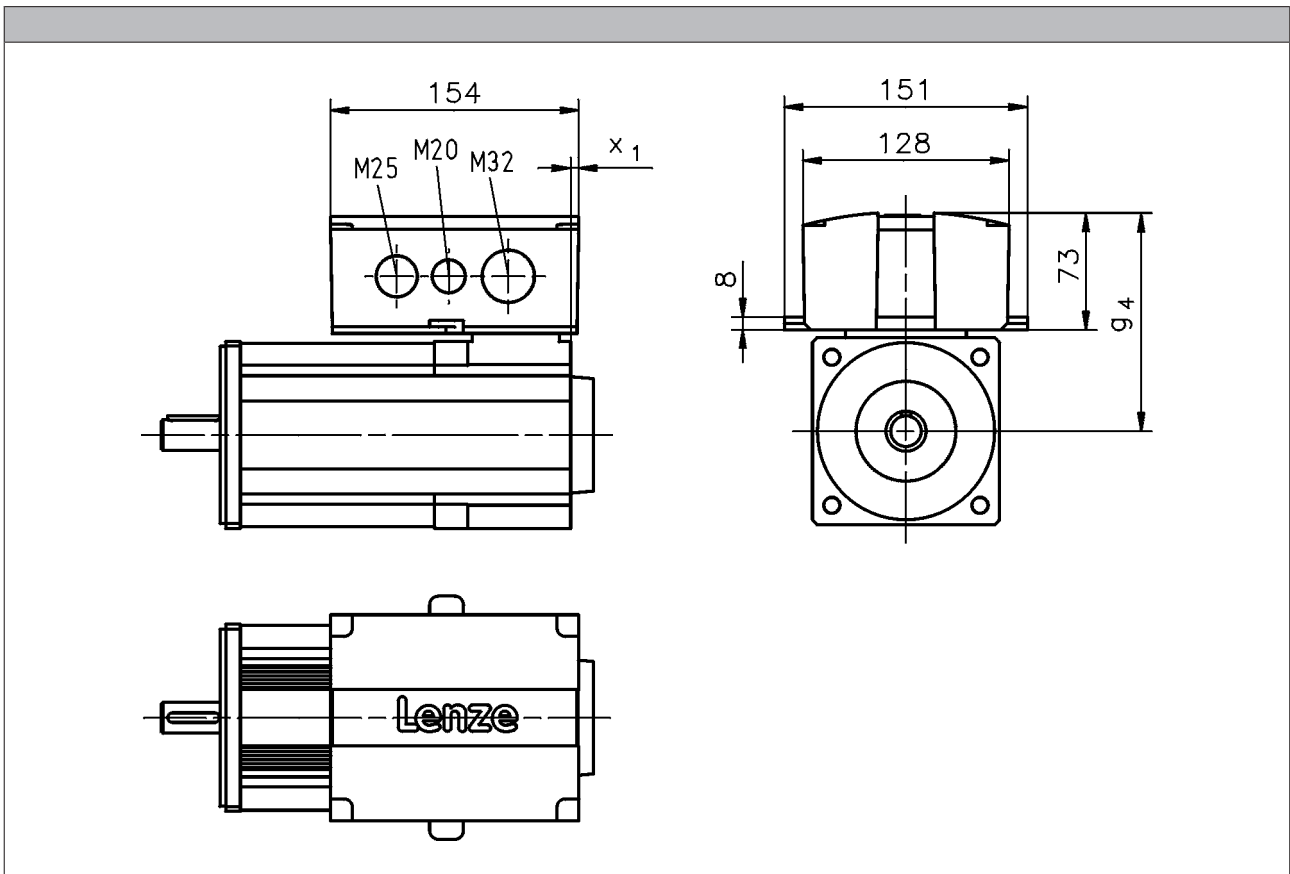
MCS synchronous servo motors

Accessories



Terminal box

Dimensions



	\varnothing_4 [mm]	x_1 [mm]
MCS09	121	8
MCS12	136	5
MCS14	147	3
MCS19	172	

5.1

MCS synchronous servo motors

Accessories



ICN connector

An ICN connector is used as standard for the electrical connection to the servo motors.

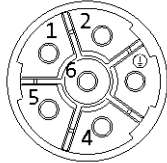
A connector is used for the connection of motor and brake. The connections to the feedback system/temperature monitoring and the blower each employ a separate connector.

The connectors can be rotated through 270° and are fitted with a bayonet catch for SpeedTec connectors. As the connector fixing is also compatible with conventional union nuts. Existing mating connectors can therefore still be used without difficulty.

Connection for power and brake

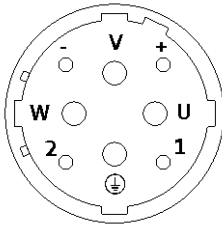
► MCS06 to 12

Pin assignment		
Contact	Designation	Meaning
1	BD1	Holding brake +
2	BD2	Holding brake -
PE	PE	PE conductor
4	U	Phase U power
5	V	Phase V power
6	W	Phase W power



► MCS14 to 19

Pin assignment		
Contact	Designation	Meaning
1		Not assigned
2		
+	BD1	Holding brake +
-	BD2	Holding brake -
PE	PE	PE conductor
U	U	Phase U power
V	V	Phase V power
W	W	Phase W power



MCS synchronous servo motors

Accessories



ICN connector

Feedback connection

► Resolver

Pin assignment		
Contact	Designation	Meaning
1	+Ref	Transformer windings
2	-Ref	
3	+VCC ETS	Supply: Electronic nameplate
4	+COS	Cosine stator windings
5	-COS	
6	+SIN	Sine stator windings
7	-SIN	
8		Not assigned
9		
10		
11	+KTY	KTY temperature sensor
12	-KTY	

► Hiperface incremental encoder and SinCos absolute value encoder

Pin assignment		
Contact	Designation	Meaning
1	B	Track B/+SIN
2	A ⁻	Track A inverse/-COS
3	A	Track A/+COS
4	+U _B	Supply +
5	GND	Mass
6	Z ⁻	Zero track inverse/-RS485
7	Z	Zero track/+RS485
8		Not assigned
9	B ⁻	Track B inverse/-SIN
10		Not assigned
11	+KTY	KTY temperature sensor
12	-KTY	

MCS synchronous servo motors

Accessories



ICN connector

Feedback connection

- SinCos absolute value encoder with EnDat interface

Pin assignment		
Contact	Designation	Meaning
1	U _p sensor	Supply: UP sensor
2		Not assigned
3		
4	0 V sensor	Supply: 0 V sensor
5	+KTY	KTY temperature sensor
6	-KTY	
7	+U _B	Supply +
8	Cycle	EnDat interface cycle
9	Cycle ⁻	EnDat interface inverse cycle
10	GND	Mass
11	Shield	Encoder housing screen
12	B	Track B
13	B ⁻	Track B inverse/-SIN
14	Data	EnDat interface data
15	A	Track A
16	A ⁻	Track A inverse
17	Data ⁻	EnDat interface inverse data

5.1

Blower connection

Pin assignment		
Contact	Designation	Meaning
PE	PE	PE conductor
1	U1	Fan
2	U2	
3		Not assigned
4		
5		
6		

MCS synchronous servo motors

Accessories



MCS synchronous servo motors

Accessories



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